

Orthogonality & Projections

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"Orthogonal" = "perpendicular"

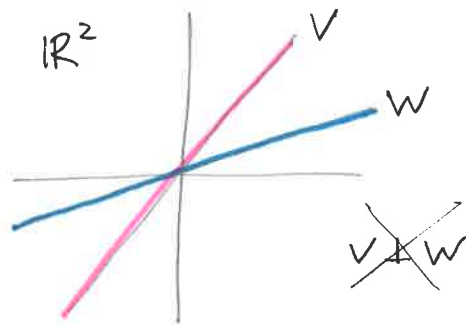
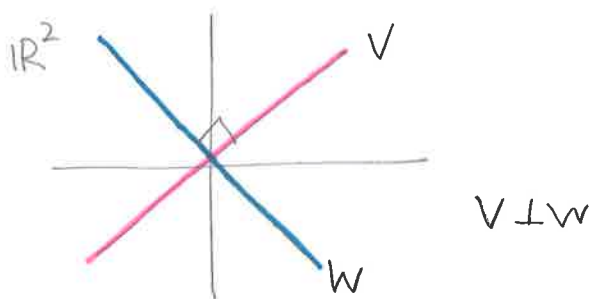
Two vectors \vec{v}, \vec{w} in \mathbb{R}^n are orthogonal if

$$\begin{matrix} \vec{v} \cdot \vec{w} = 0 & \Leftrightarrow & \vec{v}^T \vec{w} = 0 \\ n \times 1 & & 1 \times n \quad n \times 1 \end{matrix}$$

Two subspaces $V, W \subset \mathbb{R}^n$ are orthogonal if

$$\vec{v} \cdot \vec{w} = 0 \quad \text{for all } \vec{v} \text{ in } V, \vec{w} \text{ in } W$$

We also write $V \perp W$ when V, W are orthogonal.



Useful criterion:

If V has basis $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$ then $V \perp W \Leftrightarrow \vec{v}_i \cdot \vec{w}_j = 0$ for
 W has basis $\vec{w}_1, \vec{w}_2, \dots, \vec{w}_l$ $1 \leq i \leq k$
 $1 \leq j \leq l$

Given $V \subset \mathbb{R}^n$ define its orthogonal complement:

$$V^\perp = \left\{ \vec{w} \text{ in } \mathbb{R}^n \mid \vec{w} \perp \vec{v} \text{ for all } \vec{v} \text{ in } V \right\}$$

$V^\perp \subset \mathbb{R}^n$ is a subspace of \mathbb{R}^n

- Proof:
- has the zero vector since $\vec{0} \cdot \vec{v} = 0$ always
 - if \vec{w}_1, \vec{w}_2 are in V^\perp then $\vec{w}_1 \cdot \vec{v} = 0$ and $\vec{w}_2 \cdot \vec{v} = 0$ for all \vec{v} in V . Then $(\vec{w}_1 + \vec{w}_2) \cdot \vec{v} = \vec{w}_1 \cdot \vec{v} + \vec{w}_2 \cdot \vec{v} = 0$ for all \vec{v} in V , so we conclude $\vec{w}_1 + \vec{w}_2$ is in V^\perp . Therefore V^\perp is closed under $+$.
 - Closure under scalar multiplication is a similar arg.
- QED

$V, W \subset \mathbb{R}^n$ subspaces. If $V \perp W$ then $V \cap W = \{\vec{0}\}$.

- Proof: Suppose \vec{v} is in $V \cap W$, so \vec{v} is in V and W .
- $V \perp W$ means every vector in V is orthogonal to every vector in W .
- In particular, $\vec{v} \cdot \vec{v} = 0$.
- But $\vec{v} \cdot \vec{v} = \|\vec{v}\|^2 = 0$ so it must be that $\vec{v} = \vec{0}$.
- QED

Let A be an $m \times n$ matrix.

The row space of A , denoted $R(A) \subset \mathbb{R}^n$, is orthogonal to the null space $N(A) \subset \mathbb{R}^n$, i.e.

$R(A) \perp N(A)$.

Proof: Let $\vec{v}_1, \dots, \vec{v}_m$ be the rows of A

$$A = \begin{bmatrix} -\vec{v}_1 & - \\ \vdots & \\ -\vec{v}_m & - \end{bmatrix}$$

Let \vec{w} be in $N(A)$, i.e. $A\vec{w} = \vec{0}$. Then

$$\vec{0} = A\vec{w} = \begin{bmatrix} -\vec{v}_1 & - \\ \vdots & \\ -\vec{v}_m & - \end{bmatrix} \vec{w} = \begin{bmatrix} \vec{v}_1 \cdot \vec{w} \\ \vdots \\ \vec{v}_m \cdot \vec{w} \end{bmatrix}$$

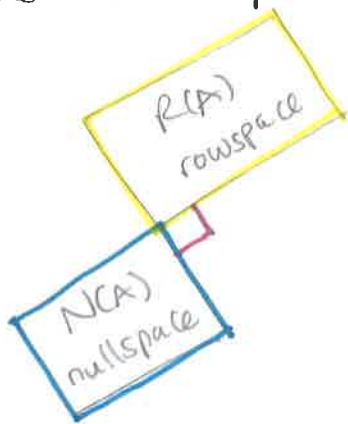
So $\vec{w} \perp \vec{v}_i$ for $i=1, \dots, m$.

\vec{w} was an arbitrary vector in $N(A)$

and the \vec{v}_i 's form a basis of $R(A)$

so we've shown $R(A) \perp N(A)$. QED

This last proposition explains the "right angle" on the cover of Strang's textbook:



$$R(A) + N(A) = \mathbb{R}^n$$

$$R(A) \perp N(A)$$

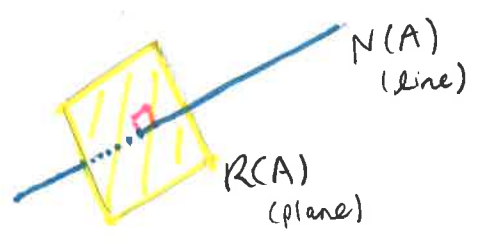
$$R(A) \cap N(A) = \{\vec{0}\}$$

Example $A = \begin{bmatrix} 2 & 1 & 1 \\ 1 & 1 & -1 \\ 1 & -1 & 5 \end{bmatrix} \xrightarrow{\text{elim.}} \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & -3 \\ 0 & 0 & 0 \end{bmatrix}$ RREF

row space $R(A) = \text{span} \left(\begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} \right)$ (note $A=A^T$ so row space = column space)

solving $A\vec{x} = \vec{0}$ gives $\vec{x} = t \begin{bmatrix} -2 \\ 3 \\ 1 \end{bmatrix}$ for any $t \in \mathbb{R}$

thus $N(A) = \text{span} \left(\begin{bmatrix} -2 \\ 3 \\ 1 \end{bmatrix} \right)$.



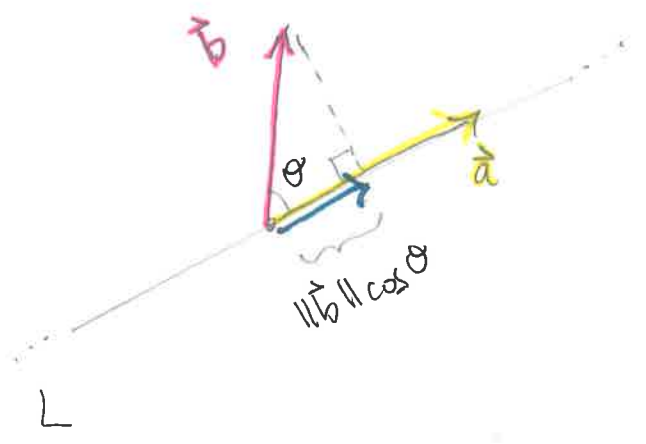
We check $\begin{bmatrix} -2 \\ 3 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} = 0$, $\begin{bmatrix} -2 \\ 3 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} = 0$ verifying $R(A) \perp N(A)$.

Projections

Let \vec{b} be any vector in \mathbb{R}^n

Suppose we're given a line $L = \text{span}(\vec{a})$, where $\vec{a} \neq \vec{0}$.

What is the projection of \vec{b} onto L ?



$$\|\vec{a}\| \|\vec{b}\| \cos \theta = \vec{a} \cdot \vec{b}$$

$$\|\vec{b}\| \cos \theta = \frac{\vec{a} \cdot \vec{b}}{\|\vec{a}\|} \quad (*)$$

The projected vector is

$$\begin{aligned}
 & \overset{\text{scalar}}{(\|\vec{b}\| \cos \theta)} \overset{\text{vector}}{(\text{unit vector in direction of } \vec{a})} \\
 &= (\|\vec{b}\| \cos \theta) \left(\frac{\vec{a}}{\|\vec{a}\|} \right) \\
 &= \left(\frac{\vec{a} \cdot \vec{b}}{\|\vec{a}\|^2} \right) \left(\frac{\vec{a}}{\|\vec{a}\|} \right) = \overset{\text{scalar}}{\left(\frac{\vec{a} \cdot \vec{b}}{\vec{a} \cdot \vec{a}} \right)} \overset{\text{vector}}{\vec{a}}
 \end{aligned}$$

Where we used (*) and also $\|\vec{a}\|^2 = \vec{a} \cdot \vec{a}$.

Define a matrix **P** as follows:

"The projection matrix associated to \vec{a} "

$$\boxed{P = \frac{\vec{a} \vec{a}^T}{\vec{a}^T \vec{a}}} = \left(\frac{1}{\vec{a} \cdot \vec{a}} \right) \vec{a} \vec{a}^T$$

scalar

Note $\vec{a} \vec{a}^T$ is an $n \times n$ matrix,
 $n \times 1 \quad 1 \times n$

$\vec{a}^T \vec{a} = \vec{a} \cdot \vec{a}$ is a scalar, so **P** is $n \times n$.
 $1 \times n \quad n \times 1$

For any \vec{b} in \mathbb{R}^n we compute:

$$P \vec{b} = \left(\frac{\vec{a} \vec{a}^T}{\vec{a}^T \vec{a}} \right) \vec{b} = \left(\frac{1}{\vec{a}^T \vec{a}} \right) \underset{\text{matrix}}{(\vec{a} \vec{a}^T)} \vec{b}$$

scalar

$$= \left(\frac{1}{\vec{a}^T \vec{a}} \right) \vec{a} (\vec{a}^T \vec{b}) = \left(\frac{\vec{a}^T \vec{b}}{\vec{a}^T \vec{a}} \right) \vec{a} = \text{projection of } \vec{b} \text{ onto } L = \text{span}(\vec{a}). \quad (6)$$

Can thus view P as a linear transformation:

$$P: \mathbb{R}^n \rightarrow \mathbb{R}^n$$

input
any vector
 \vec{b} in \mathbb{R}^n



output $P(\vec{b})$
is the projection
of \vec{b} onto $\text{span}(\vec{a})$

Note $P^2 = P$:

$$P^2 = PP = \left(\frac{\vec{a} \vec{a}^T}{\vec{a}^T \vec{a}} \right) \left(\frac{\vec{a} \vec{a}^T}{\vec{a}^T \vec{a}} \right) = \frac{\vec{a} (\cancel{\vec{a}^T \vec{a}}) \vec{a}^T}{(\cancel{\vec{a}^T \vec{a}}) (\vec{a}^T \vec{a})} = \frac{\vec{a} \vec{a}^T}{\vec{a}^T \vec{a}} = P$$

"Projecting twice gives the same answer."

Ex. Give the projection matrix P that projects onto the line $\text{span}\left(\begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}\right) \subset \mathbb{R}^3$. Use it to project $\vec{v} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ onto this line.

Here $\vec{a} = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}$. Compute $P = \frac{\vec{a} \vec{a}^T}{\vec{a}^T \vec{a}}$.

$$\vec{a}^T \vec{a} = \vec{a} \cdot \vec{a} = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} = 1^2 + 2^2 + (-1)^2 = 6.$$

$$\vec{a}\vec{a}^T = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} [1 \ 2 \ -1] = \begin{bmatrix} 1 & 2 & -1 \\ 2 & 4 & -2 \\ -1 & -2 & 1 \end{bmatrix}$$

Thus $P = \frac{\vec{a}\vec{a}^T}{\vec{a}^T\vec{a}} = \frac{1}{6} \begin{bmatrix} 1 & 2 & -1 \\ 2 & 4 & -2 \\ -1 & -2 & 1 \end{bmatrix}$.

Project \vec{v} onto $\text{span}(\vec{a})$:

$$P(\vec{v}) = \frac{1}{6} \begin{bmatrix} 1 & 2 & -1 \\ 2 & 4 & -2 \\ -1 & -2 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \frac{1}{6} \begin{bmatrix} 2 \\ 4 \\ -2 \end{bmatrix} = \begin{bmatrix} 1/3 \\ 2/3 \\ -1/3 \end{bmatrix}$$

Projection onto a subspace

Consider a subspace $V \subset \mathbb{R}^m$ with basis $\vec{a}_1, \dots, \vec{a}_n$.

In particular $V = \text{span}(\vec{a}_1, \dots, \vec{a}_n)$, $\dim V = n$.

Let $A = \begin{bmatrix} | & | & \dots & | \\ \vec{a}_1 & \vec{a}_2 & \dots & \vec{a}_n \\ | & | & \dots & | \end{bmatrix}$, so A is $m \times n$

Projection matrix:
(associated to basis
 $\vec{a}_1, \dots, \vec{a}_n$)

$$P = A(A^T A)^{-1} A^T$$

note P is $m \times m$:

$$\begin{matrix} A^T A \\ n \times m & m \times n \end{matrix} \rightarrow A^T A \text{ is } n \times n, \text{ so is } (A^T A)^{-1}$$

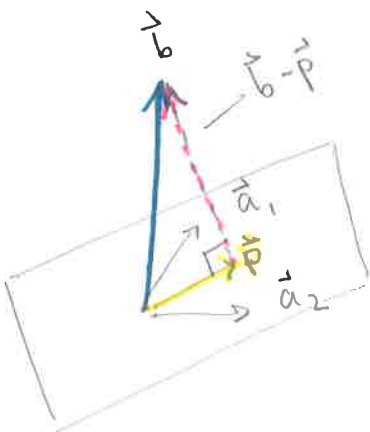
$$\text{then } P = \begin{matrix} A & (A^T A)^{-1} & A^T \\ m \times n & n \times n & n \times m \end{matrix} \text{ is } m \times m.$$

Why is $A^T A$ invertible?

Fact: $A^T A$ is invertible \Leftrightarrow columns of A are independent.

For us the columns of A are a basis, so all is well.

Claim: $P: \mathbb{R}^m \rightarrow \mathbb{R}^m$ is the linear transformation that takes any vector \vec{b} in \mathbb{R}^m and outputs the vector $P(\vec{b})$ which is the projection of \vec{b} onto V .



\vec{p} = proj. of \vec{b} onto V

$$\vec{p} = x_1 \vec{a}_1 + \dots + x_n \vec{a}_n = A \vec{x}$$

where $\vec{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$ to be determined.

V

From picture we see we should have $\vec{b} - \vec{p} \perp V$

(9)

$$\Leftrightarrow \vec{b} - \vec{p} \perp \vec{a}_i \quad \text{for } i=1, \dots, n$$

$$\Leftrightarrow (\vec{b} - \vec{p}) \cdot \vec{a}_i = 0 \quad \text{for } i=1, \dots, n$$

$$\Leftrightarrow \vec{a}_i^T (\vec{b} - \vec{p}) = 0 \quad \text{for } i=1, \dots, n$$

$$\Leftrightarrow \underbrace{\begin{bmatrix} -\vec{a}_1^T \\ \vdots \\ -\vec{a}_n^T \end{bmatrix}}_{A^T} [\vec{b} - A\vec{x}] = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$$

$$\Leftrightarrow A^T (\vec{b} - A\vec{x}) = \vec{0} \quad \Leftrightarrow A^T \vec{b} = A^T A \vec{x}$$

Multiply both sides by $(A^T A)^{-1}$ to get

$$(A^T A)^{-1} A^T \vec{b} = \vec{x}$$

so we obtain projected vector $\vec{p} = A\vec{x}$ is given by

$$A(A^T A)^{-1} A^T \vec{b} = P \vec{b},$$

as claimed!