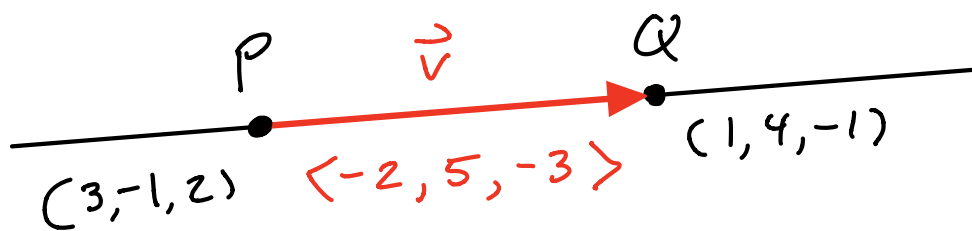


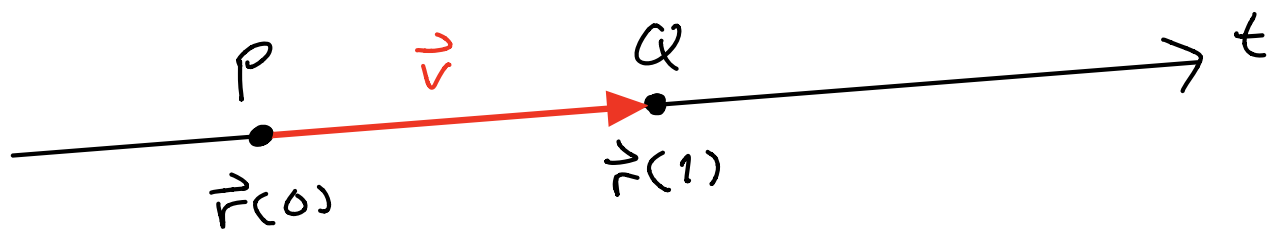
1. Consider the line passing through points  $P = (3, -1, 2)$  &  $Q = (1, 4, -1)$ .

(a) To parametrize the line, we consider the vector  $\vec{v} = \vec{PQ} = \langle a, b, c \rangle$ :



If we take  $(x_0, y_0, z_0) = P = (3, -1, 2)$  then the line can be parametrized as

$$\vec{r}(t) = (3 - 2t, -1 + 5t, 2 - 3t)$$



(b) The parametrized line can be expressed as

$$\begin{cases} x = 3 - 2t \\ y = -1 + 5t \\ z = 2 - 3t \end{cases}$$

To obtain the symmetric equations we solve for  $t$ :

$$t = \frac{x-3}{-2} = \frac{y+1}{5} = \frac{z-2}{-3}$$

Our line is the intersection of any two of the following three planes:

- $(x-3)/-2 = (y+1)/5$
- $(x-3)/-2 = (z-2)/-3$
- $(y+1)/5 = (z-2)/-3$ .

2. Consider the following two planes

$$\begin{cases} \textcircled{1} & x - y + 0 = 1, \\ \textcircled{2} & x + y + 2z = 1. \end{cases}$$

To find the line of intersection we will let  $t = z$  be the parameter. Then we solve for  $x$  &  $y$ .

$$\textcircled{1}: x - y = 1$$

$$\textcircled{2}: x + y = 1 - 2t$$

$$\textcircled{1} + \textcircled{2}: 2x = 2 - 2t$$

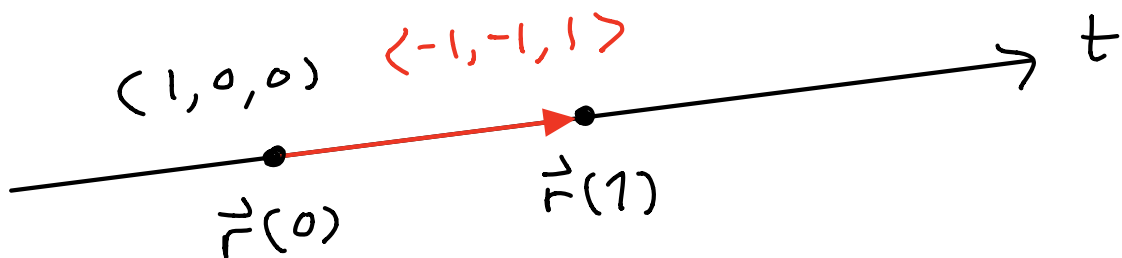
$$\textcircled{2} - \textcircled{1}: 2y = -2t$$

We conclude that

$$\begin{cases} x = 1 - t \\ y = -t \\ z = t \end{cases}$$

Thus the line has parametrization

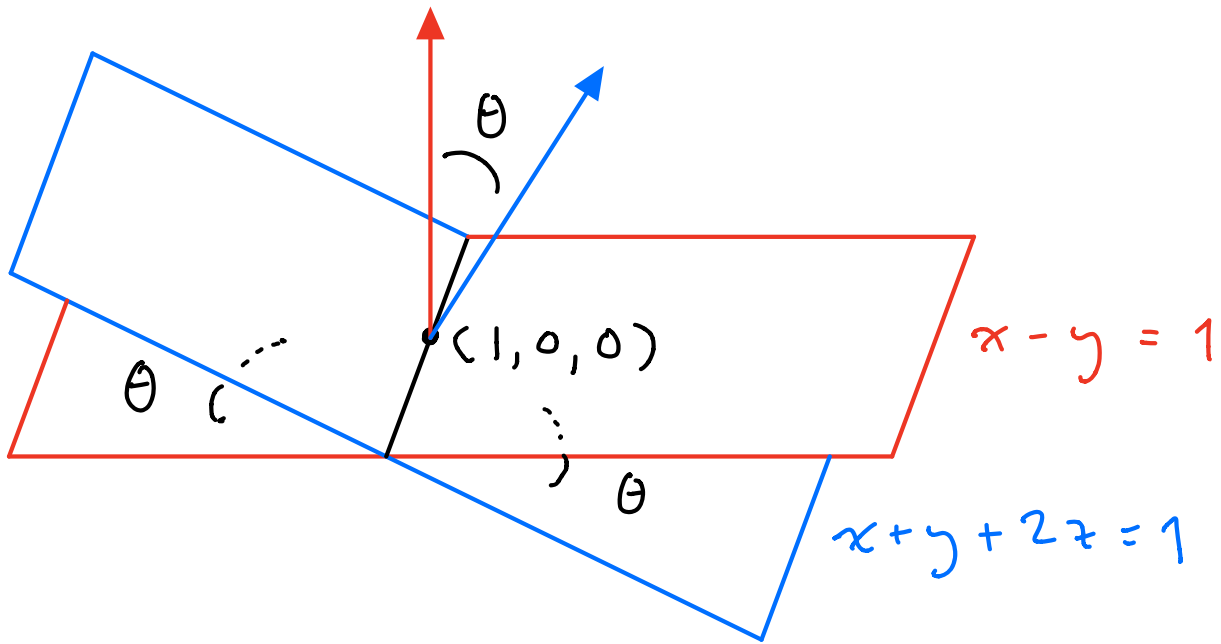
$$\vec{r}(t) = (1 - t, -t, t)$$



Remark: Observe that  $\langle -1, -1, 1 \rangle$  is  $\perp$  to both of the normal vectors  $\langle 1, -1, 0 \rangle$  &  $\langle 1, 1, 2 \rangle$  as it should be.

(b) Find the angle between the planes.

Let  $\vec{m} = \langle 1, -1, 0 \rangle$  &  $\vec{n} = \langle 1, 1, 2 \rangle$  be the normal vectors:



The angle between the planes is the same as the angle between  $\vec{m}$  &  $\vec{n}$ , so that

$$\|\vec{m}\| \|\vec{n}\| \cos \theta = \vec{m} \cdot \vec{n}$$

$$\sqrt{1^2 + (-1)^2 + 0^2} \sqrt{1^2 + 1^2 + 2^2} \cos \theta = 1 \cdot 1 + (-1) \cdot 1 + 0 \cdot 2$$

$$\sqrt{2} \sqrt{6} \cos \theta = 0$$

$$\cos \theta = 0$$

It follows that  $\theta = 90^\circ$  so the planes are perpendicular. [The picture above is not very accurate but it is better for illustrating the general concept.]

3. An interesting curve

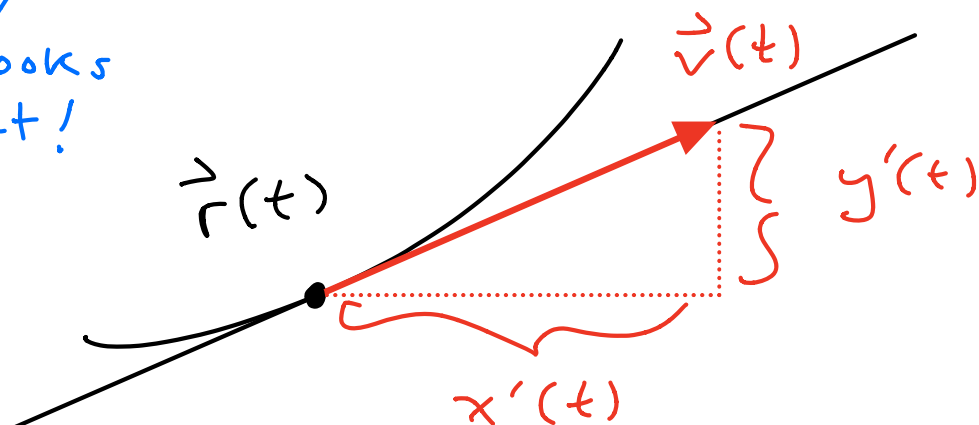
$$\vec{r}(t) = \langle x(t), y(t) \rangle = \langle t^2 - 1, t^3 - t \rangle$$

$$\vec{v}(t) = \langle x'(t), y'(t) \rangle = \langle 2t, 3t^2 - 1 \rangle$$

The slope of the tangent line at the point  $\vec{r}(t)$  is

$$\frac{dy}{dx} = \frac{dy/dt}{dx/dt} = \frac{y'(t)}{x'(t)} = \frac{3t^2 - 1}{2t}$$

this looks correct!



(a) The slope is vertical when

$$x'(t) = 0$$

$$2t = 0$$

$$t = 0$$

so that  $\vec{r}(0) = (-1, 0)$

$$\vec{v}(0) = (0, -1)$$

The slope is horizontal when

$$y'(t) = 0$$

$$3t^2 - 1 = 0$$

$$t = \pm 1/\sqrt{3} \approx \pm 0.6$$

so that  $\vec{r}(\pm 1/\sqrt{3}) \approx (-0.7, \pm 0.4)$

$$\vec{v}(\pm 1/\sqrt{3}) \approx (\pm 1.2, 0)$$

(b) The slope is +1 when

$$(3t^2 - 1)/2t = +1$$

$$3t^2 - 1 = 2t$$

$$3t^2 - 2t - 1 = 0$$

$$(3t + 1)(t - 1) = 0$$

$$t = 1 \text{ or } -1/3$$

so that

$$\vec{r}(1) = (0, 0) \quad \text{or} \quad \vec{r}(-1/3) \approx (-0.9, 0.3)$$

$$\vec{v}(1) = (2, 2) \quad \text{or} \quad \vec{v}(-1/3) \approx (-0.7, -0.7)$$

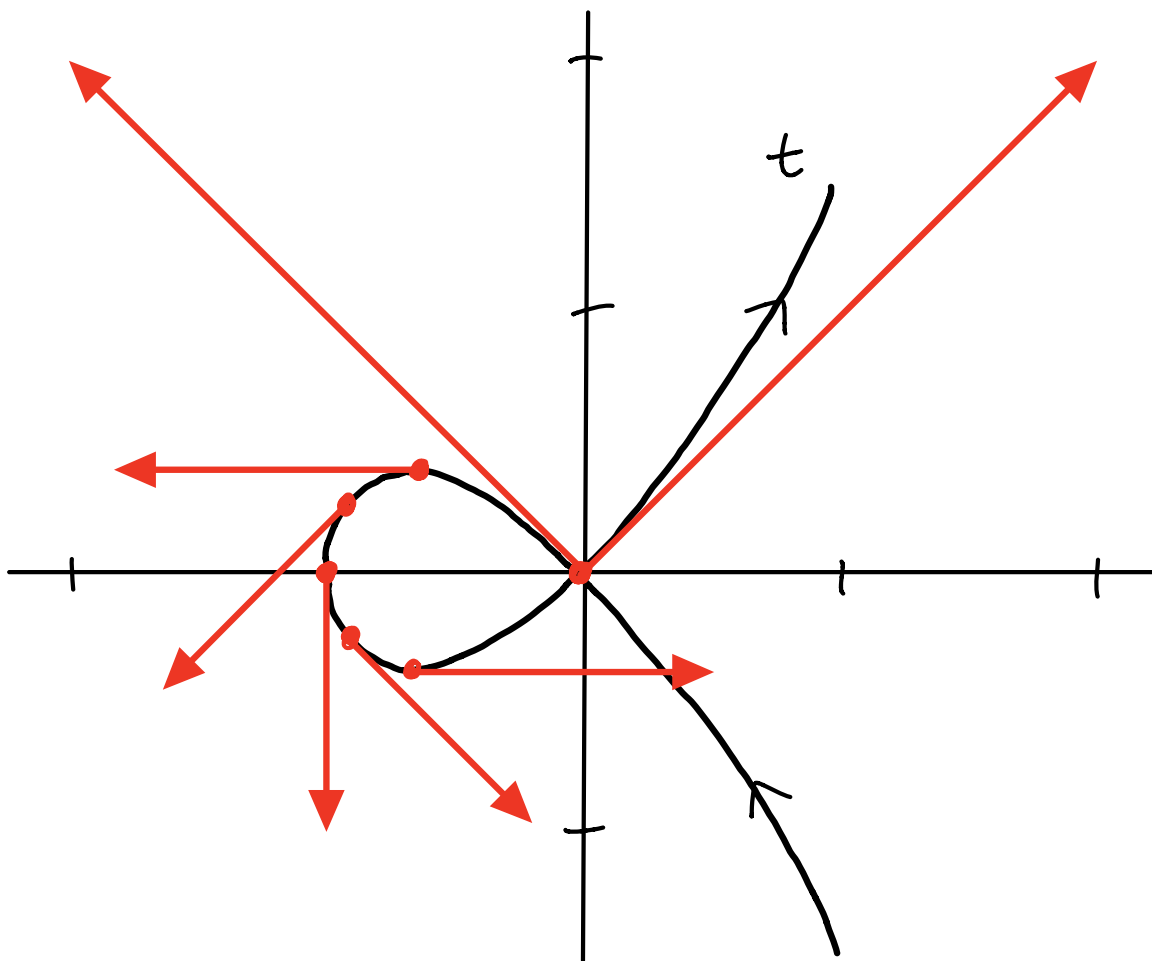
The slope is  $-1$  when  $t = -1$  or

$t = +1/3$  [similar calculation] so that

$$\vec{r}(-1) = (0, 0) \quad \text{or} \quad \vec{r}(1/3) \approx (-0.9, -0.3)$$

$$\vec{v}(-1) = (-2, 2) \quad \text{or} \quad \vec{v}(1/3) \approx (0.7, -0.7)$$

(c) Sketch



#### 4. Projectile Motion

A projectile is launched from  $(0,0)$  with initial speed  $100 \text{ ft/sec}$  and angle  $\theta$  above the horizontal, so

$$\vec{r}(0) = \langle 0, 0 \rangle,$$

$$\vec{v}(0) = \langle 100 \cos \theta, 100 \sin \theta \rangle.$$

The acceleration due to gravity is

$$\vec{a}(t) = \langle 0, -32 \rangle \text{ for all } t.$$

(a) By integrating twice we have

$$\vec{v}(t) = \langle 100 \cos \theta, -32t + 100 \sin \theta \rangle$$

$$\vec{r}(t) = \langle 100t \cos \theta, -16t^2 + 100t \sin \theta \rangle$$

[see the lecture notes for details.]

(b) The projectile hits the ground when

$$-16t^2 + 100t \sin \theta = 0$$

$$t(-16t + 100 \sin \theta) = 0,$$

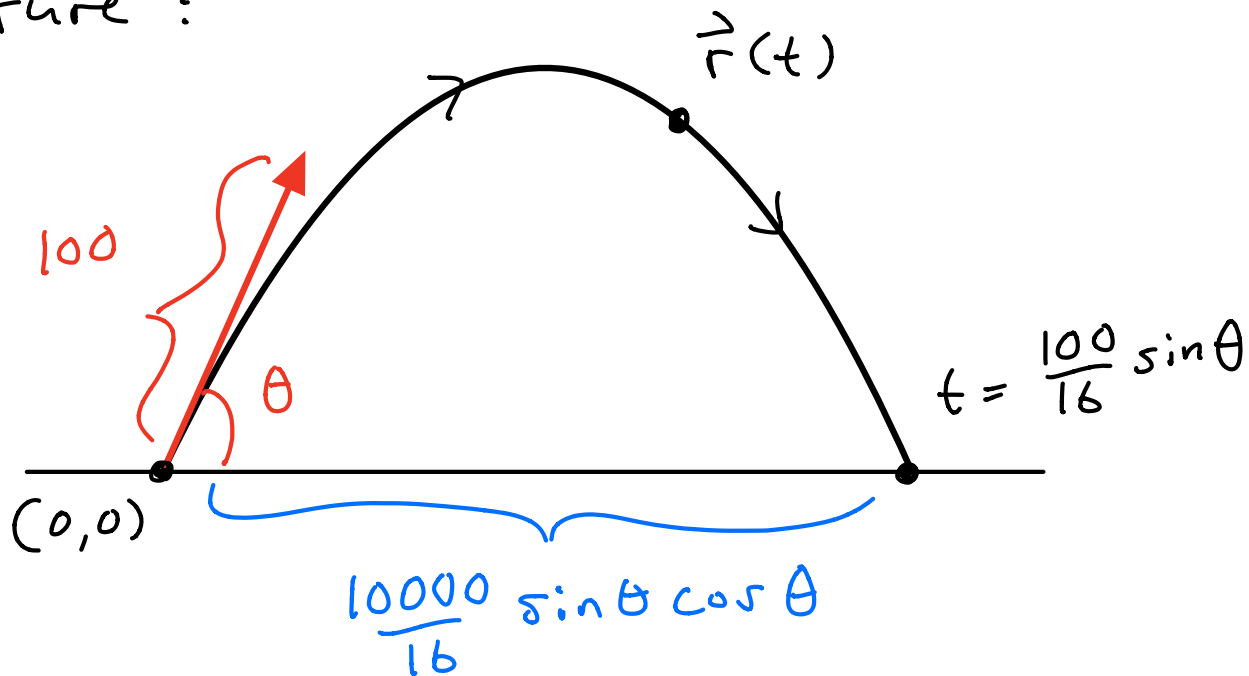


so  $t = 0$  or  $t = 100 \sin \theta / 16$ .

The horizontal distance traveled is

$$100 t \cos \theta = \frac{10000}{16} \sin \theta \cos \theta$$

Picture :



We want to maximize the distance as a function of  $\theta$ , so we set the derivative equal to zero:

$$\frac{d}{d\theta} \left( \frac{10000}{16} \sin \theta \cos \theta \right) = 0$$

$$\frac{10000}{16} [\cos \theta \cos \theta - \sin \theta \sin \theta] = 0$$

$$\cos^2 \theta - \sin^2 \theta = 0$$

$$\cos^2 \theta = \sin^2 \theta$$

$$\tan^2 \theta = 1$$

$$\tan \theta = \pm 1$$

assume  $\theta \neq 90^\circ$   
 $\theta \neq 0^\circ$

So  $\theta = 45^\circ$  or  ~~$135^\circ$~~  assume  $\theta < 90^\circ$

The maximum possible distance is

$$\frac{10000}{16} \cos(45^\circ) \sin(45^\circ) = 312.5 \text{ feet}$$

[ Remark : Actually the distance is always maximized at  $\theta = 45^\circ$  for any initial speed  $s$ . In the general case, the distance traveled is  $s^2 \cos \theta \sin \theta / 16$ , so the maximum possible distance is  $s^2 / 32$ , when  $\theta = 45^\circ$ . ]

## 5. Vector Identities.

(a) Given a vector  $\vec{r}$  (living in 137-dimensional space), let us define a new vector

$$\vec{u} = \frac{1}{\|\vec{r}\|} \vec{r}$$

scalar                      vector

To compute the length of  $\vec{u}$  we use the dot product formula:

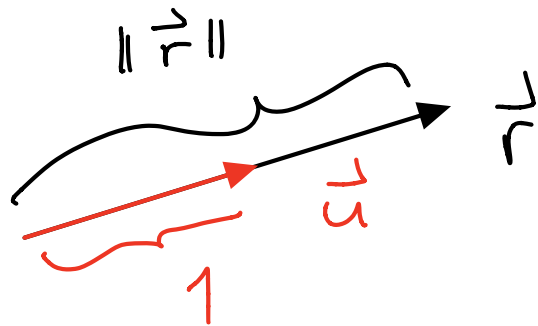
$$\begin{aligned} \|\vec{u}\|^2 &= \vec{u} \cdot \vec{u} \\ &= \left( \frac{1}{\|\vec{r}\|} \vec{r} \right) \cdot \left( \frac{1}{\|\vec{r}\|} \vec{r} \right) \\ &= \frac{1}{\|\vec{r}\|} \cdot \frac{1}{\|\vec{r}\|} (\vec{r} \cdot \vec{r}) \\ &= \frac{1}{\|\vec{r}\|} \cdot \frac{1}{\|\vec{r}\|} \|\vec{r}\|^2 = 1 \end{aligned}$$

We conclude that

$$\|\vec{u}\|^2 = 1$$

$$\|\vec{u}\| = 1$$

Jargon: We call  $\vec{u} = \vec{r} / \|\vec{r}\|$  a "unit vector" in the direction of  $\vec{r}$ .

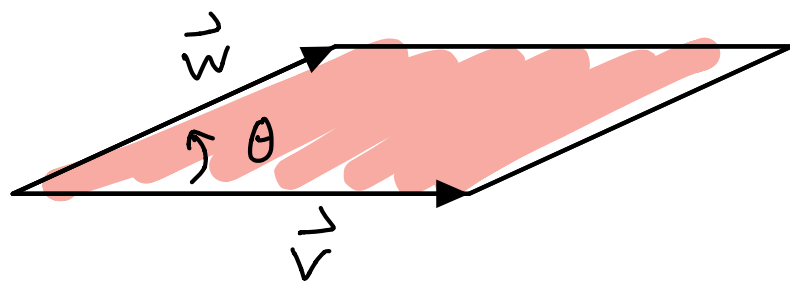


(b) For any  $\vec{v} = \langle v_1, v_2, v_3 \rangle$  we have that

$$\begin{aligned} \vec{v} \times \vec{v} &= \langle v_1, v_2, v_3 \rangle \times \langle v_1, v_2, v_3 \rangle \\ &= \langle v_2 v_3 - v_3 v_2, v_3 v_1 - v_1 v_3, v_1 v_2 - v_2 v_1 \rangle \\ &= \langle 0, 0, 0 \rangle \quad \checkmark \end{aligned}$$

Remark : There is a more satisfying geometric explanation for this. Given vectors  $\vec{v}, \vec{w}$  in  $\mathbb{R}^3$ , I claim that

$$\begin{aligned}\|\vec{v} \times \vec{w}\| &= \|\vec{v}\| \|\vec{w}\| \sin \theta \\ &= \text{area of the parallelogram spanned by } \vec{v}, \vec{w}.\end{aligned}$$



[ The proof is tricky so we won't discuss it. ]

Since the angle between  $\vec{v}$  and itself is 0 we get

$$\|\vec{v} \times \vec{v}\| = \|\vec{v}\| \|\vec{v}\| \sin 0 = 0$$

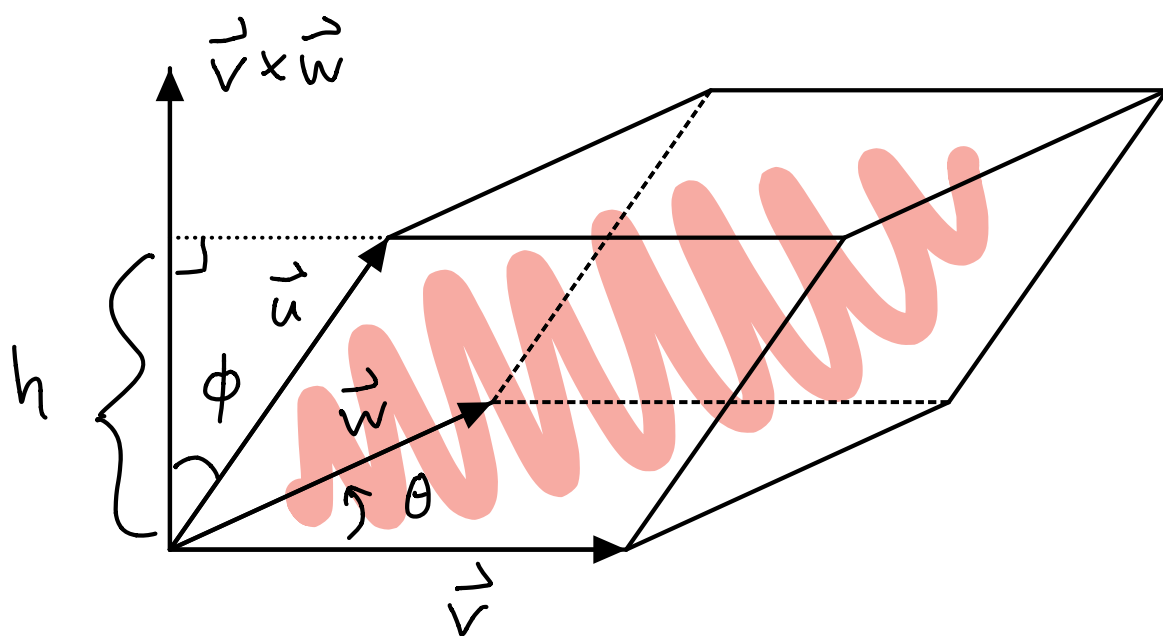
which implies that

$$\vec{v} \times \vec{v} = \langle 0, 0, 0 \rangle$$

[The only vector of length zero is the zero vector.]

This is also related to the "scalar triple product"

$$\vec{u} \cdot (\vec{v} \times \vec{w}) = \pm \text{Volume of parallelepiped}$$



The volume always equals

$$\begin{aligned}
\text{vol} &= \text{height} \cdot (\text{area of base}) \\
&= h \|\vec{v} \times \vec{w}\| \\
&= (\|\vec{u}\| \cos \phi) \|\vec{v} \times \vec{w}\| \\
&= \|\vec{u}\| \|\vec{v} \times \vec{w}\| \cos \phi \\
&= \vec{u} \cdot (\vec{v} \times \vec{w})
\end{aligned}$$

If  $\vec{u}$  is pointing below the plane generated by  $\vec{v}, \vec{w}$  (i.e. if  $\vec{v}, \vec{w}, \vec{u}$  is a "left handed system") then actually  $h = -\|\vec{u}\| \cos \phi$  and

$$\vec{u} \cdot (\vec{v} \times \vec{w}) = -\text{Vol}$$

(c) Suppose that a particle moves on the surface of a sphere of radius  $c$ :

$$\|\vec{r}(t)\| = c = \text{constant}$$

Then I claim that the velocity is always tangent to the sphere.

Proof: We have

$$\|\vec{r}(t)\|^2 = c^2$$

$$\vec{r}(t) \cdot \vec{r}(t) = c^2$$

Take the time derivative of both sides:

$$(\vec{r}(t) \cdot \vec{r}(t))' = (c^2)'$$

$$\vec{r}'(t) \cdot \vec{r}(t) + \vec{r}(t) \cdot \vec{r}'(t) = 0$$

$$2 \vec{r}(t) \cdot \vec{r}'(t) = 0$$

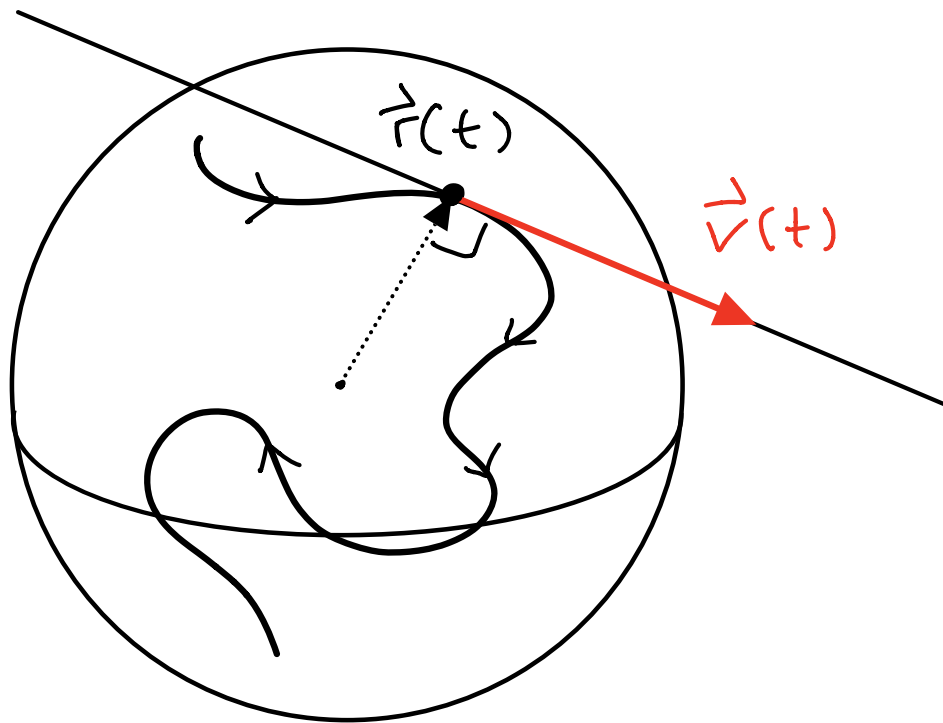
$$\vec{r}(t) \cdot \vec{r}'(t) = 0$$

for all times  $t$

In other words, the position vector  $\vec{r}(t)$  (which is a radius of the sphere) and the



velocity vector  $\vec{r}'(t) = \vec{v}(t)$   
are always perpendicular :



We used this in our computations  
yesterday when we said that

$\|\vec{u}(t)\| = 1$  for all  $t$  implies

that  $\vec{u}(t) \cdot \vec{u}'(t) = 0$  for all  $t$ .