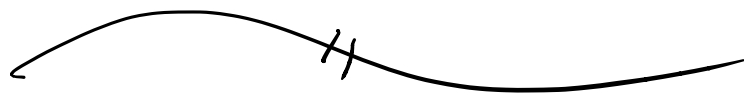


HW 3 is due now.

Today : HW3 Discussion
+ Review for Quiz 3.



General Remarks :

Consider a system of m linear equations in n unknowns :

$$\begin{cases} \vec{a}_1 \cdot \vec{x} = b_1, \\ \vec{a}_2 \cdot \vec{x} = b_2, \\ \vdots \\ \vec{a}_m \cdot \vec{x} = b_m, \end{cases}$$

where $\vec{x} = (x_1, x_2, \dots, x_n)$ are the variables & $\vec{a}_i = (a_{i1}, a_{i2}, \dots, a_{in})$ are some constant vectors.

By Problem 4, the set of solutions is "flat." What does this mean?

The solutions live in n -dim space:

$$S \subseteq \mathbb{R}^n$$

$$S = \left\{ \vec{x} \in \mathbb{R}^n : \vec{a}_i \cdot \vec{x} = b_i \text{ for all } i \right\}$$

What kind of shape is S ?

Claim: If \vec{p} & \vec{q} are two points in S then the whole line

$$(1-t)\vec{p} + t\vec{q}$$

is in S .

are in
the set

Proof: Assume $\vec{p}, \vec{q} \in S$. By

definition this means that

$$\vec{a}_i \cdot \vec{p} = b_i \quad \& \quad \vec{a}_i \cdot \vec{q} = b_i$$

for all $i = 1, 2, \dots, m$. Then for any scalar t and for any $i = 1, 2, \dots, m$ we have

$$\vec{a}_i \cdot \left[(1-t)\vec{p} + t\vec{q} \right]$$

$$= (1-t) \vec{a}_i \cdot \vec{p} + t \vec{a}_i \cdot \vec{q}$$

$$= (1-t) b_i + t b_i$$

$$= b_i - \cancel{t b_i} + t b_i$$

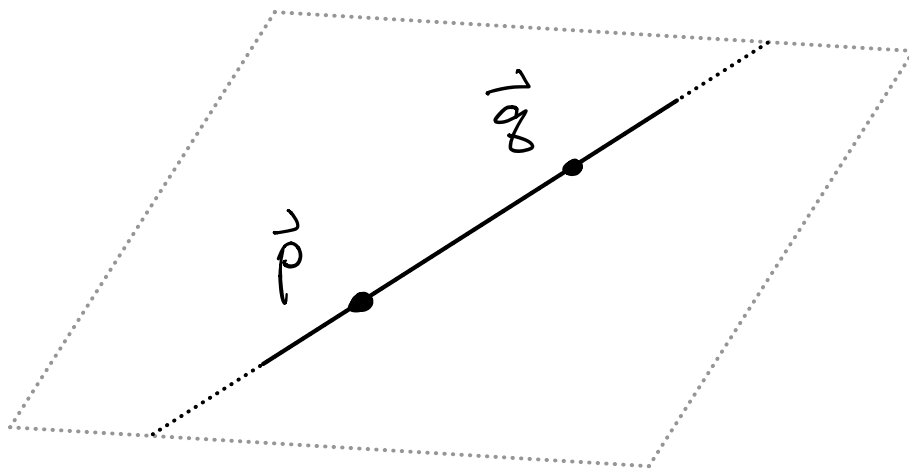
$$= b_i$$

By definition, this means that

$$(1-t)\vec{p} + t\vec{q} \in \mathcal{S}.$$

"The point $(1-t)\vec{p} + t\vec{q}$ is in the set of solutions of the system."

Picture: The solution set is "flat."



Conclusion: The solution set of a system of m linear equations in n unknowns is either empty, or it is a " d -plane" for some d .

Meaning:

$$S = \left\{ \vec{p} + t_1 \vec{u}_1 + \dots + t_d \vec{u}_d : \text{scalars } t \right\}$$

where $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_d \in \mathbb{R}^n$

are independent vectors living in n -dimensional space.



How to compute d & find some vectors $\vec{p}, \vec{u}_1, \vec{u}_2, \dots, \vec{u}_d$?

Answer: RREF.

Perform Gaussian elimination on the system. If we get some equation of the form

$$0x_1 + 0x_2 + \dots + 0x_n = c$$

where $c \neq 0$, then there is no solution. Otherwise, the solution is a d -plane where

$$d = \# \text{ free variables in the RREF.}$$

Example: Problem 2.

$$\begin{cases} x_1 + 2x_2 + x_3 + 0 + 2x_5 = 1, \\ x_1 + 2x_2 + 2x_3 - 3x_4 + 3x_5 = 1, \\ x_1 + 2x_2 + 0 + 3x_4 + 2x_5 = 3. \end{cases}$$

↓ RREF

$$\begin{cases} x_1 + 2x_2 + 0 + 3x_4 + 0 = -1, \\ 0 + 0 + x_3 - 3x_4 + 0 = -2, \\ 0 + 0 + 0 + 0 + x_5 = 2. \end{cases}$$

[See HW3 solutions for the steps.]

Pivot variables : x_1, x_3, x_5

Free variables : x_2, x_4

Rename : $s = x_2$ & $t = x_4$

The solution is

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix} = \begin{pmatrix} -1 - 2s - 3t \\ s \\ -2 + 3t \\ t \\ 2 \end{pmatrix}$$

$$= \begin{pmatrix} -1 \\ 0 \\ -2 \\ 0 \\ 2 \end{pmatrix} + s \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + t \begin{pmatrix} -3 \\ 0 \\ 3 \\ 1 \\ 0 \end{pmatrix}$$

$$= \vec{p} + s\vec{u} + t\vec{v}$$

A 2-plane living in 5-dim space.

In this case

$$m = \# \text{ eqns} = 3$$

$$n = \# \text{ variables} = 5$$

$$d = \# \text{ free variables} = 2.$$

In general, let

$r = \#$ pivot variables

$d = \#$ free variables

so that

$$r + d = \text{total } \# \text{ variables} = n$$

There can be at most one pivot in each row, so that

$$0 \leq r \leq m$$

$$0 \leq \# \text{ pivot vars} \leq \# \text{ equations}$$

Apply the formula $r + d = n$

$$-m \leq -r \leq 0$$

$$n - m \leq n - r \leq n$$

$$n - m \leq d \leq n.$$

Assuming the solution is not empty,

the dimension of the solution must satisfy

$$n - m \leq d \leq n$$

If the system was chosen "randomly" I have claimed that $n - m = d$, i.e.,

$$\text{dim of solutions} = \# \text{ variables} - \# \text{ equations.}$$

More precisely, this happens when

$$r = m,$$

i.e., when there is a pivot in every row, i.e., when the row vectors of the system have no linear relations.

"no row relations"

Example : Problem 2

The row vectors of matrix

$$\begin{pmatrix} 1 & 2 & 1 & 0 & 2 & 1 \\ 1 & 2 & 2 & -3 & 3 & 1 \\ 1 & 2 & 0 & 3 & 2 & 3 \end{pmatrix}$$

are independent, i.e., they point in "3 different directions." This is why we got a pivot in every row of RREF.

Example : Problem 1.

$$\begin{cases} x + 2y + 3z = 4, \\ x + 2y + 4z = 6, \\ x + 2y + 5z = 8. \end{cases}$$

\downarrow RREF

$$\begin{cases} \boxed{x} + 2y + 0 = -2, \\ 0 + 0 + \boxed{z} = 2, \\ 0 + 0 + 0 = 0. \end{cases}$$

Pivot variables : x, z

Free variables : y .

Rename : $t = y$.

The solution is

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -2 - 2t \\ t \\ z \end{pmatrix}$$

$$= \begin{pmatrix} -2 \\ 0 \\ 2 \end{pmatrix} + t \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix}$$

$$= \vec{p} + t\vec{u}$$

A 1-plane (i.e., a line) living
in 3-dimensional space \mathbb{R}^3 .

$$m = \# \text{ equations} = 3$$

$$n = \# \text{ variables} = 3$$

$$r = \# \text{ pivot variables} = 2$$

$$d = \# \text{ free variables} = 1.$$

In this case we have

$$n - m < d$$

because

$$r < m.$$

$$\# \text{ pivots} < \# \text{ rows}.$$

We did not get a pivot in every row. Why not?

There must be a "row relation" in the matrix

$$A = \begin{pmatrix} 1 & 2 & 3 & 4 \\ 1 & 2 & 4 & 6 \\ 1 & 2 & 5 & 8 \end{pmatrix}.$$

How can we find this relation?

$$\begin{aligned} r(\text{row } 1) + s(\text{row } 2) + t(\text{row } 3) \\ = (0 \ 0 \ 0 \ 0) \end{aligned}$$

for some r, s, t not all zero.

Find r, s, t .

TRICK: Problem 3.

Flip the matrix on its side:

$$A^T = \begin{pmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 3 & 4 & 5 \\ 4 & 6 & 8 \end{pmatrix}.$$

"the transpose of A "

Compute the RREF of A^T :

$$\text{RREF}(A^T) = \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}.$$

So what? In $\text{RREF}(A^T)$
we observe that

$$(\text{col } 3) = -1(\text{col } 1) + 2(\text{col } 2)$$

$$\begin{pmatrix} -1 \\ 2 \\ 0 \\ 0 \end{pmatrix} = -1 \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + 2 \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$$

EASY.

TRICK : Column relations are unchanged by row operations.

So the same column relation must hold in A^T :

$$\begin{pmatrix} 1 \\ 2 \\ 5 \\ 8 \end{pmatrix} = -1 \begin{pmatrix} 1 \\ 2 \\ 3 \\ 4 \end{pmatrix} + 2 \begin{pmatrix} 1 \\ 2 \\ 4 \\ 6 \end{pmatrix}$$

[Maybe you could have found this relation by trial-and-error, but RREF is a systematic method.]

Finally :

column relations in A^T = row relations in A .

Conclusion: In the matrix

$$A = \begin{pmatrix} 1 & 2 & 3 & 4 \\ 1 & 2 & 4 & 6 \\ 1 & 2 & 5 & 8 \end{pmatrix} \begin{matrix} \textcircled{1} \\ \textcircled{2} \\ \textcircled{3} \end{matrix}$$


we have row relation

$$\textcircled{3} = -1\textcircled{1} + 2\textcircled{2}$$

$$1\textcircled{1} - 2\textcircled{2} - 1\textcircled{3} = (0 \ 0 \ 0 \ 0)$$

$$(r, s, t) = (1, -2, -1).$$

And this is why RREF(A)

has a row of zeroes 

In other words, the system

$$\begin{cases} \textcircled{1} & x + 2y + 3z = 4, \\ \textcircled{2} & x + 2y + 4z = 6, \\ \textcircled{3} & x + 2y + 5z = 8, \end{cases}$$

really only has 2 independent equations.

Problem 5:

Let $U \subseteq \mathbb{R}^n$ be a "d-dimensional subspace of \mathbb{R}^n ."

Jargon:

"d-dim subspace" = "d-plane passing through $\vec{0}$ "

Why the fancy name? Never mind.

So, $U \subseteq \mathbb{R}^n$ d-dim subspace means

$$U = \left\{ t_1 \vec{u}_1 + \dots + t_d \vec{u}_d : t_1, \dots, t_d \in \mathbb{R} \right\}$$

for some independent vectors

$$\vec{u}_1, \vec{u}_2, \dots, \vec{u}_d \in \mathbb{R}^n$$

[This implies that $d \leq n$.]

Now let $U^\perp \subseteq \mathbb{R}^n$ be the

"orthogonal complement" of U .

Meaning:

For all $\vec{x} \in U$ & $\vec{y} \in U^\perp$ we have

$$\vec{x} \cdot \vec{y} = 0.$$

Then I claim that

$$\dim U + \dim U^\perp = \dim \mathbb{R}^n$$

$$d + \dim U^\perp = n$$

$$\dim U^\perp = n - d.$$

Example: Let $U \subseteq \mathbb{R}^4$ be the following 2-plane in \mathbb{R}^4 :

$$U = s \begin{pmatrix} 1 \\ 1 \\ 2 \\ 2 \end{pmatrix} + t \begin{pmatrix} 1 \\ 2 \\ 3 \\ 4 \end{pmatrix} = s\vec{u} + t\vec{v}$$

We want to find all the vectors $\vec{x} \in \mathbb{R}^4$ that are perpendicular to this 2-plane.

[This should remind you of the cross product, but the cross product only works in \mathbb{R}^3 .]

In our case:

$$U^\perp = \left\{ \vec{x} \in \mathbb{R}^4 : \vec{u} \cdot \vec{x} = 0 \text{ \& \ } \vec{v} \cdot \vec{x} = 0 \right\}$$

In other words, U^\perp is the solution set of the following linear system:

$$\begin{cases} x_1 + x_2 + 2x_3 + 2x_4 = 0, \\ x_1 + 2x_2 + 3x_3 + 4x_4 = 0. \end{cases}$$

↓ RREF

$$\begin{cases} x_1 + 0 + x_3 + 0 = 0, \\ 0 + x_2 + x_3 + 2x_4 = 0. \end{cases}$$

Pivot variables: x_1, x_2

Free variables: x_3, x_4 .

Rename : $s = x_3$, $t = x_4$

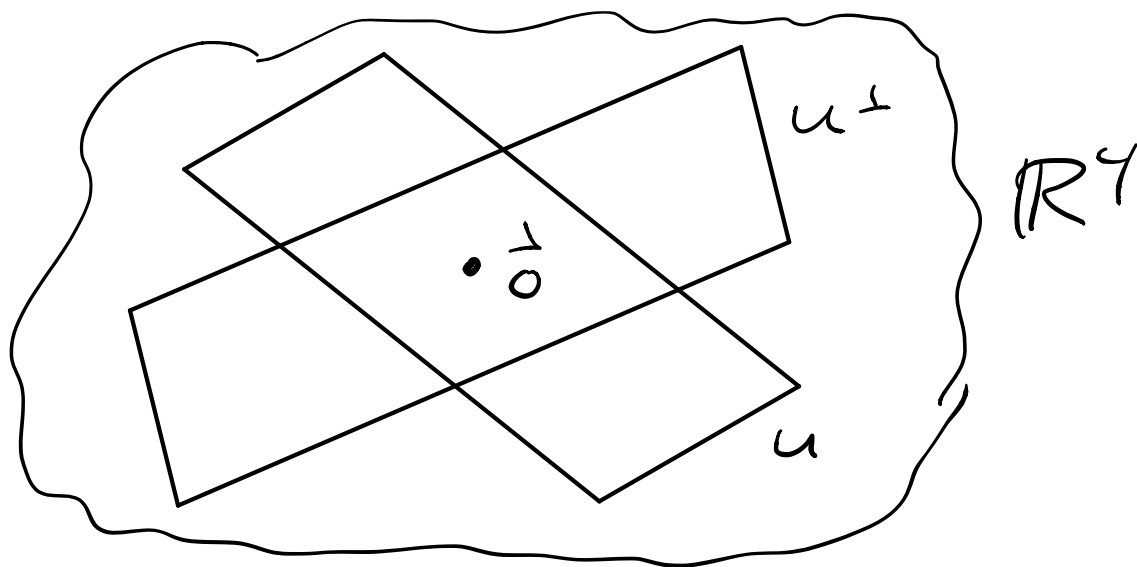
Solution :

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} -s \\ -s - 2t \\ s \\ t \end{pmatrix}$$

$$= s \begin{pmatrix} -1 \\ -1 \\ 1 \\ 0 \end{pmatrix} + t \begin{pmatrix} 0 \\ -2 \\ 0 \\ 1 \end{pmatrix} .$$

This is a 2-plane in \mathbb{R}^4 .

So, the orthogonal complement of a 2-plane in \mathbb{R}^4 is another 2-plane. Bad Picture :

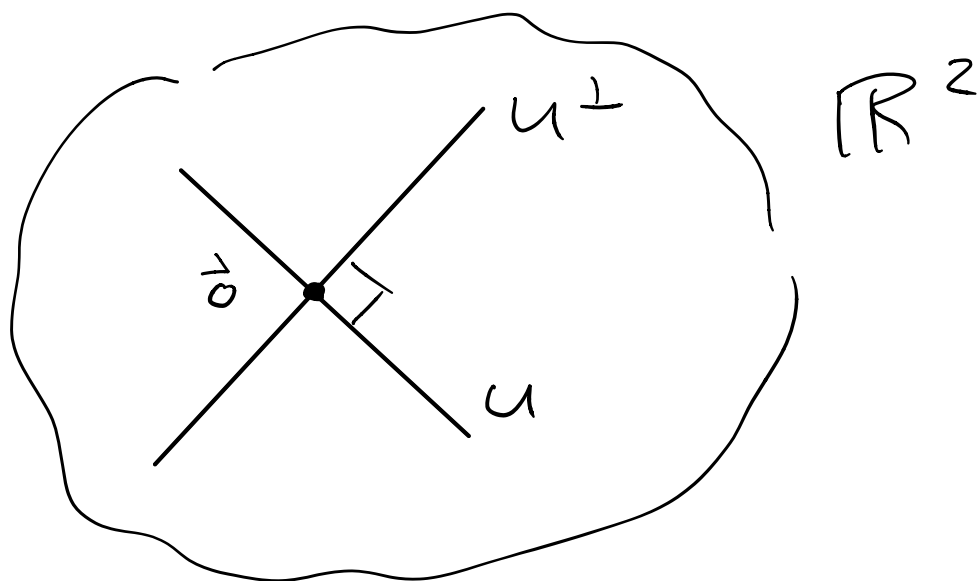


We have two 2-planes in \mathbb{R}^4 that are perpendicular and meet only at a single point, the origin.

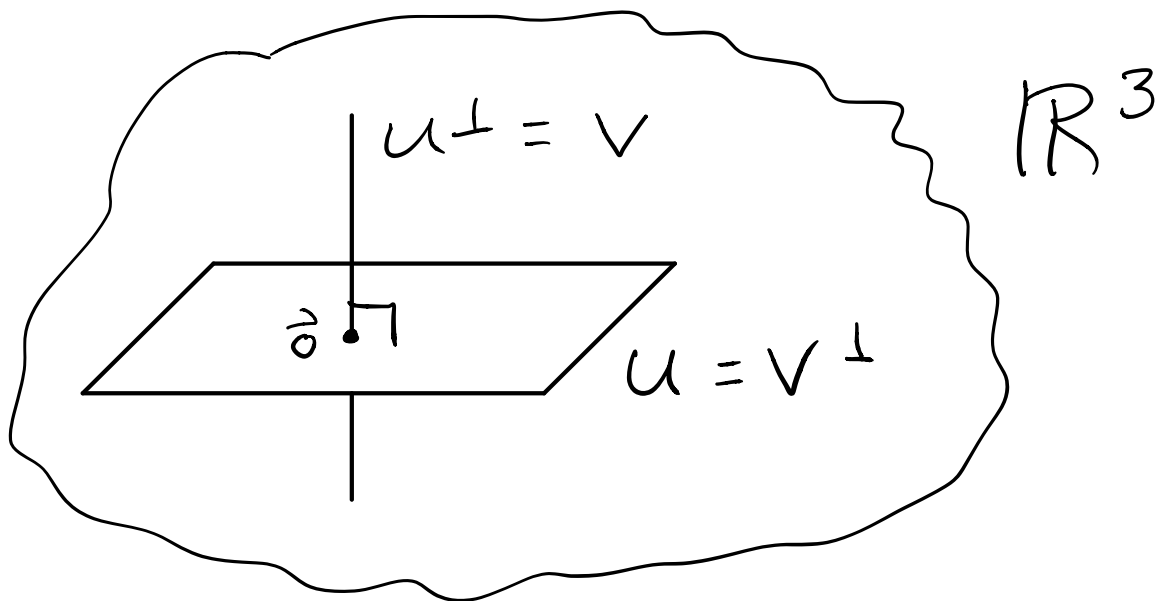
Can you visualize this?

No you can't!

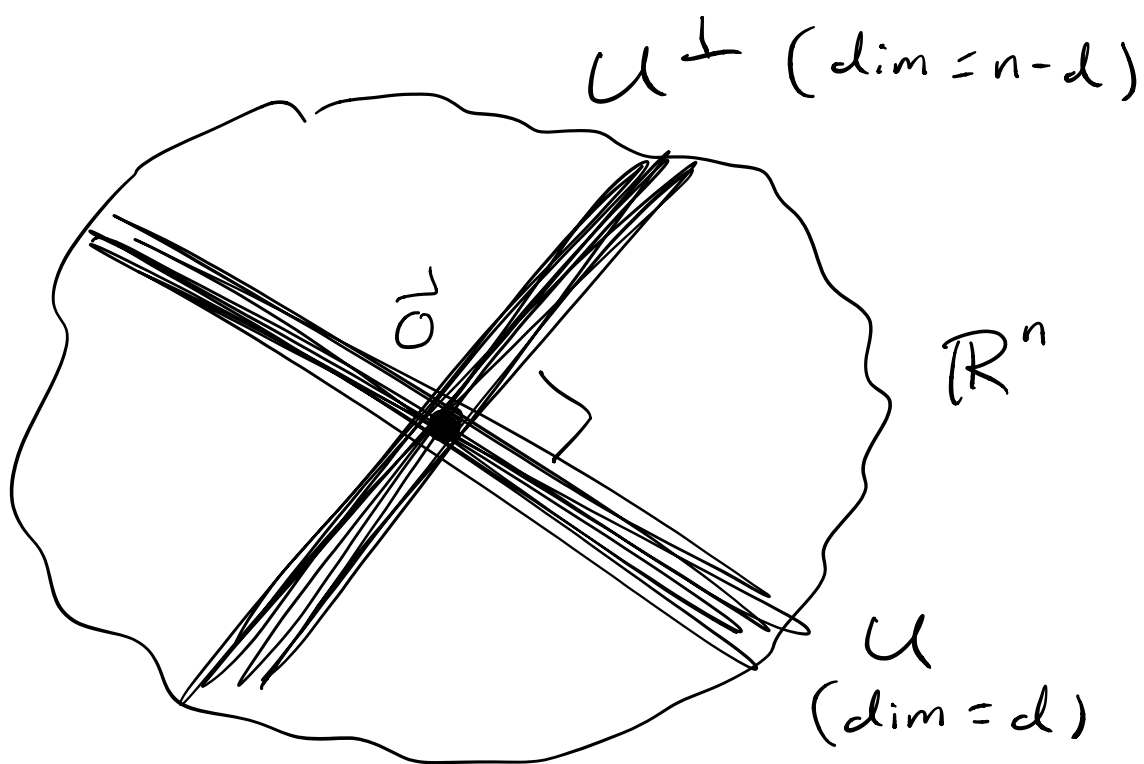
The only examples that can be visualized are in \mathbb{R}^2 , where orthogonal subspaces are pairs of perpendicular lines:



Or in \mathbb{R}^3 , where orthogonal subspaces are perpendicular (line, plane) pairs:



The general situation can only be hinted at with a diagram such as this:





Topics for Quiz 2 :

- Computing RREF of any matrix.
- Interpreting the RREF of a linear system :
 - $m = \# \text{ equations}$
 - $n = \# \text{ unknowns}$
 - $r = \# \text{ pivot variables in RREF}$
 - $d = \# \text{ free variables in RREF}$

Then

$$0 \leq r \leq m$$
$$r + d = n$$
$$n - m \leq d \leq n.$$

The solution set is either empty or it is a d -plane in \mathbb{R}^n .