

HW 4 due tomorrow before class.

Today: Invertibility of Matrices.

A function $f: X \rightarrow Y$ between sets is invertible if there exists a function $g: Y \rightarrow X$ in the opposite direction such that

$g \circ f: X \rightarrow X$ is the identity function
and

$f \circ g: Y \rightarrow Y$ is the identity function.

In other words, we require

$$g(f(x)) = x \text{ for all } x \in X$$

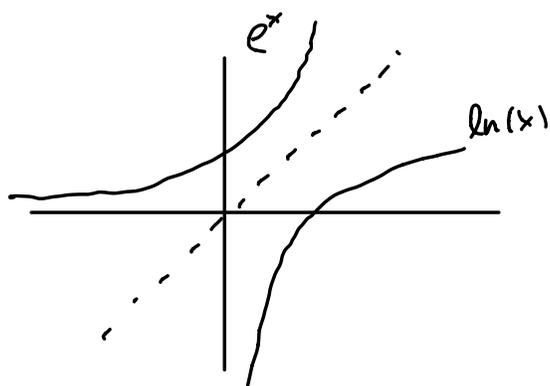
$$f(g(y)) = y \text{ for all } y \in Y.$$

In this case the function g is unique
and we write

$$\begin{aligned} g &= "f^{-1}" \\ &= "the inverse of f" \end{aligned}$$

Example : $f(x) = e^x$, $f: \mathbb{R} \rightarrow \mathbb{R}_{>0}$.

$g(x) = \ln(x)$, $g: \mathbb{R}_{>0} \rightarrow \mathbb{R}$.



Non Example : $\sin: \mathbb{R} \rightarrow [-1, 1]$

is not invertible, but $\sin: [0, 2\pi) \rightarrow [-1, 1]$

is invertible : $\sin^{-1}: [-1, 1] \rightarrow [0, 2\pi)$.

Theorem : $f: X \rightarrow Y$ is invertible
if and only if :

- it is "one-to-one", meaning that

$$x_1 \neq x_2 \implies f(x_1) \neq f(x_2).$$

- it is "onto", meaning that for any $y \in Y$ there exists some $x \in X$ such that $f(x) = y$.



Special Case: Let A be $m \times n$ matrix and consider the linear function

$$A : \mathbb{R}^n \rightarrow \mathbb{R}^m$$

① When is A "one-to-one"?

② When is A "onto"?

Suppose $r = \text{rank}(A)$

Theorem:

① A is "one-to-one"

$$\iff N(A) = \{ \vec{0} \}$$

$$\iff \dim N(A) = 0$$

$$\iff n - r = 0$$

$$\iff r = n$$

\iff the columns of A are independent.

\iff there exists at least one matrix C such that

$$\begin{array}{ccc} CA = I & & \\ \small n \times m \quad m \times n & & \small n \times n. \end{array}$$

② A is "onto"

$$\iff C(A) = \mathbb{R}^m$$

$$\iff \dim C(A) = m$$

$$\iff r = m.$$

\iff the rows of A are independent

\iff there exists at least one matrix B such that

$$\begin{matrix} AB = I \\ m \times n \quad n \times m \quad m \times m \end{matrix}$$

///

Example: $A = \begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & -3 \end{pmatrix}$. ($r=2$)

Since rank = # rows, we know that A has at least one right inverse.

$$AB = I$$

$$\begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & -3 \end{pmatrix} \begin{pmatrix} a & d \\ b & e \\ c & f \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

$$\begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & -3 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \Bigg| \quad \begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & -3 \end{pmatrix} \begin{pmatrix} d \\ e \\ f \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 1+2c \\ 3c \\ c \end{pmatrix}$$

$$\begin{pmatrix} d \\ e \\ f \end{pmatrix} = \begin{pmatrix} 2f \\ 1+3f \\ f \end{pmatrix}$$

$$\Rightarrow B = \begin{pmatrix} 1+2c & 2f \\ 3c & 1+3f \\ c & f \end{pmatrix}$$

Infinitely many solutions!

e.g., take $c=f=0$:

$$\begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & -3 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

Next, since rank \neq # columns, I claim that A has NO left inverse.

Proof: The columns of $\begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & -3 \end{pmatrix}$ are not independent. To be specific, we have a nontrivial relation:

$$2(\text{col } 1) + 3(\text{col } 2) + 1(\text{col } 3) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

In matrix language, this tells us a nonzero vector in the nullspace:

$$\begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & -3 \end{pmatrix} \begin{pmatrix} 2 \\ 3 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$A \vec{x} = \vec{0}.$$

If we had a left inverse, say $CA = I$, then this would imply

$3 \times 2 \quad 2 \times 3 \quad 3 \times 3$

$$A \begin{pmatrix} 2 \\ 3 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$CA \begin{pmatrix} 2 \\ 3 \\ 1 \end{pmatrix} = C \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$I \begin{pmatrix} 2 \\ 3 \\ 1 \end{pmatrix} = C \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$3 \times 2 \quad 2 \times 1$

$$\begin{pmatrix} 2 \\ 3 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \text{ NOPE!}$$

[Remark: $\begin{pmatrix} a & d \\ b & e \\ c & f \end{pmatrix} \begin{pmatrix} 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}.]$

HW 4.4b : If $A\vec{x} = \vec{0}$ and $\vec{x} \neq \vec{0}$
then A has no left inverse (hence also
no two-sided inverse). Proof: If
we had $CA = I$ then we would have

$$\begin{aligned}A\vec{x} &= \vec{0} \\CA\vec{x} &= C\vec{0} \\I\vec{x} &= C\vec{0} \\ \vec{x} &= \vec{0} \\ \text{Contradiction!}\end{aligned}$$



Two-Sided Inverse ?

Theorem: If $AB = I$ & $CA = I$
then we must have

$$B = IB = (CA)B = C(AB) = CI = C$$

In other words, if A has both a
left and a right inverse, then it
has a unique two-sided inverse.

Call it A^{-1} .

- ① When does it exist?
- ② How can we compute it?

Theorem:

① A^{-1} exists

\iff A is one-to-one & onto

\iff $r = n$ & $r = m$ (hence $m = n$)

In other words, A^{-1} exists when

- A is square, ($m = n$)
- Rows of A are independent, ($r = m$)
- Columns of A are independent. ($r = n$)

② To compute A^{-1} there is a GOOD TRICK. Form the augmented matrix $(A | I)$. Compute RREF:

$$(A | I) \xrightarrow{\text{RREF}} (I | A^{-1}).$$



Example: $A = \begin{pmatrix} 1 & 2 \\ 2 & 2 \end{pmatrix}$.

SQUARE ✓

RANK = # ROWS = # COLS ✓

Compute the inverse $A^{-1} = \begin{pmatrix} a & c \\ b & d \end{pmatrix}$.

$$\begin{pmatrix} 1 & 2 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} a & c \\ b & d \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$



$$\begin{pmatrix} 1 & 2 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} c \\ d \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & | & 1 \\ 2 & 2 & | & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & | & 0 \\ 2 & 2 & | & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & | & 1 \\ 0 & -2 & | & -2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & | & 0 \\ 0 & -2 & | & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & | & 1 \\ 0 & 1 & | & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & | & 0 \\ 0 & 1 & | & -1/2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & | & -1 \\ 0 & 1 & | & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & | & 1 \\ 0 & 1 & | & -1/2 \end{pmatrix}$$

$$\begin{cases} a + 0b = -1 \\ 0a + b = 1 \end{cases}$$

$$\begin{cases} c + 0d = 1 \\ 0c + d = -\frac{1}{2} \end{cases}$$

$$\Rightarrow A^{-1} = \begin{pmatrix} a & c \\ b & d \end{pmatrix} = \begin{pmatrix} -1 & 1 \\ 1 & -\frac{1}{2} \end{pmatrix}.$$

[Remark: And the solution is unique!]

Check:

$$\begin{pmatrix} 1 & 2 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} -1 & 1 \\ 1 & -\frac{1}{2} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \checkmark$$

Do we need to check the other

direction? $\begin{pmatrix} -1 & 1 \\ 1 & -\frac{1}{2} \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 2 & 2 \end{pmatrix} = ?$

NO. This is guaranteed to work out.

Theorem: If A, B are square then

$$AB = I \Leftrightarrow BA = I.$$

You only need to check one of these.

Proof: This is quite subtle, but it follows from the above theorems. //

Note that to find $\begin{pmatrix} 1 & 2 \\ 2 & 2 \end{pmatrix}^{-1}$
 we had to compute the RREF
 of two very similar matrices:

$$\left(\begin{array}{cc|c} 1 & 2 & 1 \\ 2 & 2 & 0 \end{array} \right) \xrightarrow{\text{RREF}} \left(\begin{array}{cc|c} 1 & 0 & -1 \\ 0 & 1 & 1 \end{array} \right)$$

$$\left(\begin{array}{cc|c} 1 & 2 & 0 \\ 2 & 2 & 1 \end{array} \right) \xrightarrow{\text{RREF}} \left(\begin{array}{cc|c} 1 & 0 & 1 \\ 0 & 1 & -1/2 \end{array} \right)$$

The GOOD TRICK just tells us
 to perform these computations
simultaneously:

$$\left(\begin{array}{cc|cc} 1 & 2 & 1 & 0 \\ 2 & 2 & 0 & 1 \end{array} \right) \rightsquigarrow \left(\begin{array}{cc|cc} 1 & 0 & -1 & 1 \\ 0 & 1 & 1 & -1/2 \end{array} \right)$$

If remove one of the vertical bars
 then this becomes

$$\left(\begin{array}{cc|cc} 1 & 2 & 1 & 0 \\ 2 & 2 & 0 & 1 \end{array} \right) \rightarrow \left(\begin{array}{cc|cc} 1 & 0 & -1 & 1 \\ 0 & 1 & 1 & -1/2 \end{array} \right)$$

$$(A | I) \rightarrow (I | A^{-1}) \quad \text{NICE} \quad \ddot{\smile}$$

Another Example :

$$A = \begin{pmatrix} 1 & 1 & 2 \\ 1 & 2 & 2 \\ 2 & 3 & 4 \end{pmatrix}, \quad A^{-1} = ?$$

$$\left(\begin{array}{ccc|ccc} \textcircled{1} & 1 & 2 & 1 & 0 & 0 \\ 1 & 2 & 2 & 0 & 1 & 0 \\ 2 & 3 & 4 & 0 & 0 & 1 \end{array} \right)$$

$$\rightarrow \left(\begin{array}{ccc|ccc} \textcircled{1} & 1 & 2 & 1 & 0 & 0 \\ 0 & \textcircled{1} & 0 & -1 & 1 & 0 \\ 0 & 1 & 0 & -2 & 0 & 1 \end{array} \right)$$

$$\rightarrow \left(\begin{array}{ccc|ccc} \textcircled{1} & 1 & 2 & 1 & 0 & 0 \\ 0 & \textcircled{1} & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & -1 & -1 & 1 \end{array} \right)$$

oops!

What Happened?

We just found out that

$$\text{rank}(A) = 2.$$

So the inverse does not exist!

Hint for HW 4.3 :

If A^{-1} exists, then the matrix equation $A\vec{x} = \vec{b}$ can be solved symbolically:

$$\begin{aligned}A\vec{x} &= \vec{b} \\A^{-1}A\vec{x} &= A^{-1}\vec{b} \\I\vec{x} &= A^{-1}\vec{b} \\ \vec{x} &= A^{-1}\vec{b} .\end{aligned}$$

This is the power of matrix arithmetic. It can turn complicated problems into simple algebra.



Preview for next week :

Suppose that the equation $A\vec{x} = \vec{b}$ has no solution. What can we do?

The "Least Squares Approximation"

tells us to multiply on the left by A^T to get

$$A^T A \vec{x} = A^T \vec{b}.$$

Under good conditions, the matrix $A^T A$ is invertible, hence

$$\vec{x} = (A^T A)^{-1} A^T \vec{b}.$$

↗
This is not an exact solution to the original $A\vec{x} = \vec{b}$ (because it has no exact solution) but it is a "best approximate solution" in some precise sense that we will discuss next week.