

Quiz 1 Discussion:

Given $\vec{x} \cdot \vec{x} = \vec{y} \cdot \vec{y} = 1$ & $\vec{x} \cdot \vec{y} = 0$,
find the angle between $\vec{x} + \vec{y}$ & $\vec{x} - \vec{y}$.

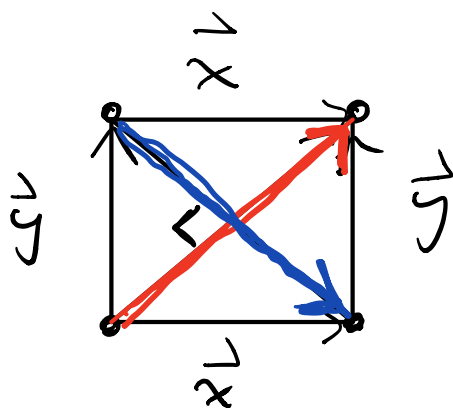
$$\text{Say } \vec{u} = \vec{x} + \vec{y}$$
$$\vec{v} = \vec{x} - \vec{y}.$$

$$\begin{aligned}\vec{u} \cdot \vec{v} &= (\vec{x} + \vec{y}) \cdot (\vec{x} - \vec{y}) \\ &= \vec{x} \cdot \vec{x} + \vec{x} \cdot \vec{y} - \vec{x} \cdot \vec{y} - \vec{y} \cdot \vec{y} \\ &= 1 + 0 - 0 - 1 \\ &= 0.\end{aligned}$$

$$\text{Hence } \cos \theta = \frac{0}{\|\vec{u}\| \|\vec{v}\|} = 0.$$

$$\text{So } \theta = 90^\circ.$$

Picture:



$\vec{x} + \vec{y}$ & $\vec{x} - \vec{y}$
are diagonals of
a square, hence
perpendicular.

More generally, let \vec{x} & \vec{y} be any vectors of the same length, so

$$\|\vec{x}\| = \|\vec{y}\|$$

$$\|\vec{x}\|^2 = \|\vec{y}\|^2$$

$$\vec{x} \cdot \vec{x} = \vec{y} \cdot \vec{y}$$

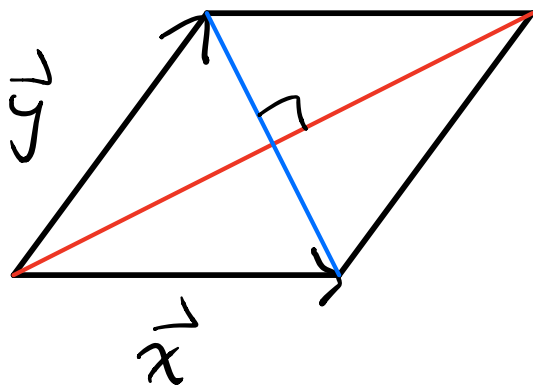
Then we have

$$(\vec{x} + \vec{y}) \cdot (\vec{x} - \vec{y})$$

$$= \cancel{\vec{x} \cdot \vec{x}} + \cancel{\vec{x} \cdot \vec{y}} - \cancel{\vec{x} \cdot \vec{y}} - \cancel{\vec{y} \cdot \vec{y}}$$

$$= 0.$$

Picture:



Theorem: The diagonals in a "rhombus" are perpendicular.

New Topic : Planes in \mathbb{R}^3

& Introduction to Linear Systems.

How to describe a plane in \mathbb{R}^3 ?

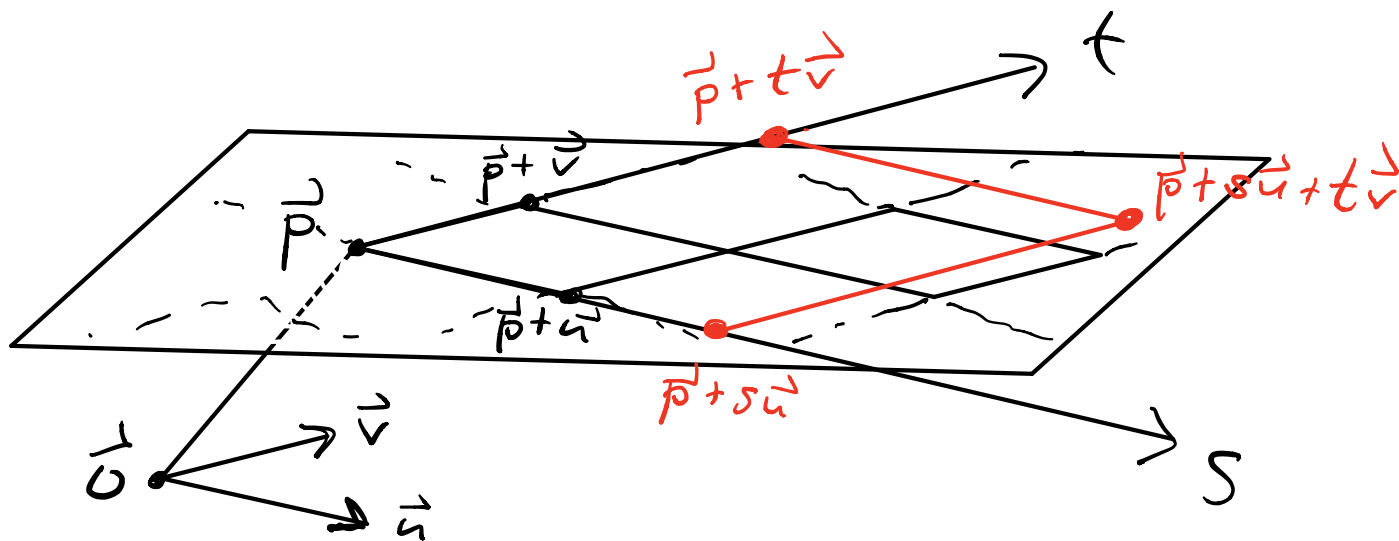
- A point \vec{p}
& two direction vectors \vec{u} & \vec{v} .

Then points \vec{x} on the plane have

the form $\boxed{\vec{x} = \vec{p} + s\vec{u} + t\vec{v}}$

two parameters

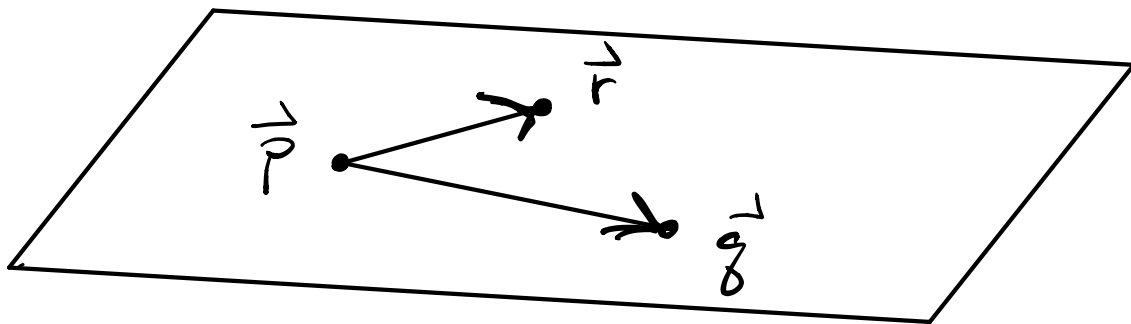
Picture :



Every point in the plane has the form " $\vec{p} + s\vec{u} + t\vec{v}$ " for some unique values of s & t . We could call this the " (s, t) -plane."

We can think of \vec{p} , \vec{u} & \vec{v} as a "coordinate system" for the plane.

- Three points \vec{p} , \vec{q} , \vec{r} .



We can take $\vec{u} = \vec{q} - \vec{p}$
 $\vec{v} = \vec{r} - \vec{p}$

as direction vectors, so that

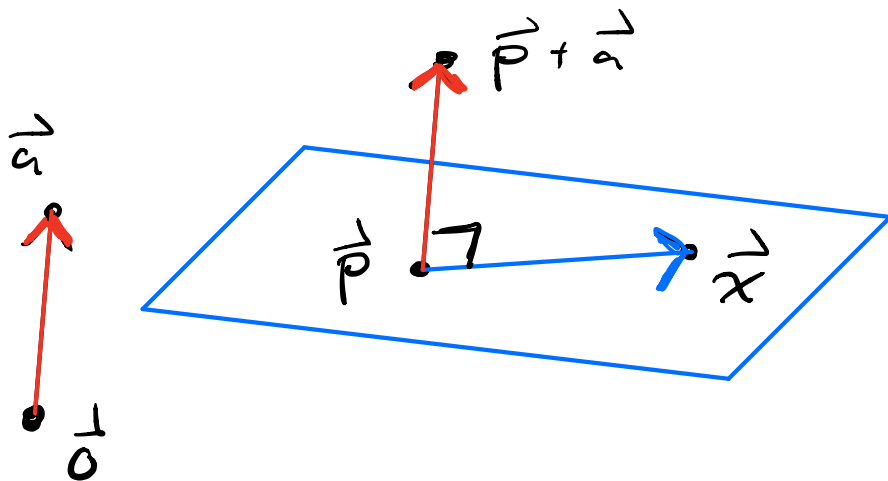
$$\begin{aligned} \text{plane} &= \{ \vec{p} + s\vec{u} + t\vec{v} : s, t \in \mathbb{R} \} \\ &= \{ \vec{p} + s(\vec{q} - \vec{p}) + t(\vec{r} - \vec{p}) : s, t \in \mathbb{R} \} \end{aligned}$$

$$= \left\{ \underbrace{(1-s-t)}_{\text{coeffs. add to 1.}} \vec{p} + s\vec{q} + t\vec{r} : s, t \in \mathbb{R} \right\}$$

$$= \left\{ x\vec{p} + y\vec{q} + z\vec{r} : x+y+z=1 \right\}$$

[Once you've seen lines in \mathbb{R}^2 and planes in \mathbb{R}^3 you can easily imagine how these formulas generalize to higher dimensions ...]

- A point \vec{p} & a normal vector \vec{a} .



For any point \vec{x} on the plane we require that vector $\vec{x} - \vec{p}$ is

perpendicular to vector \vec{a} :

$$\vec{a} \cdot (\vec{x} - \vec{p}) = 0.$$

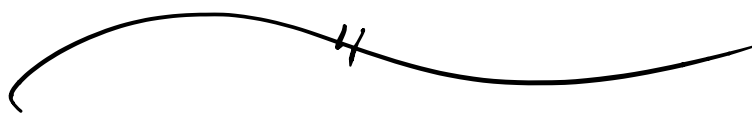
$$\vec{a} \cdot \vec{x} - \vec{a} \cdot \vec{p} = 0$$

$$\vec{a} \cdot \vec{x} = \vec{a} \cdot \vec{p}$$

$$\vec{a} \cdot \vec{x} = \text{constant.}$$

$$\begin{pmatrix} a \\ b \\ c \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \text{const.}$$

$$ax + by + cz = \text{const.}$$



Examples :

Express the plane $x + 2y + 3z = 1$
in the "parametric form"

$$\vec{x} = \vec{p} + s\vec{u} + t\vec{v}.$$

Let's take $\vec{p} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ ok ✓

Tell me 2 more points on the plane.

$$\vec{q} = \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} \text{ \& } \vec{r} = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \text{ ✓}$$

$$\text{Let } \vec{u} = \vec{q} - \vec{p} = \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} - \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix}$$

$$\vec{v} = \vec{r} - \vec{p} = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} - \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix}$$

be direction vectors. Then

$$\vec{x} = \vec{p} + s\vec{u} + t\vec{v}$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + s \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix} + t \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix}$$

$$\begin{cases} x = 1 - s - 2t, \\ y = -s + t, \\ z = s. \end{cases}$$

But this answer is not unique.

There are ∞ many ways to parametrize a plane.

Quick Method (Shortcut):

Let $y = s$ & $z = t$. Then

$$\boxed{x + 2y + 3z = 1} \quad \text{Definition of the plane.}$$
$$x + 2s + 3t = 1$$

$$x = 1 - 2s - 3t.$$

$$\begin{cases} x = 1 - 2s - 3t, \\ y = s, \\ z = t. \end{cases}$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 - 2s - 3t \\ s \\ t \end{pmatrix}$$

$$= \begin{pmatrix} 1 - 2s - 3t \\ 0 + 1s + 0t \\ 0 + 0s + 1t \end{pmatrix}$$

$$= \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + s \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix} + t \begin{pmatrix} -3 \\ 0 \\ 1 \end{pmatrix}.$$

So $\vec{u} = \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix}$ & $\vec{v} = \begin{pmatrix} -3 \\ 0 \\ 1 \end{pmatrix}$ is

another valid choice of direction vectors for the plane.



On Thurs we will begin with more examples.....