

Tues Oct 30.

Some business:

HW 1 due next week.

Class maybe cancelled Thurs.

Sign up for second semester please.

Today: "Affine" geometry.

Let  $\mathbb{F}$  be a field and consider

$A \in \text{Mat}_n(\mathbb{F})$  and  $b \in \mathbb{F}^n$ . We know that

$$V = \left\{ x \in \mathbb{F}^n : Ax = 0 \right\}$$

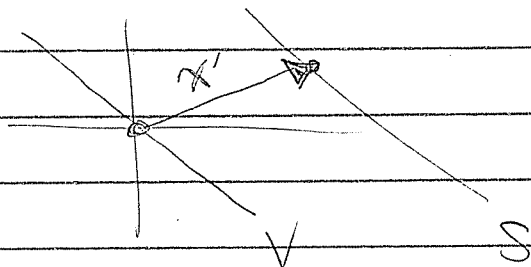
is a vector space over  $\mathbb{F}$ .

Q: What is

$$S = \left\{ x \in \mathbb{F}^n : Ax = b \right\} ?$$

Answer 1:

$S$  is a coset of  $V$  inside  $\mathbb{F}^n$ .  
(as abelian groups)



Given any one particular solution  
(coset representative)  $Ax' = b$ , we have

$$S = V + x'$$

Answer 2: For any two  $x, y \in S$  we have

$$A(x-y) = Ax - Ay = b - b = 0$$

$$\Rightarrow x-y \in V$$

Think:  $V$  is the space of "directions"  
in  $S$ .  $S$  is like a vector space but  
it doesn't have a distinguished origin.

Say  $S$  is an "affine space" associated  
to  $V$  (we forget the origin)

Axiomatically: Let  $V$  be a vector  
space. An affine space is a set  $S$   
with a function  $\Theta: S \times S \rightarrow V$  such that

①  $\forall x \in S$ ,  $\Theta(x, \cdot): S \rightarrow V$  is surjective

②  $\forall x, y \in S$ ,  $\Theta(x, y) = 0 \Rightarrow x = y$ .

③  $\forall x, y, z \in S$  we have

$$\Theta(x, y) + \Theta(y, z) = \Theta(x, z)$$

Think:  $\theta(x, y) = \overrightarrow{xy} = \text{"}x - y\text{"}$   
a "displacement vector"

Note: Actually  $\theta(x, \circ) : S \rightarrow V$  is a  
bijection since if  $\theta(x, y) = \theta(x, z)$  then

$$\theta(x, y) + \theta(y, z) = \theta(x, z) = \theta(x, y)$$

$$\implies \theta(y, z) = 0 \implies y = z \quad \square$$

Thus any point  $x \in S$  defines an  
isomorphism

$$\theta(x, \circ) : S \xrightarrow{\sim} V$$

called "choosing an origin".

The choice is not canonical, and  
that's the whole point.

Commonly we just write

$$S = \mathbb{A}V \quad \text{"affine } V\text{"}$$

$$S = \mathbb{A}\mathbb{F}^n \quad \text{in coordinates.}$$



If  $K \trianglelefteq G$  (normal) then  $H \curvearrowright K$  by conjugation  $\forall h \in H, k \in K \quad k \mapsto h^{-1}kh \in K$ .  
Group product on  $G$  is

$$(h_1, k_1)(h_2, k_2) = \underbrace{h_1 h_2}_{\in H} \underbrace{(h_2^{-1} k_1 h_2)}_{\in K} k_2$$

Notation:  $G = H \ltimes K$   
"semi-direct product"

Abstractly: Given groups  $H, K$  and group hom  $\varphi: H \rightarrow \text{Aut}(K)$   
 $h \mapsto \varphi_h: K \rightarrow K$

we can define

$$H \ltimes_{\varphi} K := \left\{ (h, k) : h \in H, k \in K \right\}$$

with group structure

$$(h_1, k_1) * (h_2, k_2) := (h_1 h_2, \varphi_{h_2}(k_1) k_2)$$

Note: If  $\varphi: H \rightarrow \text{Aut}(K)$  is trivial  
i.e.  $\varphi_h(k) = k \quad \forall h, k$ . we say

$$H \ltimes_{\varphi} K = H \times K$$

"direct product"

Q: But groups = geometry. What does  $X$  mean geometrically?

A: "Torsors"

Suppose group  $G$  acts on set  $S$  preserving some structure.

★ Easy but important Lemma:  
For all  $g \in G$ ,  $x \in S$  we have

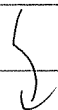
$$G_{g(x)} = g G_x g^{-1} \leq G$$

Proof: Given  $ghg^{-1}$  with  $h(x) = x$ , have

$$\begin{aligned} ghg^{-1}(g(x)) &= gh((g^{-1}g)(x)) \\ &= gh(x) \\ &= g(h(x)) \\ &= g(x) \implies ghg^{-1} \in G_{g(x)} \end{aligned}$$

We have shown  $g G_x g^{-1} \leq G_{g(x)}$ .

Now let  $x' = g(x)$ , so  $x = g^{-1}(x')$ .



Some argument shows

$$(g^{-1}) G_x (g^{-1})^{-1} \leq G_{g^{-1}(x)}$$

$$g^{-1} G_{g(x)} g \leq G_x$$

$$G_{g(x)} \leq g G_x g^{-1}$$



"Points in the same  $G$ -orbit have conjugate  $G$ -stabilizers"

IF  $G$  acts "transitively" (i.e.  $\forall x_1, x_2 \in S$   
 $\exists g \in G$  with  $g(x_1) = x_2$ ) then for  
any  $x \in S$  we get

$$S \longleftrightarrow G/G_x$$

We say  $G$  acts "freely" if  $G_x = 1$   
 $\forall x \in S$  (i.e.  $g(x) = h(x) \Rightarrow (g^{-1}h)(x) = x$   
 $\Rightarrow g^{-1}h \in G_x \Rightarrow g^{-1}h = 1 \Rightarrow g = h$ ).

Free + Transitive = Regular  
(or "simply transitive")

If  $G \curvearrowright S$  regularly then  $\forall x \in S$  we have

$$\begin{aligned} S &\longleftrightarrow G/G_x \longleftrightarrow G \\ g(x) &\longleftrightarrow gG_x \longleftrightarrow g. \end{aligned}$$

Then we can think of  $S$  as a group ( $\cong G$ ) with identity element  $x$ .

But this is NOT CANONICAL!

It depends on the choice  $x \in S$ .

However, given any  $x_1, x_2 \in S$   $\exists$  unique  $g \in G$  with  $g(x_1) = x_2$

Think:  $g = "x_2/x_1"$

and this is canonical.

We get a map  $\theta: S \times S \rightarrow G$

where  $\theta(x_1, x_2) = "x_2/x_1"$

= the unique  $g$  with  $g(x_1) = x_2$

Observe  $\theta(x, y) = 1 \implies 1(x) = y \implies x = y$ .

And  $\theta(y, z) \theta(x, y) = \theta(x, z)$  since

$g(x) = y$  and  $h(y) = z$

$\implies (hg)(x) = h(g(x)) = h(y) = z$  //



Any choice of basepoint  $x_0 \in S$   
identifies  $S$  with  $G$

$$\begin{array}{ccc} S & \xleftrightarrow{x_0} & G \\ x & \xleftrightarrow{\quad} & \theta(x_0, x) \end{array}$$

Q: Is  $S$  a group?

A: NO. It's a "G-torsor"

(simple example of a principle  
G-bundle from gauge theory)

Axiomatically: Given group  $G$ , a  
G-torsor is a set  $S$  and a  
map  $\theta : S \times S \rightarrow G$  such that  
 $\forall x, y, z \in S$ ,

(T1)  $\theta(x, \bullet) : S \rightarrow G$  is surjective

(T2)  $\theta(x, y) = 1 \Rightarrow x = y$ .

(T3)  $\theta(y, z) \theta(x, y) = \theta(x, z)$

T1 + T2 + T3 also imply

(T4)  $\theta(x, \bullet) : S \rightarrow G$  is a bijection.

Note:  $\theta$  is equivalent to a regular group action  $G \curvearrowright S$ .

Examples:

- Energy is an  $\mathbb{R}$ -torsor.

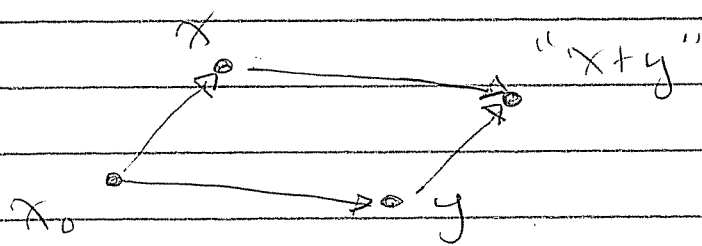
We can measure energy difference as a real number, but it makes no sense to discuss THE energy of a system.

- Voltage

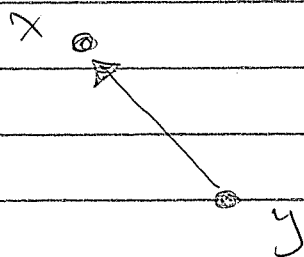
- Indefinite integral

- 3D space is an  $\mathbb{R}^3$ -torsor

[ you can only "add points" once you choose an arbitrary basepoint  $x_0$



However, you can always "subtract"



" $x-y$ " exists, but it's not a point

-  $G$  itself is a  $G$ -torsor with left regular action  $g(h) := gh$ .  
I'll call this torsor

$\mathbb{A}G = \text{"affine } G\text{"}$

$\uparrow$   
my notation

So what? Here's the point:

$$\text{Aut}(\mathbb{A}G) \supseteq \text{Aut}(G)$$

In fact we have

$$\text{Aut}(\mathbb{A}G) \cong \text{Aut}(G) \rtimes G$$

$\nearrow$   
automorphisms  
that fix the  
basepoint.

$\uparrow$   
change the  
basepoint

Proof: Given  $g \in G$  define the translation map  $\tau_g: AG \rightarrow AG$ .

(1) Fix basepoint  $x_0 \in G$

(2) Define

$$\begin{array}{ccc} AG & \xleftrightarrow{x_0} & G \ni x \\ \tau_g \downarrow & & \downarrow \quad \downarrow \\ AG & \xleftrightarrow{x_0} & G \ni gx \end{array}$$

(3) Check that  $\tau_g: AG \rightarrow AG$  is independent of the choice  $x_0 \in G$  (omitted).

Note that  $\tau: G \rightarrow \text{Isom}(AG)$

$$g \mapsto \tau_g$$

is an injective group hom:

$$\begin{aligned} \text{(1)} \quad \tau_g \circ \tau_h(x) &= g(hx) \\ &= (gh)x = \tau_{gh}(x). \end{aligned}$$

(2) If  $gx = hx \quad \forall x \in G$ .

$$\text{Then } x=1 \implies g=h \quad \checkmark$$

Abuse notation and say

$$G \leq \text{Isom}(AG).$$

"translations"

Note  $\tau_g \notin \text{Aut}(G)$  if  $g \neq 1$  since  
 $g(1) = g \neq 1$ .

Given any  $x_0 \in G$ , get a subgroup

$$\text{Aut}_{x_0}(AG) \leq \text{Aut}(AG)$$

" $\varphi(x_0) = x_0$ "

Note  $\text{Aut}_{x_0}(AG) \cong \text{Aut}(G)$  via  $\theta(x_0, \circ)$

Might as well say  $x_0 = 1$ .

Have:  $G \leq \text{Aut}(AG)$

$$\text{Aut}(G) \leq \text{Aut}(AG)$$

with  $G \cap \text{Aut}(G) = \{id\}$

Now let  $\varphi \in \text{Aut}(AG)$  and define

$g := \varphi(1)$ . Then we have

$$\tau_{g^{-1}} \circ \varphi(1) = \tau_{g^{-1}}(g) = g^{-1}g = 1.$$

Hence  $\mu := \tau_{g^{-1}} \circ \varphi \in \text{Aut}(G)$ .

$$\Rightarrow \varphi = \tau_g \circ \mu$$

$$\Rightarrow \text{Aut}(AG) = G \text{Aut}(G)$$

Finally note

$$\begin{aligned} \mu \circ \tau_g(x) &= \mu(gx) \\ &= \mu(g)\mu(x) \\ &= \tau_{\mu(g)}(\mu(x)) \\ &= \tau_{\mu(g)} \circ \mu(x). \end{aligned}$$

$$\Rightarrow \mu \circ \tau_g = \tau_{\mu(g)} \circ \mu.$$

OR  $\boxed{\mu \circ \tau_g \circ \mu^{-1} = \tau_{\mu(g)}}$

We conclude that  $G \cong \text{Aut}(AG)$ , hence

$$\text{Aut}(AG) = G \rtimes \text{Aut}(G)$$

↖  
natural action



This is the geometric meaning of  $\rtimes$ .