Given a square matrix A, a constant  $\lambda$  and a vector v satisfying

 $A\mathbf{v} = \lambda \mathbf{v},$ 

we say that v is an eigenvector of A with eigenvalue  $\lambda$ . The eigenvalues of a given matrix are the roots of its *characteristic polynomial*. In the case of a  $2 \times 2$  matrix we have

$$\begin{array}{lll} (\text{matrix}) & \rightsquigarrow & (\text{characteristic polynomial}) \\ A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} & \rightsquigarrow & \det \begin{pmatrix} a - \lambda & b \\ c & d - \lambda \end{pmatrix} = 0. \end{array}$$

Once an eigenvalue  $\lambda$  is found, the corresponding eigenvectors  $\mathbf{v} = (u, v)$  can be found by solving a linear system:

$$A\mathbf{v} = \lambda \mathbf{v} \quad \rightsquigarrow \quad \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix} = \lambda \begin{pmatrix} u \\ v \end{pmatrix} \quad \rightsquigarrow \quad \begin{cases} (a - \lambda)u + bv = 0, \\ cu + (d - \lambda)v = 0. \end{cases}$$

Given the matrix A we may consider the system of first order linear differential equations:

$$\mathbf{x}'(t) = A\mathbf{x}(t) \quad \rightsquigarrow \quad \left\{ \begin{array}{ll} x'(t) &=& ax(t) + by(t), \\ y'(t) &=& cx(t) + dy(t). \end{array} \right.$$

If the matrix A has distinct eigenvalues  $\lambda_1 \neq \lambda_2$  with corresponding eigenvectors  $\mathbf{v}_1$  and  $\mathbf{v}_2$ then the general solution of the system is

$$\mathbf{x}(t) = a_1 e^{\lambda_1 t} \mathbf{v}_1 + a_2 e^{\lambda_2 t} \mathbf{v}_2.$$

We may also consider the system of second order differential equations:

$$\mathbf{x}''(t) = A\mathbf{x}(t) \quad \rightsquigarrow \quad \left\{ \begin{array}{ll} x''(t) &=& ax(t) + by(t), \\ y''(t) &=& cx(t) + dy(t). \end{array} \right.$$

If the eigenvalues are negative, say  $\lambda_1 = -\omega_1^2$  and  $\lambda_2 = -\omega_2^2$ , then the general solution of the second order system is

$$\mathbf{x}(t) = (a_1 \cos(\omega_1 t) + b_1 \sin(\omega_1 t))\mathbf{v}_1 + (a_2 \cos(\omega_2 t) + b_2 \sin(\omega_2 t))\mathbf{v}_2$$

## 1. First Order Linear System. Consider the following system of differential equations:

$$\begin{cases} 5x'(t) &= x(t) + 6y(t), \\ 5y'(t) &= 4x(t) - y(t). \end{cases}$$

- (a) Find the 2 × 2 matrix A such that  $\mathbf{x}'(t) = A\mathbf{x}(t)$ , where  $\mathbf{x}(t) = (x(t), y(t))$ .
- (b) Find the eigenvalues and eigenvectors of A.
- (c) Use part (b) to find the general solution of the system.
- (d) Find the specific solution with initial conditions x(0) = 0 and y(0) = 5.

(a): We have

$$\begin{cases} 5x'(t) &= x(t) + 6y(t), \\ 5y'(t) &= 4x(t) - y(t), \\ x'(t) &= x(t)/5 + 6y(t)/5, \\ 5y'(t) &= 4x(t)/5 - y(t)/5, \end{cases}$$

(b): The eigenvalues are the solutions of the characteristic equation:

$$\begin{vmatrix} 1/5 - \lambda & 6/5 \\ 4/5 & -1/5 - \lambda \end{vmatrix} = 0$$
  
(1/5 -  $\lambda$ )(-1/5 -  $\lambda$ ) - (4/5)(6/5) = 0  
 $\lambda^2 - 1/25 - 24/25 = 0$   
 $\lambda^2 - 1 = 0$   
( $\lambda - 1$ )( $\lambda + 1$ ) = 0  
 $\lambda = \pm 1$ .

The eigenvectors for  $\lambda = 1$  satisfy

$$\begin{pmatrix} 1/5 & 6/5 \\ 4/5 & -1/5 \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix} = 1 \begin{pmatrix} u \\ v \end{pmatrix}$$

$$\Rightarrow \begin{cases} (1/5 - 1)u + (6/5)v = 0, \\ (4/5)u + (-1/5 - 1)v = 0, \\ (4/5)u + (6/5)v = 0, \\ (4/5)u + (-6/5)v = 0, \\ 2u - 3v = 0, \\ 2u - 3v = 0. \end{cases}$$

We can choose any solution we want. Let's take (u, v) = (3, 2). We verify that

$$\begin{pmatrix} 1/5 & 6/5\\ 4/5 & -1/5 \end{pmatrix} \begin{pmatrix} 3\\ 2 \end{pmatrix} = \begin{pmatrix} 15/5\\ 10/5 \end{pmatrix} = 1 \begin{pmatrix} 3\\ 2 \end{pmatrix}$$

The eigenvectors for  $\lambda = -1$  satisfy

$$\begin{pmatrix} 1/5 & 6/5 \\ 4/5 & -1/5 \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix} = -1 \begin{pmatrix} u \\ v \end{pmatrix}$$
  

$$\sim \quad \begin{cases} (1/5+1)u + (6/5)v = 0, \\ (4/5)u + (-1/5+1)v = 0, \\ (4/5)u + (6/5)v = 0, \\ (4/5)u + (4/5)v = 0, \\ \end{pmatrix}$$
  

$$\sim \quad \begin{cases} u+v = 0, \\ u+v = 0. \\ \\ u+v = 0. \end{cases}$$

We can choose any solution we want. Let's take (u, v) = (1, -1). We verify that

$$\begin{pmatrix} 1/5 & 6/5 \\ 4/5 & -1/5 \end{pmatrix} \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} -5/5 \\ 5/5 \end{pmatrix} = -1 \begin{pmatrix} 1 \\ -1 \end{pmatrix}.$$

(c): Based on part (b), the general solution is

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = c_1 \begin{pmatrix} 3 \\ 2 \end{pmatrix} e^t + c_2 \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{-t} = \begin{pmatrix} 3c_1 e^t + c_2 e^{-t} \\ 2c_1 e^t - c_2 e^{-t} \end{pmatrix}.$$

(d): Substituting the initial conditions x(0) = 0 and y(0) = 5 gives

$$\begin{pmatrix} 0\\5 \end{pmatrix} = \begin{pmatrix} x(0)\\y(0) \end{pmatrix} = \begin{pmatrix} 3c_1 + c_2\\2c_1 - c_2 \end{pmatrix}$$
  

$$\Rightarrow \begin{cases} 0 = 3c_1 + c_2, \\ 5 = 2c_1 - c_2, \\ \\ c_1 = 1, \\ c_2 = -3. \end{cases}$$

Hence the solution is

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = 1 \begin{pmatrix} 3 \\ 2 \end{pmatrix} e^t - 3 \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{-t} = \begin{pmatrix} 3e^t - 3e^{-t} \\ 2e^t + 3e^{-t} \end{pmatrix}.$$

2. Second Order Linear System. Consider the following system of differential equations:

$$\begin{cases} x''(t) &= -2x(t) + 2y(t), \\ y''(t) &= x(t) - 3y(t). \end{cases}$$

- (a) Find the 2 × 2 matrix A such that  $\mathbf{x}''(t) = A\mathbf{x}(t)$ , where  $\mathbf{x}(t) = (x(t), y(t))$ .
- (b) Find the eigenvalues and eigenvectors of A.
- (c) Use (b) to find the general solution of the system.
- (d) Find the specific solution with initial conditions x(0) = x'(0) = y(0) = 0 and y'(0) = 1.

(a): We have

$$\begin{cases} x''(t) = -2x(t) + 2y(t), \\ y''(t) = x(t) - 3y(t), \end{cases}$$
  
$$\rightsquigarrow \quad \begin{pmatrix} x''(t) \\ y''(t) \end{pmatrix} = \begin{pmatrix} -2 & 2 \\ 1 & -3 \end{pmatrix} \begin{pmatrix} x(t) \\ y(t) \end{pmatrix}$$
  
$$\rightsquigarrow \quad \mathbf{x}''(t) = \begin{pmatrix} -2 & 2 \\ 2 & -3 \end{pmatrix} \mathbf{x}(t).$$

(b): The eigenvalues are the solutions of the characteristic equation:

$$\begin{vmatrix} -2 - \lambda & 2 \\ 1 & -3 - \lambda \end{vmatrix} = 0$$
  
(-2 -  $\lambda$ )(-3 -  $\lambda$ ) - (1)(2) = 0  
 $\lambda^2 + 5\lambda + 6 - 2 = 0$   
 $\lambda^2 + 5\lambda + 4 = 0$   
( $\lambda + 1$ )( $\lambda + 4$ ) = 0  
 $\lambda = -1, -4.$ 

The eigenvectors for  $\lambda = -1$  satisfy

$$\rightsquigarrow \begin{cases} -u+2v = 0, \\ u-2v = 0. \end{cases}$$

We can choose any solution we want. Let's take (u, v) = (2, 1). We verify that

$$\begin{pmatrix} -2 & 2\\ 1 & -3 \end{pmatrix} \begin{pmatrix} 2\\ 1 \end{pmatrix} = \begin{pmatrix} -2\\ -1 \end{pmatrix} = -1 \begin{pmatrix} 2\\ 1 \end{pmatrix}.$$

The eigenvectors for  $\lambda = -4$  satisfy

$$\begin{pmatrix} -2 & 2\\ 1 & -3 \end{pmatrix} \begin{pmatrix} u\\ v \end{pmatrix} = -4 \begin{pmatrix} u\\ v \end{pmatrix}$$

$$\implies \begin{cases} (-2+4)u + (2)v = 0, \\ (1)u + (-3+4)v = 0, \end{cases}$$

$$\implies \begin{cases} 2u+2v = 0, \\ u+v = 0. \end{cases}$$

We can choose any solution we want. Let's take (u, v) = (1, -). We verify that

$$\begin{pmatrix} -2 & 2\\ 1 & -3 \end{pmatrix} \begin{pmatrix} 1\\ -1 \end{pmatrix} = \begin{pmatrix} -4\\ 4 \end{pmatrix} = -4 \begin{pmatrix} 1\\ -1 \end{pmatrix}.$$

(c): The eigenvalues  $\lambda = -1, -4$  correspond to frequencies  $\omega = \sqrt{-\lambda} = 1, 2$ . Then based on part (b) the general solution is

$$\begin{pmatrix} x(t)\\ y(t) \end{pmatrix} = (a_1 \cos t + b_1 \sin t) \begin{pmatrix} 2\\ 1 \end{pmatrix} + (a_2 \cos(2t) + b_2 \sin(2t)) \begin{pmatrix} 1\\ -1 \end{pmatrix}.$$

(d): Substituting initial positions x(0) = y(0) = 0 into the solution gives

$$\begin{pmatrix} 0\\0 \end{pmatrix} = \begin{pmatrix} x(0)\\y(0) \end{pmatrix} = (a_1 + 0) \begin{pmatrix} 2\\1 \end{pmatrix} + (a_2 + 0) \begin{pmatrix} 1\\-1 \end{pmatrix}$$

$$\Rightarrow \begin{cases} 0 = 2a_1 + a_2, \\ 0 = a_1 - a_2, \\ a_1 = 0, \\ a_2 = 0. \end{cases}$$

Now we compute the derivative of the solution:

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = (0\cos t + b_1\sin t) \begin{pmatrix} 2 \\ 1 \end{pmatrix} + (0\cos(2t) + b_2\sin(2t)) \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$
$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = b_1\sin(t) \begin{pmatrix} 2 \\ 1 \end{pmatrix} + b_2\sin(2t) \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$
$$\begin{pmatrix} x'(t) \\ y'(t) \end{pmatrix} = b_1\cos(t) \begin{pmatrix} 2 \\ 1 \end{pmatrix} + 2b_2\cos(2t) \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

Finally, we substitute the initial velocities x'(0) = 0 and y'(0) = 1:

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$$\rightsquigarrow \begin{cases} b_1 = 1/3, \\ b_2 = -1/3. \end{cases}$$

Hence the solution is

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = \frac{1}{3}\sin(t) \begin{pmatrix} 2 \\ 1 \end{pmatrix} - \frac{1}{3}\sin(2t) \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} (2/3)\sin t - (1/3)\sin(2t) \\ (1/3)\sin t + (1/3)\sin(2t) \end{pmatrix}$$

Remark: A system of second order linear ODEs represents a system of coupled oscillators. The eigenvectors of the system correspond to the "normal modes of oscillation". The general solution is a "superposition of normal modes". Here are the normal modes for our problem:

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https://www.math.miami.edu/~armstrong/311sp23/hw6_2_mode1.gif
https://www.math.miami.edu/~armstrong/311sp23/hw6_2_mode2.gif
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And here is our solution, which is the superposition of the two modes:

https://www.math.miami.edu/~armstrong/311sp23/hw6\_2\_modes\_superposition.gif

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