

## Homework 5

In this homework you will explore the concepts of spanning, independence, and basis.

### Problems in Strang:

§3.4: # 1, 2, 8, 11, 16, 18, 20

### And the following problems:

A. Consider the following matrix, for a fixed real number  $\theta$ :

$$A_\theta = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

As discussed in lecture, this matrix acts on vectors by rotating them by angle  $\theta$  in the CCW direction. The fact that rotation is represented by a matrix has powerful consequences.

- (i) For two different angles  $\theta$  and  $\phi$ , compute the product matrix  $A_\phi A_\theta$ . Argue geometrically that  $A_\phi A_\theta$  should be the same matrix as  $A_{\theta+\phi}$ . Use this to derive formulas for  $\cos(\theta + \phi)$  and  $\sin(\theta + \phi)$ . Takeaway: linear algebra recovers trigonometric identities!
- (ii) Apply the same strategy to compute formulas for  $\cos(3\theta)$  and  $\sin(3\theta)$  for any given angle  $\theta$ . (You will multiply three matrices this time.)

B. Suppose  $A$  is an  $n \times n$  invertible matrix. Show that if  $\mathbf{v}_1, \dots, \mathbf{v}_n$  is a basis of  $\mathbb{R}^n$ , then the set of vectors  $A\mathbf{v}_1, \dots, A\mathbf{v}_n$  is also a basis of  $\mathbb{R}^n$ .

C. Let  $V$  be the vector space consisting of polynomials of degree at most  $n$ , which we considered in class. Show that the set of polynomials  $1, x, x^2, \dots, x^n$  is a basis of  $V$ .