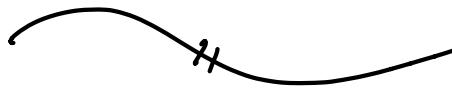


HW 2 due Friday 11:40am.

Quiz 2 Tuesday 11:40am.



Recall : Suppose a particle in \mathbb{R}^2 has constant acceleration vector

$$\vec{a}(t) = \langle a, b \rangle \text{ for all } t.$$

If the initial position & velocity are

$$\vec{r}(0) = \langle x_0, y_0 \rangle$$

$$\vec{v}(0) = \langle u_0, v_0 \rangle$$

Then we can "integrate the system":

$$\vec{v}(t) = \int \vec{a}(t) dt$$

$$= \langle at + c_1, bt + c_2 \rangle$$

When $t=0$ we find that

$$\langle u_0, v_0 \rangle = \vec{v}(0) = \langle 0 + c_1, 0 + c_2 \rangle,$$

$$\text{so } \vec{v}(t) = \langle at + u_0, bt + v_0 \rangle.$$

Then we have

$$\begin{aligned}\vec{r}(t) &= \int \vec{v}(t) dt \\ &= \left\langle \frac{1}{2}at^2 + u_0 t + c_3, \frac{1}{2}bt^2 + v_0 t + c_4 \right\rangle\end{aligned}$$

When $t = 0$ we find that

$$\langle x_0, y_0 \rangle = \vec{r}(0) = \langle 0 + c_3, 0 + c_4 \rangle$$

We conclude that

$$\vec{r}(t) = \left\langle \frac{1}{2}at^2 + u_0 t + x_0, \frac{1}{2}bt^2 + v_0 t + y_0 \right\rangle$$

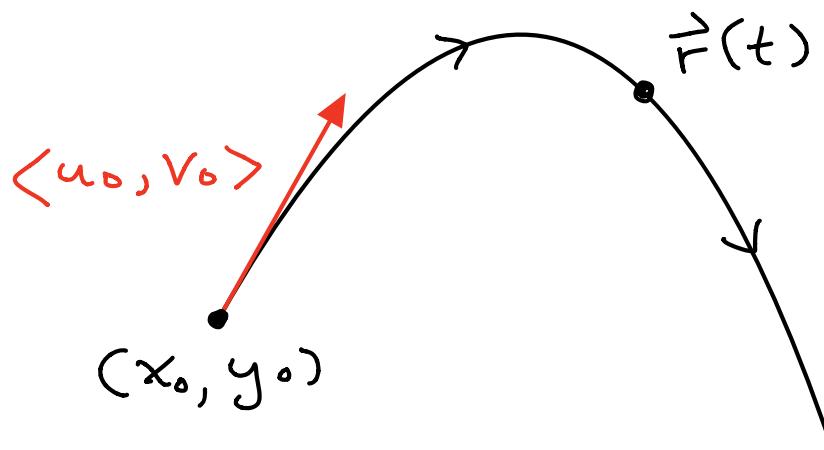
Example : The acceleration due to gravity near the earth's surface is approximately constant :

$$\vec{a}(t) \approx \langle 0, -32 \text{ ft/sec}^2 \rangle.$$

So the above formula gives

$$\vec{r}(t) = \langle u_0 t + x_0, -16t^2 + v_0 t + y_0 \rangle.$$

This is a parametrized parabola:



Today we will discuss a more interesting example where the acceleration vector is not constant.



Universal Gravitation:

We have two points with mass M & m , say the sun has mass M and a planet has mass m . Fix the sun at the origin $\langle 0, 0, 0 \rangle$

and let the planet have position

$$\vec{r}(t) = \langle x(t), y(t), z(t) \rangle.$$

Newton says that the planet experiences a force due to gravity:

- $\|\vec{F}(t)\| = GMm / \|\vec{r}(t)\|^2$
- $\vec{F}(t)$ in the direction of $-\vec{r}(t)$.

If we let $\vec{u}(t) = \vec{r}(t) / \|\vec{r}(t)\|$
be a unit vector in the direction
of $\vec{r}(t)$ [see HWZ.5] then we
have $\|\vec{u}(t)\| = 1$ for all t , and

$$\vec{F}(t) = -\frac{GMm}{\|\vec{r}(t)\|^2} \vec{u}(t)$$

$$= -\frac{GMm}{\|\vec{r}(t)\|^3} \vec{r}(t)$$

From Newton's Second Law, this causes the planet to accelerate:

$$m \vec{a}(t) = \vec{F}(t)$$

$$\vec{a}(t) = \frac{1}{m} \vec{F}(t)$$

$$\vec{a}(t) = -\frac{GM}{\|\vec{r}(t)\|^2} \vec{u}(t)$$

$$\text{or } -\frac{GM}{\|\vec{r}(t)\|^3} \vec{r}(t)$$

To simplify notation we will assume that $GM = 1$, we will write $\|\vec{r}(t)\| = r(t)$ and we will omit the "t" whenever possible:

$$\vec{a} = -\frac{1}{r^2} \vec{u} = -\frac{1}{r^3} \vec{r}$$

This is called a "differential egn."

$$\vec{r}'' = -\frac{1}{r^3} \vec{r}.$$

We want to solve for

$$\vec{r} = \vec{r}(t) = \langle x(t), y(t), z(t) \rangle.$$

[Remark : $r(t) = \|\vec{r}(t)\|$
 $= \sqrt{x(t)^2 + y(t)^2 + z(t)^2}$.]

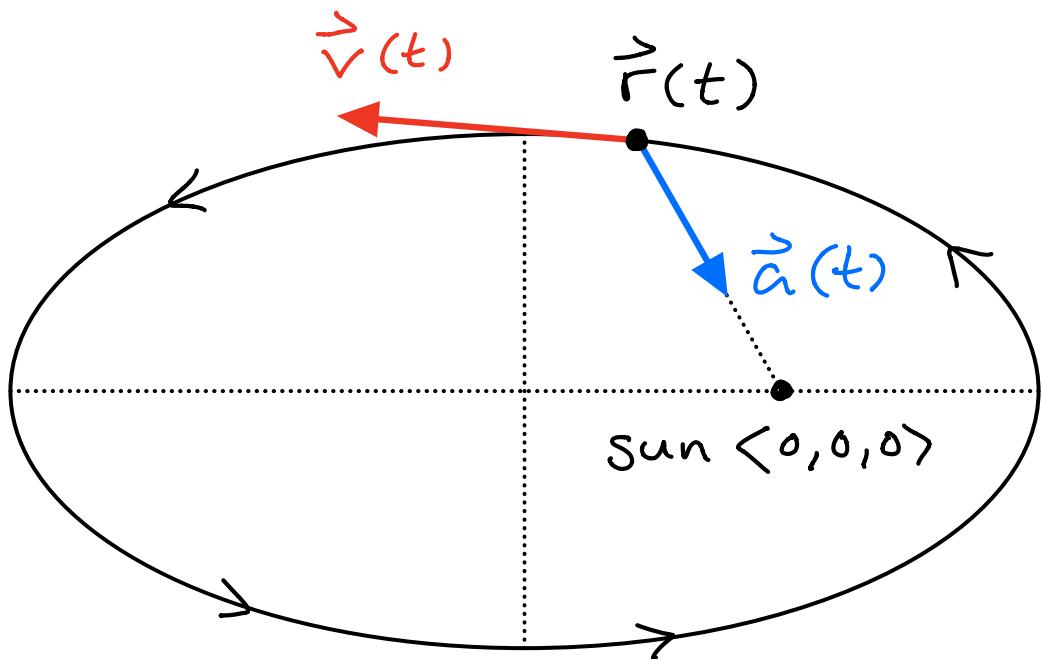
That is, we want to compute the orbit of the planet.



Kepler observed experimentally that planetary orbits are ellipses with sun at one "focus". Newton used his "inverse square law" to prove this!

We will find that the picture looks like this :





The proof is “a bit involved” but I want to show you because it is is a beautiful application of vector calculus. We will need to use the following rules:

- $\vec{x} \times \vec{x} = \vec{0}$
- if $\|\vec{x}(t)\| = \text{constant}$, then $\vec{x}(t) \cdot \vec{x}'(t) = 0$ for all times t .

[See HW 2.5]

We will also need some properties
of the cross product

- $\vec{x} \cdot (\vec{y} \times \vec{z}) = (\vec{x} \times \vec{y}) \cdot \vec{z}$
- $\vec{x} \times (\vec{y} \times \vec{z}) = (\vec{x} \cdot \vec{z}) \vec{y} - (\vec{x} \cdot \vec{y}) \vec{z}$,

and the "product rules"

- $[f(t) \vec{x}(t)]' = f'(t) \vec{x}(t) + f(t) \vec{x}'(t)$
- $[\vec{x}(t) \cdot \vec{y}(t)]' = \vec{x}'(t) \cdot \vec{y}(t) + \vec{x}(t) \cdot \vec{y}'(t)$
- $[\vec{x}(t) \times \vec{y}(t)]' = \vec{x}'(t) \times \vec{y}(t) + \vec{x}(t) \times \vec{y}'(t)$.



Let's begin. We have defined

$$\vec{u} = \frac{1}{r} \vec{r}$$

and we know the inverse square law

$$\vec{a} = \vec{r}'' = -\frac{1}{r^2} \vec{u} = -\frac{1}{r^3} \vec{r}$$

First we observe that

$$\begin{aligned}(\vec{r} \times \vec{v})' &= \vec{r}' \times \vec{v} + \vec{r} \times \vec{v}' \\&= \vec{v} \times \vec{v} + \vec{r} \times \vec{a} \\&= \cancel{\vec{v} \times \vec{v}} - \frac{1}{r^3} \vec{r} \times \cancel{\vec{r}} \\&= \vec{0} - \vec{0} \\&= \vec{0}\end{aligned}$$

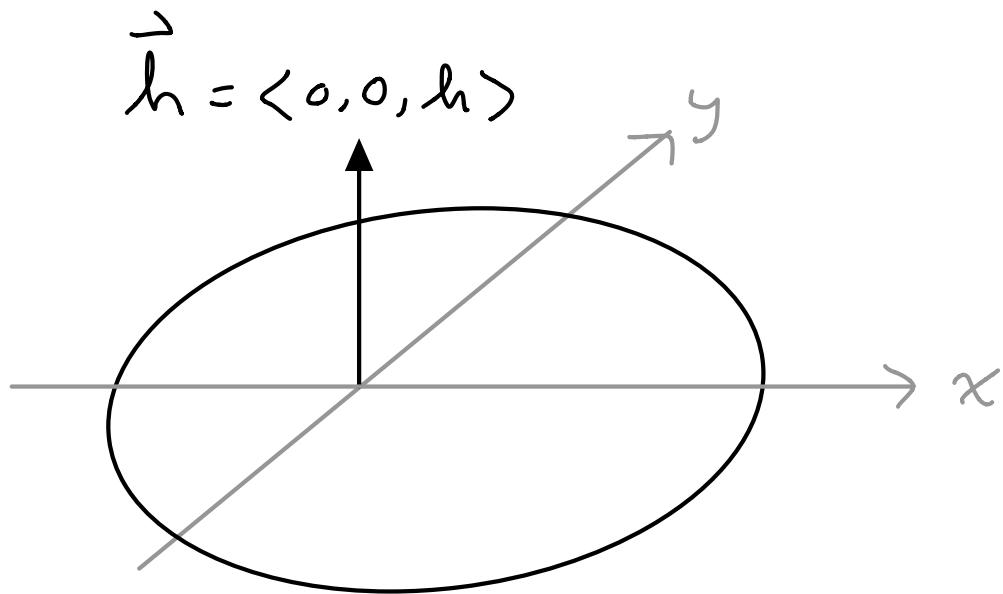
This tells us that the vector $\vec{r}(t) \times \vec{v}(t)$ is constant, i.e., does not depend on t . Let's choose a coordinate system so

$$\vec{r}(t) \times \vec{v}(t) = \vec{h} = \langle 0, 0, h \rangle$$

for some constant $h > 0$.

Since $\vec{r} \times \vec{v}$ is simultaneously

perpendicular to \vec{r} & \vec{v} , it follows that the planet stays in the x, y -plane:



Next, I claim that

$$(\vec{v} \times \vec{h})' = \vec{u}' = \left(\frac{\vec{r}}{r} \right)'$$

This is the tricky part! To prove it we will express everything in terms of $\vec{u}(t)$:

$$\vec{a} = -\frac{1}{r^2} \vec{u}$$

$$\vec{r} = r \vec{u}$$

$$\vec{v} = (r \vec{u})'$$

$$= r \vec{u}' + r' \vec{u}$$

and

$$\vec{h} = \vec{r} \times \vec{v}$$

$$= (r \vec{u}) \times (r \vec{u}' + r' \vec{u})$$

$$= r^2 (\vec{u} \times \vec{u}') + rr' (\vec{u} \times \vec{u}) \quad \text{O}$$

$$= r^2 (\vec{u} \times \vec{u}').$$

Thus we can prove the desired identity :

$$\begin{aligned}
 (\vec{v} \times \vec{h})' &= \vec{v}' \times \vec{h} + \vec{v} \times \vec{h}' \quad \vec{h} \text{ is constant} \\
 &= \vec{v}' \times \vec{h} + \vec{0} \\
 &= \vec{u} \times \vec{h} \\
 &= \left(-\frac{1}{r^2} \vec{u} \right) \times (r^2 (\vec{u} \times \vec{u}'))
 \end{aligned}$$

$$= -\vec{u} \times (\vec{u} \times \vec{u}')$$

$$= (\overset{1}{\cancel{\vec{u}}} \cdot \overset{0}{\cancel{\vec{u}}}) \vec{u}' - (\overset{0}{\cancel{\vec{u}}} \cdot \overset{1}{\cancel{\vec{u}'}}) \vec{u}$$

[definition] [HW 2.5]

$$= \vec{u}' \text{ as desired } \checkmark$$

That was the harder part.

The rest is downhill.

By integrating

$$(\vec{v} \times \vec{h})' = \vec{u}'$$

we obtain

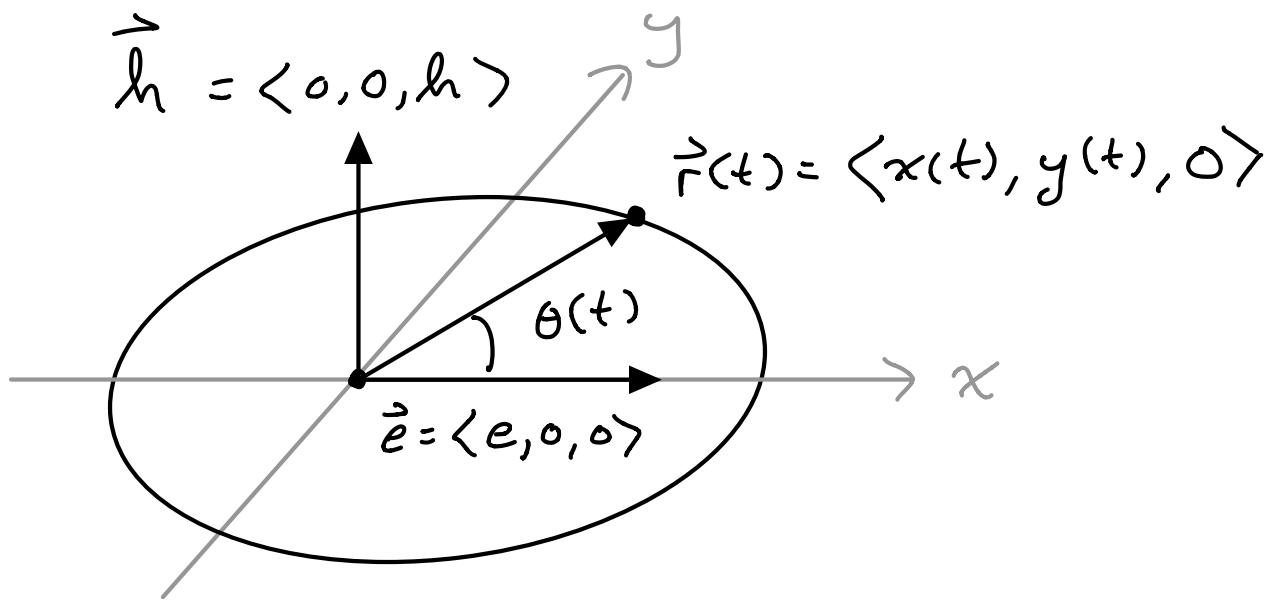
$$\vec{v} \times \vec{h} = \vec{u} + \vec{e}$$

for some constant vector \vec{e} .

By choosing coordinates we can assume that

$$\vec{e} = \langle e, 0, 0 \rangle \text{ for some } e \geq 0.$$

Picture :



The position of the planet has the form

$$\vec{r}(t) = \langle x(t), y(t), 0 \rangle.$$

IF we let $\theta(t)$ be the angle between $\vec{r}(t)$ & \vec{e} then we can write

$$\begin{cases} x(t) = r(t) \cos \theta(t) \\ y(t) = r(t) \sin \theta(t) \end{cases}$$

in "polar coordinates". To find an equation for x & y we first find an equation for r & θ .

To do this we compute the number $\vec{r} \cdot (\vec{v} \times \vec{h})$ in two different ways:

$$1) \vec{r} \cdot (\vec{v} \times \vec{h}) = \vec{r} \cdot (\vec{u} + \vec{e})$$

$$= \vec{r} \cdot \vec{u} + \vec{r} \cdot \vec{e}$$

$$= (r\vec{u}) \cdot \vec{u} + \vec{r} \cdot \vec{e}$$

$$= r(\cancel{\vec{u} \cdot \vec{u}}^1) + r e \cos \theta$$

$$= r + r e \cos \theta$$

$$= r(1 + e \cos \theta)$$

$$2) \vec{r} \cdot (\vec{v} \times \vec{h}) = (\vec{r} \times \vec{v}) \cdot \vec{h}$$

$$= \vec{h} \cdot \vec{h}$$

$$= \|\vec{h}\|^2 = h^2.$$

dot product
identity

Combining ① and ② gives

$$r(1 + e \cos \theta) = h^2$$

$$r = \frac{h^2}{1 + e \cos \theta}$$

!!

This is the desired equation for the shape of the orbit.

Believe it or not, this is the equation of a "conic section" in polar coordinates. To see this we will convert to the more familiar cartesian coordinates

$$\begin{cases} x = r \cos \theta, \\ y = r \sin \theta. \end{cases}$$

- If $e = 0$ then this is easy.

We have

$$r = h^2$$

$$r^2 = h^4$$

$$x^2 + y^2 = h^4,$$

which is a circle of radius h^2 .

To clean it up, let $c = h^2$ so

we get a circle of radius c :

$$x^2 + y^2 = c^2.$$

- IF $0 < e < 1$ then with "a bit of effort" one can verify that

$$\frac{(x+d)^2}{a^2} + \frac{y^2}{b^2} = 1$$

where the constants a, b, c, d are related to the constants h, e by

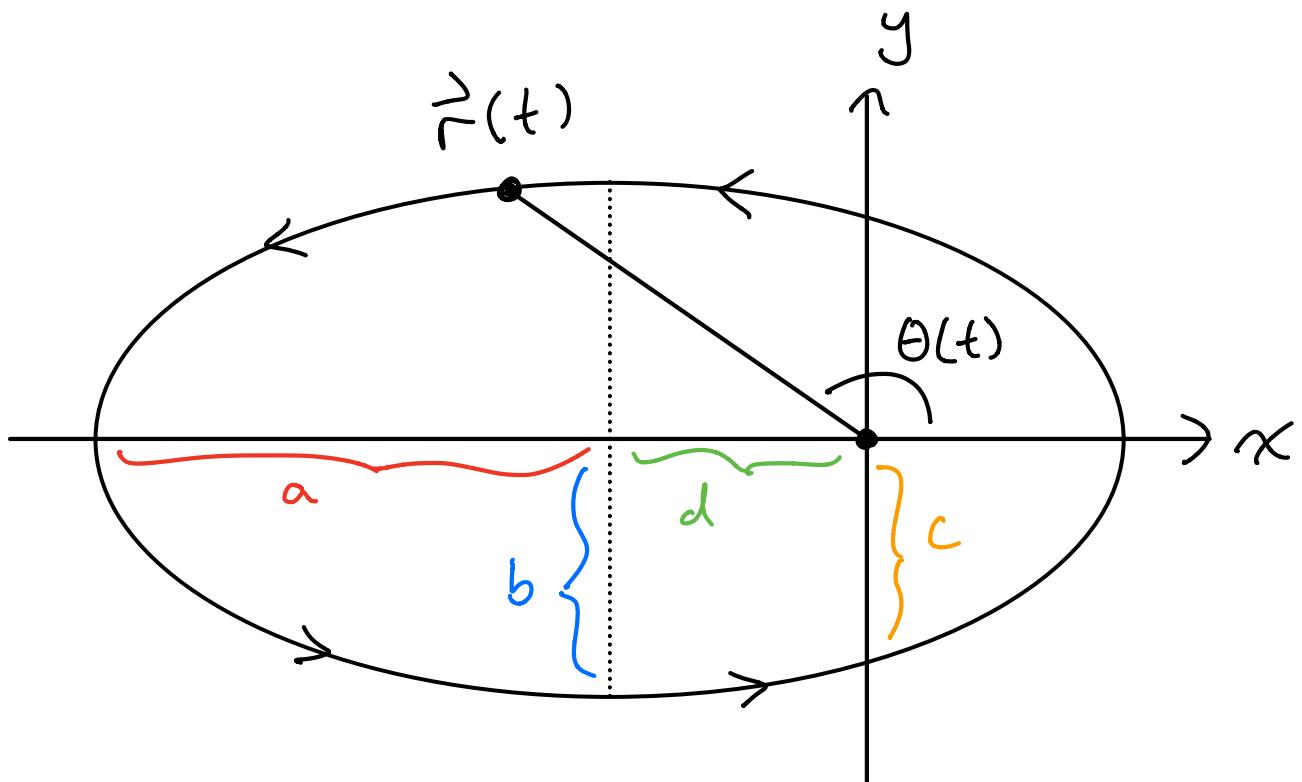
$$c = h^2$$

$$a = c / (1 - e^2)$$

$$b = c / \sqrt{1 - e^2}$$

$$d = a e$$

This is the familiar equation
of an ellipse :



Remark : Sadly, there are no nice formulas for the coordinates $r(t)$, $\theta(t)$, $x(t)$, $y(t)$ as functions

of t . I presume that the formulas would involve "elliptic functions" just as the arc length of an ellipse does.

- If $e \geq 1$ then the planet has enough energy to escape the solar system:

