

Example: Find all left & right inverses for matrix

$$A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \end{pmatrix}.$$

Right inverse

$$AB = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$A(\vec{b}_1, \vec{b}_2) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$(A\vec{b}_1 \mid A\vec{b}_2) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\begin{cases} A\vec{b}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \\ A\vec{b}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}. \end{cases}$$

$$A\vec{b}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \rightsquigarrow \vec{b}_1 = \begin{pmatrix} 2+s \\ -1-2s \\ s \end{pmatrix}$$

$$A\vec{b}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \rightsquigarrow \vec{b}_2 = \begin{pmatrix} -1+t \\ 1-2t \\ t \end{pmatrix}.$$

Two-dimensional family of right inv:

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \end{pmatrix} \begin{pmatrix} 2+s & -1+t \\ -1-2s & 1-2t \\ s & t \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

For any s, t .

Not a subspace of $\mathbb{R}^{3 \times 2}$
 • doesn't contain $\begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}$.

Left inverses?

$$CA = I$$

$$\begin{pmatrix} \cdot & \cdot \\ \cdot & \cdot \\ \cdot & \cdot \end{pmatrix} \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

This is not possible.

Proof: We have at least two right inverses, $B \neq B'$.

If A had a left inverse C
 then

$$I_2 = I_2$$

$$AB = AB'$$

$$C(AB) = C(AB')$$

$$(CA)B = (CA)B'$$

$$I_3 B = I_3 B'$$

$$B = B' \quad \times$$



Goal: Study two-sided
inverses:

$$AB = I \quad \& \quad BA = I$$

When does B exist?

How to find it?



Need to discuss subspaces
associated to linear transformations
& matrices.

consider a linear trans

$$T: V \rightarrow W$$

Call this an isomorphism of vector spaces when it is

- o injective (one-to-one)
- o surjective (onto)

If we can find an isomorphism $V \rightarrow W$ then we write

$$V \cong W$$

isomorphic
as vector spaces.

Key fact:

$$V \cong W \implies \dim V = \dim W$$

Proof: let $T: V \rightarrow W$ be an isomorphism.

let $\vec{b}_1, \dots, \vec{b}_n \in V$ be a basis.

Claim: $T(\vec{b}_1), \dots, T(\vec{b}_n) \in W$
is a basis of W .

What do we need?

• Spanning set.

Given $\vec{w} \in W$ need

$$\vec{w} = ? T(\vec{b}_1) + \dots + ? T(\vec{b}_n).$$

Well, T is onto we can

find some $\vec{v} \in V$ such that $\vec{w} = T(\vec{v})$.

Since $\vec{b}_1, \dots, \vec{b}_n$ spans V have

$$\vec{v} = a_1 \vec{b}_1 + \dots + a_n \vec{b}_n$$

$$\vec{w} = T(\vec{v}) = \underbrace{(a_1)}_{\checkmark} T(\vec{b}_1) + \dots + \underbrace{(a_n)}_{\checkmark} T(\vec{b}_n)$$

• Independent?

$$a_1 T(\vec{b}_1) + \dots + a_n T(\vec{b}_n) = \vec{0}.$$

Need to show $a_1 = a_2 = \dots = a_n = 0$.

[T one-to-one equivalent to

$$T(\vec{v}) = \vec{0} \Leftrightarrow \vec{v} = \vec{0}.$$

Proof: T one-to-one then

$$T(\vec{v}) = \vec{0}$$

$$\Rightarrow T(\vec{v}) = T(\vec{0})$$

$$\Rightarrow \vec{v} = \vec{0}.$$

one-to-one.

Conversely, if

$$T(\vec{v}) = \vec{0} \Rightarrow \vec{v} = \vec{0}.$$

Then

$$T(\vec{v}_1) = T(\vec{v}_2)$$

$$T(\vec{v}_1) - T(\vec{v}_2) = \vec{0}$$

$$T(\vec{v}_1 - \vec{v}_2) = \vec{0}$$

$$\vec{v}_1 - \vec{v}_2 = \vec{0}$$

$$\vec{v}_1 = \vec{v}_2 \quad \checkmark$$

]

$$\vec{0} = a_1 T(\vec{b}_1) + \dots + a_n T(\vec{b}_n)$$

$$\vec{0} = T(a_1 \vec{b}_1 + \dots + a_n \vec{b}_n)$$

$$\vec{0} = a_1 \vec{b}_1 + \dots + a_n \vec{b}_n$$

one-to-one.

$$\Rightarrow a_1 = a_2 = \dots = a_n = 0$$

because $\vec{b}_1, \dots, \vec{b}_n$ are independent. ✓

Conclusion:

$$V \cong W \Rightarrow \dim V = \dim W.$$



The Fundamental Theorem:

Given matrix A ,

$$\dim R(A) = \dim C(A).$$

Strategy:

① Show for any invertible matrices E & F that

$$\dim R(A) = \dim R(EAF).$$

$$\dim C(A) = \dim C(EAF).$$

② Find E & F to put A in a simple form:

$$EAF = \underbrace{r}_{\left\{ \begin{array}{c|c} \begin{matrix} 1 & & & \\ & \ddots & & \\ & & 1 & \\ \hline 0 & & & 0 \end{matrix} & \begin{matrix} 0 \\ 0 \end{matrix} \end{array} \right. \right)$$

Then $\dim C(EAF) = r$ ✓ ☺
 $\dim R(EAF) = r$

Proof of ①: For inv. E & F

We will show:

$$R(EA) = R(A)$$

$$R(AF) \cong R(A)$$

not equal but isom.

Idea: Let $\vec{a}_1^T \dots \vec{a}_m^T$ be the rows of A .

$$A = \begin{pmatrix} - & \vec{a}_1^T & - \\ \vdots & & \vdots \\ - & \vec{a}_m^T & - \end{pmatrix}$$

Write $E = \begin{pmatrix} e_{i1} & \dots & e_{im} \\ \vdots & & \vdots \\ e_{m1} & \dots & e_{mm} \end{pmatrix}$

i th row $EA = (\textit{i}th \textit{ row } E) A$

$$= (e_{i1} \dots e_{im}) \begin{pmatrix} - \vec{a}_1^T - \\ \vdots \\ - \vec{a}_m^T - \end{pmatrix}$$

$$= e_{i1} \vec{a}_1^T + \dots + e_{im} \vec{a}_m^T.$$

(lin. comb. of rows of A .)

Each row of EA is in $R(A)$.

Hence $R(EA) \subseteq R(A)$.

[Technically :

$$R(B) = \text{span} \{ \text{rows of } B \}.$$

We showed every lin comb of rows of EA is also a lin

comb of row of A :

$$R(EA) \subseteq R(A) \quad]$$

Now (trick) since E^{-1} is
invertible ($(E^{-1})^{-1} = E$) have

$$R(E^{-1}B) \subseteq R(B) \quad \text{any } B.$$

$$R(E^{-1}EA) \subseteq R(EA)$$

$$R(A) \subseteq R(EA).$$

Hence $R(A) = R(EA)$ ✓

Next : $R(AF) \cong R(A)$

Rows of AF ?

$$\text{ith row } AF = (\text{ith row } A) F \\ \vec{a}_i^T F$$

$$R(A) = \text{span} \{ \vec{a}_1^T, \dots, \vec{a}_m^T \}$$

$$R(AF) = \text{span} \{ \vec{a}_1^T F, \dots, \vec{a}_m^T F \}$$

Define an isomorphism

$$T: R(A) \longrightarrow R(AF)$$
$$\vec{v}^T \longmapsto \vec{v}^T F$$

$$T(a_1 \vec{a}_1^T + \dots + a_n \vec{a}_n^T)$$
$$= a_1 T(\vec{a}_1^T) + \dots + a_n T(\vec{a}_n^T)$$
$$= a_1 (\vec{a}_1^T F) + \dots + a_n (\vec{a}_n^T F)$$
$$\in R(AF)$$

Linear: $(a \vec{v}^T + b \vec{w}^T) F$

$$= a \vec{v}^T F + b \vec{w}^T F$$

Invertible with inverse

$$\vec{w}^T \longmapsto \vec{w}^T F^{-1}$$

[Recall: $T: V \rightarrow W$ called isom

- linear
- injective } bijective
- surjective }

]

Conclusion:

$$\dim R(A) = \dim R(A\bar{F}).$$

Similar proof shows

$$C(EA) \cong C(A)$$

$$C(A\bar{F}) = C(A).$$

(2) Learn how to perform row & column operations via matrix multiplication.