

More general chain rule.

$$\text{Let } \vec{x} = \{x_1, \dots, x_n\} / \mathbb{R}$$

$$\text{Let } F(\vec{x}) = (f_1(\vec{x}), \dots, f_m(\vec{x})) \in \mathbb{R}[\vec{x}]^m$$

Define the total derivative (Jacobian)

$$DF = \left( \begin{array}{ccc} D_{x_1} f_1 & D_{x_2} f_1 & \dots & D_{x_n} f_1 \\ \vdots & \vdots & & \vdots \\ D_{x_1} f_m & D_{x_2} f_m & \dots & D_{x_n} f_m \end{array} \right) \left. \vphantom{\begin{array}{ccc} D_{x_1} f_1 & D_{x_2} f_1 & \dots & D_{x_n} f_1 \\ \vdots & \vdots & & \vdots \\ D_{x_1} f_m & D_{x_2} f_m & \dots & D_{x_n} f_m \end{array}} \right\} m$$

$\underbrace{\hspace{10em}}_n$

If  $m=1$ ,  $DF = \nabla F$  is the gradient (row) vector.

Now let  $\Phi(\vec{x}) = (\Phi_1(\vec{x}), \dots, \Phi_n(\vec{x}))$   
in  $\mathbb{R}[\vec{x}]^n$ , and define formal  
composition

$$(F \circ \Phi)(\vec{x}) = ((f_1 \circ \Phi)(\vec{x}), \dots, (f_m \circ \Phi)(\vec{x}))$$

and

$$(f \circ \Phi) := f(\Phi_1(\vec{x}), \dots, \Phi_n(\vec{x})).$$

[Think:  $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$

$\Phi: \mathbb{R}^n \rightarrow \mathbb{R}^n$  "change of coords"

$f \circ \Phi: \mathbb{R}^n \rightarrow \mathbb{R}^m$

Over infinite domain this is correct.]

Chain Rule:

$$D(f \circ \Phi) = (Df \circ \Phi) D\Phi$$

$m \times n$                        $m \times n$                        $n \times n$

Proof: Same as before, because we can work row by row. //



Today: Taylor Expansion.

for every  $f(\vec{x}) \in \mathbb{R}[\vec{x}]$  &  $\vec{a} \in \mathbb{R}^n$ ,

there is a unique Taylor expansion of  $f(\vec{x})$  "near  $\vec{x} = \vec{a}$ ":

$$f(\vec{x}) = \sum c_{\mathbf{I}} (\vec{x} - \vec{a})^{\mathbf{I}}$$

$$= \sum c_{\mathbf{I}} (x_1 - a_1)^{i_1} (x_2 - a_2)^{i_2} \dots (x_n - a_n)^{i_n},$$

sum over all index vectors  $\mathbf{I} \in \mathbb{N}^n$ .

We want to compute the coefficients.

The answer is expressed in terms of differential operators.

Definition: For an  $\mathbf{I} = (i_1, \dots, i_n) \in \mathbb{N}^n$  we define the operator

$$D_{\vec{x}}^{\mathbf{I}} : \mathbb{R}[\vec{x}] \rightarrow \mathbb{R}[\vec{x}]$$

as

$$D_{\vec{x}}^{\mathbf{I}} = D_{x_1}^{i_1} D_{x_2}^{i_2} \dots D_{x_n}^{i_n}$$

$$= \frac{\partial^{i_1 + i_2 + \dots + i_n}}{\partial x_1^{i_1} \partial x_2^{i_2} \dots \partial x_n^{i_n}}$$

which is well-defined because

mixed partials commute.

Theorem (Taylor Expansion):

For any  $f(\vec{x}) \in \mathbb{R}[x_1, \dots, x_n]$  and for any point  $\vec{a} = (a_1, \dots, a_n) \in \mathbb{R}^n$ , I claim that

$$f(\vec{x}) = \sum_{\mathbf{I} \in \mathbb{N}^n} \frac{(D_{\vec{x}}^{\mathbf{I}} f)(\vec{a})}{\mathbf{I}!} (\vec{x} - \vec{a})^{\mathbf{I}},$$

where  $(\vec{x} - \vec{a})^{\mathbf{I}} := (x_1 - a_1)^{i_1} \dots (x_n - a_n)^{i_n}$

$$\mathbf{I}! := i_1! i_2! \dots i_n!$$

We observe that the sum is finite because  $D_{\vec{x}}^{\mathbf{I}} f = 0(\vec{x})$  whenever

$i_k > \deg(f)$  for some  $k$ .

Proof: Given  $\vec{a} \in \mathbb{R}^n$ ,  $f(\vec{x}) \in \mathbb{R}[\vec{x}]$

we consider  $g(\vec{x}) := f(\vec{x} + \vec{a}) \in \mathbb{R}[\vec{x}]$ .

From the single variable chain rule,

we have  $(D_{x_i} g)(\vec{x}) = (D_{x_i} f)(\vec{x} + \vec{a})$

because  $D_{x_i}(x_j + a_j) = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases}$ .

This implies that

$$(D_{\vec{x}}^I g)(\vec{x}) = (D_{\vec{x}}^I f)(\vec{x} + \vec{a})$$

$$(D_{\vec{x}}^I g)(\vec{0}) = (D_{\vec{x}}^I f)(\vec{a}).$$

Note that  $g(\vec{x}) \in \mathcal{R}[\vec{x}]$  can be expressed as  $g(\vec{x}) = \sum c_I \vec{x}^I$ ,

as can any polynomial. If we can

show that

$$c_I = \frac{(D_{\vec{x}}^I g)(\vec{0})}{I!} = \frac{(D_{\vec{x}}^I f)(\vec{a})}{I!},$$

then we will have

$$f(\vec{x}) = g(\vec{x} - \vec{a}) = \sum \frac{(D_{\vec{x}}^I f)(\vec{a})}{I!} (\vec{x} - \vec{a})^I$$

as desired.

To prove the red formula, we define a partial order on  $\mathbb{N}^n$  by

$$"I \leq J" \Leftrightarrow i_k \leq j_k \quad \forall k$$

$$"I < J" \Leftrightarrow I \leq J \text{ \& } I \neq J \\ \forall k, i_k \leq j_k \text{ \& } \exists k, i_k \neq j_k$$

Then I claim that  $D_{\vec{x}}^I$  acts on monomials as follows:

$$D_{\vec{x}}^I (\vec{x}^J) = \begin{cases} (J!_I) \vec{x}^{J-I} & I < J \\ I! & I = J \\ 0 & \text{else} \end{cases}$$

where we define

$$(r)_s = r(r-1)(r-2) \dots (r-s+1)$$

$$J!_I = (j_1)_{i_1} (j_2)_{i_2} \dots (j_n)_{i_n}$$

Indeed, if  $I \neq J$  then we have  $i_k > j_k$  for some  $k$ . It follows that  $D_{x_k}^{i_k} \vec{x}^J = 0$  and hence  $D_{\vec{x}}^I \vec{x}^J = 0$ .

On the other hand, if  $I \leq J$  then we have  $i_k \leq j_k$  and hence

$$\begin{aligned} D_{x_k}^{i_k} \vec{x}^J &= j_k (j_k - 1) \cdots (j_k - i_k + 1) \frac{\vec{x}^J}{x_k^{i_k}} \\ &= (j_k)_{i_k} \vec{x}^J / x_k^{i_k} \end{aligned}$$

for any  $k$ . It follows that

$$\begin{aligned} D_{\vec{x}}^I \vec{x}^J &= (j_1)_{i_1} (j_2)_{i_2} \cdots (j_n)_{i_n} \frac{\vec{x}^J}{x_1^{i_1} x_2^{i_2} \cdots x_n^{i_n}} \\ &= (J!_I) \vec{x}^J / \vec{x}^I \\ &= (J!_I) \vec{x}^{J-I} \end{aligned}$$

In the special case  $I = J$  this becomes

$$D_{\vec{x}}^I \vec{x}^I = I! \vec{x}^{\vec{0}} = I! \quad \equiv \equiv \equiv$$

By applying  $D_{\vec{x}}^I$  to

$$g(\vec{x}) = \sum c_J \vec{x}^J$$

we obtain

$$D_{\vec{x}}^{\vec{I}} g = c_{\vec{I}} \vec{I}! + \sum_{\vec{J} > \vec{I}} c_{\vec{J}} (\vec{J}!_{\vec{I}}) \vec{x}^{\vec{J}-\vec{I}}$$

Evaluate at  $\vec{0}$  to get

$$(D_{\vec{x}}^{\vec{I}} g)(\vec{0}) = c_{\vec{I}} \vec{I}!$$

$$c_{\vec{I}} = \frac{(D_{\vec{x}}^{\vec{I}} g)(\vec{0})}{\vec{I}!}$$



[ Shreeram Abhyankar : There are three kinds of algebra:

High School, College, University.

None is harder than the others, they only differ in abstraction. ]



The first few terms of the Taylor expansion have special meaning.



$$\begin{aligned}
 F(\vec{x}) &= f(\vec{a}) + (\nabla f)_{\vec{a}} (\vec{x} - \vec{a}) \\
 &+ \frac{1}{2} (\vec{x} - \vec{a})^T (Hf)_{\vec{a}} (\vec{x} - \vec{a}) \\
 &+ \text{higher terms,}
 \end{aligned}$$

where  $(\vec{x} - \vec{a})$  is a column vector,

$$(\nabla f)_{\vec{a}} = (D_{x_1} f(\vec{a}), \dots, D_{x_n} f(\vec{a}))$$

is the gradient row vector, and

$Hf$  is the Hessian matrix of  
2nd derivatives:

$$Hf = \begin{pmatrix} D_{x_1} D_{x_1} f & \dots & D_{x_1} D_{x_n} f \\ \vdots & & \vdots \\ D_{x_n} D_{x_1} f & \dots & D_{x_n} D_{x_n} f \end{pmatrix}$$