

Today : Projective Tangent Spaces.  
This will finish the story of Taylor series, from the 19th century point of view.



Given line  $L$  & hypersurface  $V_F$  in  $\mathbb{F}P^n$  we have defined the intersection multiplicity  $[L \cdot V_F]_p \in \mathbb{N}$  and shown it is invariant under:

- automorphisms of  $\mathbb{F}P^n$
- automorphisms of  $L \approx \mathbb{F}P^1$

We say  $L$  &  $V_F$  are tangent if

$$[L \cdot V_F]_p \geq 2.$$

We will use this define/compute the projective tangent space.

To do this, let  $F(\vec{x}) \in \mathbb{F}[x_1, \dots, x_{n+1}]$  be homogeneous & parametrize the line as  $L: \vec{p} + t\vec{q}$  for distinct  $\vec{p}, \vec{q} \in \mathbb{F}\mathbb{P}^n$ .

For a specific representation

$$\vec{p} = (p_1, p_2, \dots, p_{n+1})$$

we compute the Taylor expansion of  $F$  near  $\vec{x} = \vec{p}$ :

$$F(\vec{x}) = F(\vec{p}) + (\nabla F)_{\vec{p}}(\vec{x} - \vec{p}) + \frac{1}{2}(\vec{x} - \vec{p})^T (H F)_{\vec{p}}(\vec{x} - \vec{p}) + \dots$$

Choose specific representation

$$\vec{q} = (q_1, \dots, q_{n+1})$$

and substitute  $L: \vec{p} + t\vec{q}$  into  $F$ :

$$\Phi(t) := F(\vec{p} + t\vec{q})$$

$$= F(\vec{p}) + t(\nabla F)_{\vec{p}}\vec{q} + \frac{t^2}{2}\vec{q}^T (H F)_{\vec{p}}\vec{q} + \dots$$

By definition,  $[L \cdot V_F]_{\vec{p}}$  is the multiplicity

of  $t=0$  as a root of  $\Phi(t)$ . So

$L$  &  $V_F$  are tangent iff

- $F(\vec{p}) = 0$

- $(\nabla F)_{\vec{p}} \vec{q} = 0$ .

If  $(\nabla F)_{\vec{p}} \neq \vec{0}$ , the second equation defines a projective hyperplane

$$T_{\vec{p}} V_F = H_{(\nabla F)_{\vec{p}}} \text{ called the projective}$$

tangent space to  $V_F$  at  $\vec{p}$ .

If  $(\nabla F)_{\vec{p}} = \vec{0}$  then every line through  $\vec{p}$  is tangent to  $V_F$ , so we define

$$T_{\vec{p}} V_F = \mathbb{F}P^n.$$

We say  $\vec{p} \in V_F$  is smooth (regular)

when  $\dim T_{\vec{p}} V_F = n-1$  and singular

when  $\dim T_{\vec{p}} V_F = n$ , as projective subspaces.

Next, want to understand affine vs. projective tangent spaces. The key fact connecting them is

Euler's Homogeneous Function Theorem:

Let  $F(\vec{x}) \in \mathbb{F}[x_1, \dots, x_{n+1}]$  over field  $\mathbb{F}$  and consider 3 conditions:

$$(H1) \quad F(\vec{x}) = F^{(d)}(\vec{x})$$

$$(H2) \quad F \neq 0 \text{ \& } F(\lambda \vec{x}) = \lambda^d F(\vec{x}) \quad \forall \lambda \neq 0.$$

$$(H3) \quad d \cdot F(\vec{x}) = (\nabla F)_{\vec{x}} \cdot \vec{x}$$

$$= x_1 F_{x_1}(\vec{x}) + \dots + x_{n+1} F_{x_{n+1}}(\vec{x}),$$

Then  $(H1) \Rightarrow (H2)$  &  $(H1) \Rightarrow (H3)$  always.

$(H2) \Rightarrow (H1)$  if  $\mathbb{F}$  infinite

$(H3) \Rightarrow (H1)$  if  $\text{char}(\mathbb{F}) = 0$ . ///

We already discussed  $H1$  &  $H2$ .

Proof:  $(H1) \Rightarrow (H3)$ :

Assume  $F(\vec{x}) = \bar{F}^{(d)}(\vec{x}) = \sum a_I \vec{x}^I$

where each  $I = (i_1, \dots, i_{n+1})$  satisfies

$$\sum I = i_1 + \dots + i_{n+1} = d. \text{ Note that for}$$

each  $x_k$  and each monomial  $\vec{x}^I$  we

have  $x_k D_{x_k} \vec{x}^I = i_k \vec{x}^I$ , hence

$$(\nabla F)_{\vec{x}} \vec{x} = \sum x_k D_{x_k} F$$

$$= \sum_I a_I \sum_k x_k D_{x_k} \vec{x}^I$$

$$= \sum_I a_I \sum_k i_k \vec{x}^I$$

$$= \sum_I a_I \left( \frac{i_1 + \dots + i_{n+1}}{d} \right) \vec{x}^I$$

$$= d \sum_I a_I \vec{x}^I$$

$$= d \cdot \bar{F}(\vec{x}).$$

(H3)  $\Leftrightarrow$  (H1): Assume  $d \cdot \bar{F} = (\nabla F)_{\vec{x}} \vec{x}$ .

Assume  $\text{char}(\mathbb{F}) = 0$ .

Let  $F(\vec{x}) = \sum F^{(k)}(\vec{x})$  be

homogeneous filtration.

Since  $(\nabla F)_{\vec{x}} \vec{x}$  is linear in  $F$  we have

$$\begin{aligned} dF &= (\nabla F)_{\vec{x}} \vec{x} \\ &= \sum_k (\nabla F^{(k)})_{\vec{x}} \vec{x} \\ &= \sum_k k \cdot F^{(k)} \quad \text{since } (H1) \Rightarrow (H3). \end{aligned}$$

Now let  $y$  be another variable and substitute  $\vec{x} \mapsto y\vec{x}$ . Then since  $(H1) \Rightarrow (H2)$  we have

$$\begin{aligned} d \cdot F(y\vec{x}) &= \sum k \cdot F^{(k)}(y\vec{x}) \\ d \sum_k F^{(k)}(y\vec{x}) &= \sum k \cdot F^{(k)}(y\vec{x}) \\ \sum_k d y^k F^{(k)}(\vec{x}) &= \sum k y^k F^{(k)}(\vec{x}) \end{aligned}$$

This is an identity of polynomials in the ring  $\mathbb{F}[\vec{x}^1](y)$ , hence the coefficient of  $y^k$  on each side is the same:

$$\begin{aligned} d F^{(k)}(\vec{x}) &= k F^{(k)}(\vec{x}) \\ (d - k) F^{(k)}(\vec{x}) &= 0. \end{aligned}$$

Since  $\text{char}(F) = 0$  then  $d \neq k$  in  $\mathbb{Z}$  implies  $d - k \neq 0$  in  $F$ , hence

$$F^{(k)}(\vec{x}) = 0.$$

We conclude that  $F(\vec{x}) = F^{(d)}(\vec{x})$ . ✓



We use this lemma to relate affine & projective tangent spaces.

Theorem: Let  $\vec{p} \in V_F \subseteq \mathbb{F}P^n$  be a point on a projective hypersurface, let  $T_{\vec{p}}V_F$  be projective tangent space.

If  $\vec{p} \notin H_i$ , let  $f$  be its de-homog.

of  $F$ . Then I claim that affine tangent space  $T_{\vec{p}}V_f \subseteq U_i \subseteq \mathbb{F}P^n$  is the de-homog. of  $T_{\vec{p}}V_F$  in  $U_i$ .

Conversely, if  $V_F$  does not contain  $H_i$  (i.e. if  $x_i \notin F$ ) then  $T_{\vec{p}}V_F$  is the

its homogenization of  $T_{\vec{p}} V_f$ .

Geometric Meaning: The tangent space at a point is determined by any local neighborhood.

Proof: The proj. tangent space is defined by equation

$$(\nabla F)_{\vec{p}} \vec{x} = 0 \quad (*)$$

$$x_1 F_{x_1}(\vec{p}) + \dots + x_{n+1} F_{x_{n+1}}(\vec{p}) = 0$$

Let  $\vec{p} = (p_1, \dots, p_{i-1}, 1, p_{i+1}, \dots, p_{n+1}) \in U_i$ .

If  $k \neq i$  we observe that  $D_{x_k}$  commutes with substituting  $x_i = 1$ .

The affine tangent space  $T_p V_f \subseteq U_i$  is defined by equation

$$f_{x_1}(\vec{p})(x_1 - p_1) + \dots + f_{x_{i-1}}(\vec{p})(x_{i-1} - p_{i-1}) \\ + f_{x_{i+1}}(\vec{p})(x_{i+1} - p_{i+1}) + \dots + f_{x_{n+1}}(\vec{p})(x_{n+1} - p_{n+1}) = 0.$$

Now homogenize in the  $i$ th place:



$$F_{x_1}(\vec{p})(x_1 - p_1 x_i) + \dots + F_{x_{i-1}}(\vec{p})(x_{i-1} - p_{i-1} x_i) \quad (**)$$

$$+ F_{x_{i+1}}(\vec{p})(x_{i+1} - p_{i+1} x_i) + \dots + F_{x_{n+1}}(\vec{p})(x_{n+1} - p_{n+1} x_i) = 0$$

Is this the same as (\*) ?

Yes because of Euler's formula:

$$d \cdot F(\vec{p}) = (\nabla F)_{\vec{p}} \vec{p}$$

$$0 = p_1 F_{x_1}(\vec{p}) + \dots + p_{i-1} F_{x_{i-1}}(\vec{p})$$

$$1 F_{x_i}(\vec{p}) + p_{i+1} F_{x_{i+1}}(\vec{p}) + \dots + p_{n+1} F_{x_{n+1}}(\vec{p}).$$

$$\Rightarrow F_{x_i}(\vec{p}) = -p_1 F_{x_1}(\vec{p}) - \dots - p_{n+1} F_{x_{n+1}}(\vec{p}).$$

Substitute into (\*\*) to get (\*).



Next time : Abstract Algebra !