

HW 4 Discussion:

Problem 1: $k > n \Rightarrow \dim A^k(\mathbb{R}^n) = 0$.

(a) A has repeated column.

Say $A' = A$ where A' obtained from A by switching 2 columns.
Then from def. of "alternating"

$$\varphi(A') = -\varphi(A).$$

$$\text{O.T.O.H, } A' = A \Rightarrow \varphi(A') = \varphi(A).$$

$$\text{So } \varphi(A) = -\varphi(A)$$

$$2\varphi(A) = 0$$

$$\varphi(A) = 0.$$

(b) A has dependent cols.

$$\text{e.g. } A = \left(\vec{a}_1 \mid \vec{a}_2 \mid \lambda \vec{a}_1 + \mu \vec{a}_2 \right).$$

By "multilinearity":

$$\begin{aligned} \varphi(A) &= \lambda \cdot \varphi(\vec{a}_1 \mid \vec{a}_2 \mid \vec{a}_1) + \mu \cdot \varphi(\vec{a}_1 \mid \vec{a}_2 \mid \vec{a}_2) \\ &= 0 + 0 = 0. \end{aligned}$$

(c) Let $k > n$, $\varphi \in A^k(\mathbb{R}^n)$.

Any set of k vectors in \mathbb{R}^n
must be dependent. So, for

any $\vec{a}_1, \dots, \vec{a}_k \in \mathbb{R}^n$ have

$$\varphi(\vec{a}_1, \dots, \vec{a}_k) = 0.$$

In other words $\varphi = 0$, i.e.,
the zero function $(\mathbb{R}^n)^k \rightarrow \mathbb{R}$.

Remark: For $0 \leq k \leq n$ I mentioned
that $\dim A^k(\mathbb{R}^n) = \binom{n}{k}$.

[Convention $A^0 = \mathbb{R}$, $A^1 = \mathbb{R}^n$,
so $\dim A^0 = 1 = \binom{n}{0}$
 $\dim A^1 = n = \binom{n}{1} \checkmark$]

Proved in class

$$A^n(\mathbb{R}^n) = \text{span} \{ \det \}.$$

More generally, given $n \times k$ matrix
($0 \leq k \leq n$) and subset $I \subseteq \{1, \dots, n\}$,
define the function $\det_I : A^k(\mathbb{R}^n)$

by $\det_I(A) =$ determinant of
 $k \times k$ submatrix of A
consisting of rows I .

e.g. $\det_{\{2,3\}} \begin{pmatrix} 1 & -1 \\ \boxed{1} & \boxed{2} \\ \boxed{2} & \boxed{3} \end{pmatrix} = 1 \cdot 3 - 2 \cdot 2 = -1.$

Theorem: For any $0 \leq k \leq n$,
the functions \det_I with $I \subseteq \{1, \dots, n\}$
of size k are a basis for $A^k(\mathbb{R}^n)$.

Hence

$$\begin{aligned} \dim A^k(\mathbb{R}^n) &= \# \text{ subsets of } \{1, \dots, n\} \\ &\quad \text{of size } k \\ &= \binom{n}{k}. \end{aligned}$$



Problem 2: Volume.

e.g. $k=3$. Consider $\vec{a}_1, \vec{a}_2, \vec{a}_3 \in \mathbb{R}^n$.

$$A = (\vec{a}_1 \mid \vec{a}_2 \mid \vec{a}_3) \quad n \times 3.$$

$$3 \times 3 \quad A^T A = \begin{pmatrix} \frac{\vec{a}_1^T \vec{a}_1}{\vec{a}_1^T \vec{a}_1} \\ \frac{\vec{a}_2^T \vec{a}_1}{\vec{a}_1^T \vec{a}_1} \\ \frac{\vec{a}_3^T \vec{a}_1}{\vec{a}_1^T \vec{a}_1} \end{pmatrix} (\vec{a}_1 \mid \vec{a}_2 \mid \vec{a}_3)$$

$$= \begin{pmatrix} \|\vec{a}_1\|^2 & \vec{a}_1 \cdot \vec{a}_2 & \vec{a}_1 \cdot \vec{a}_3 \\ \vec{a}_1 \cdot \vec{a}_2 & \|\vec{a}_2\|^2 & \vec{a}_2 \cdot \vec{a}_3 \\ \vec{a}_1 \cdot \vec{a}_3 & \vec{a}_2 \cdot \vec{a}_3 & \|\vec{a}_3\|^2 \end{pmatrix}$$

Use $\vec{a}_i \cdot \vec{a}_j = \|\vec{a}_i\| \|\vec{a}_j\| \cos \theta_{ij}$

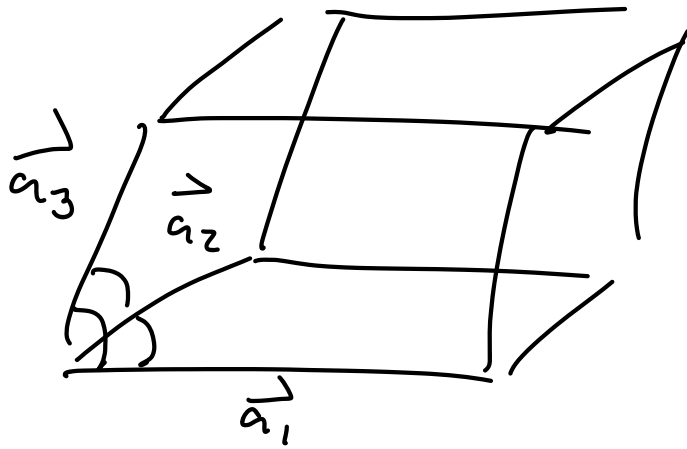
Plug into $A^T A$ to get

$$\det(A^T A) = \|\vec{a}_1\|^2 \|\vec{a}_2\|^2 \|\vec{a}_3\|^2.$$

$$\left(1 + 2 \cos \theta_{12} \cos \theta_{13} \cos \theta_{23} \right.$$

$$\left. - (\cos^2 \theta_{12} + \cos^2 \theta_{13} + \cos^2 \theta_{23}) \right)$$

= Volume² of parallelepiped (3D)
gen. by $\vec{a}_1, \vec{a}_2, \vec{a}_3$.



Since the formula depends only on lengths & angles, it holds in any # of dimensions.

$$\text{Vol}_k(A) = \sqrt{\det(A^T A)}$$

True even when A not square.

Special case $k=n$,

$$\text{Vol}_n(A) = \sqrt{\det(A^T A)}$$

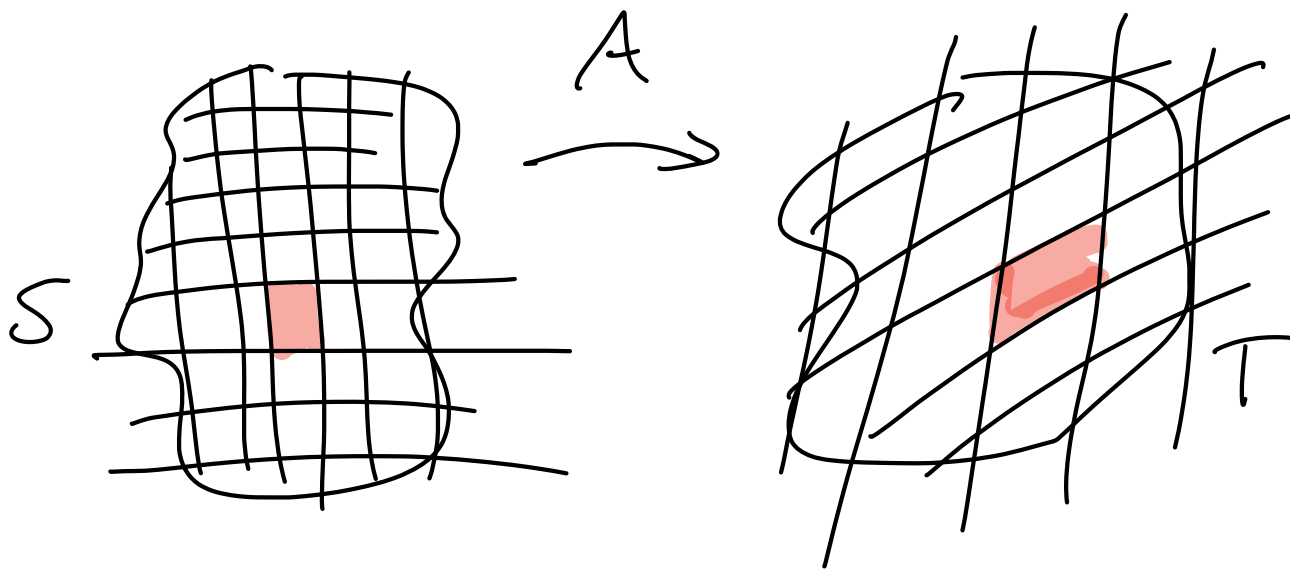
$$= \sqrt{\det(A) \det(A)}$$

$$= \sqrt{\det(A)^2} = |\det(A)|.$$

only makes sense for SQUARE A .

Application To Calculus.

Linear $A : \mathbb{R}^n \rightarrow \mathbb{R}^m$



Say A maps set $S \subseteq \mathbb{R}^n$
onto set $T \subseteq \mathbb{R}^m$. Then

$$\text{Vol}_n(T) = \sqrt{\det(A^T A)} \cdot \text{Vol}_n(S)$$

Non-linear $\vec{r} : \mathbb{R}^n \rightarrow \mathbb{R}^m$.

$$\vec{r}(\vec{p}) = (r_1(\vec{p}), \dots, r_m(\vec{p}))$$

where each $r_i : \mathbb{R}^n \rightarrow \mathbb{R}$

Taylor expand each component

$$r_i: \mathbb{R}^n \rightarrow \mathbb{R} \text{ at } \vec{p} \in \mathbb{R}^n:$$

$$r_i(\vec{p} + \vec{x}) = r_i(\vec{p}) + (\nabla r_i)_{\vec{p}}^T \vec{x} + \text{h.t.}$$

Then

$$\vec{r}(\vec{p} + \vec{x}) = \vec{r}(\vec{p}) + \begin{pmatrix} (\nabla r_1)_{\vec{p}}^T \\ \vdots \\ (\nabla r_m)_{\vec{p}}^T \end{pmatrix} \vec{x} + \dots$$

m x n matrix

Jacobian Matrix:

$$J_{\vec{r}} = \begin{pmatrix} \nabla r_1^T \\ \vdots \\ \nabla r_m^T \end{pmatrix} = \begin{pmatrix} \partial r_1 / \partial x_1 & \dots & \partial r_1 / \partial x_n \\ \vdots & & \vdots \\ \partial r_m / \partial x_1 & \dots & \partial r_m / \partial x_n \end{pmatrix}$$

$$\vec{r}(\vec{p} + \vec{x}) = \vec{r}(\vec{p}) + \underbrace{(J_{\vec{r}})_{\vec{p}}}_{m \times n} \underbrace{\vec{x}}_{n \times 1} + \dots$$

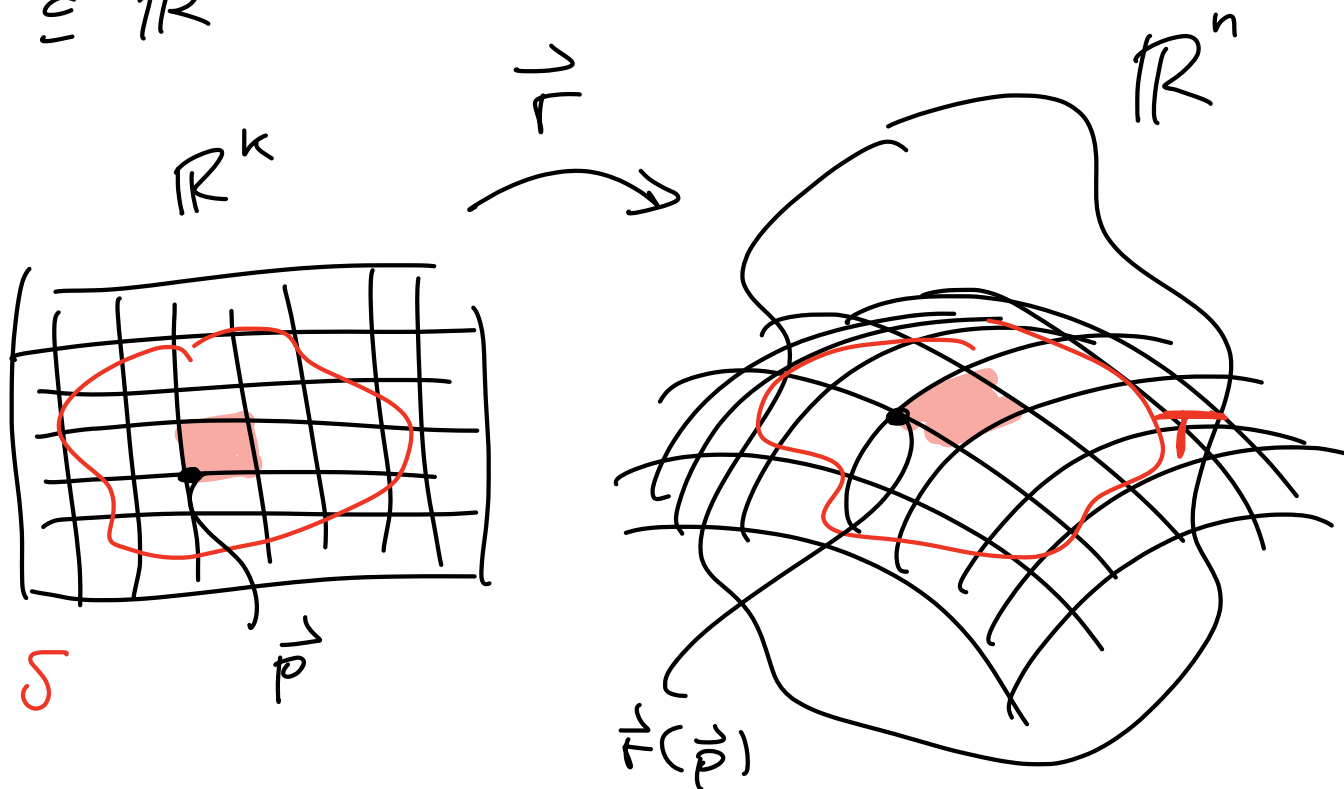
m x 1

Near \vec{p} the volume gets stretched

by factor of $\sqrt{\det((\mathbf{J}\vec{r})^T(\mathbf{J}\vec{r}))}$

THINK: $\vec{r} : \mathbb{R}^k \rightarrow \mathbb{R}^n$ as
a "parametrization" of a region

$T \subseteq \mathbb{R}^n$



Near \vec{p} , \vec{r} stretches volume by

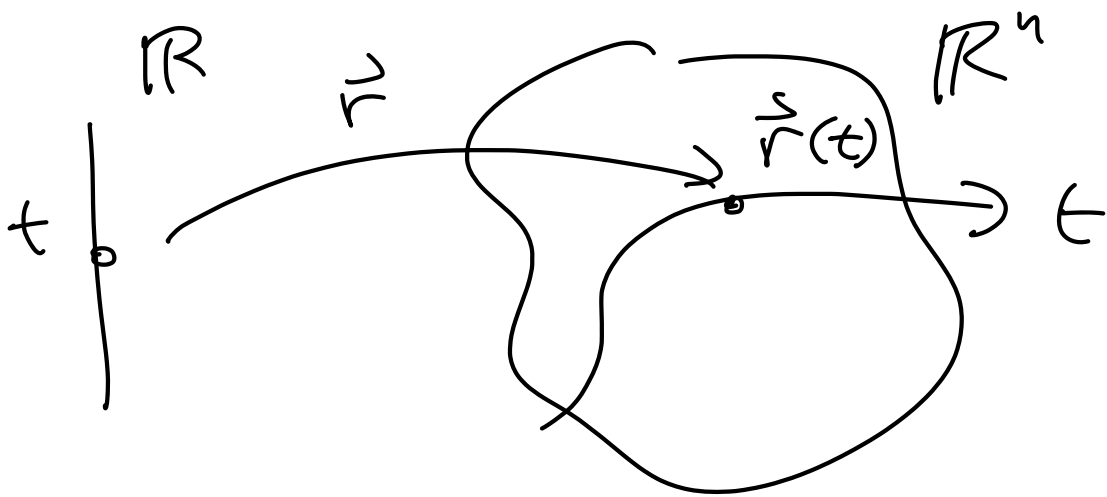
$$\sqrt{\det((\mathbf{J}\vec{r})_{\vec{p}}^T(\mathbf{J}\vec{r}))}$$

To compute k -volume of k -region
 $T \subseteq \mathbb{R}^n$ we integrate all the
little pieces of k -volume

$$\text{Vol}_k(T) = \int_{\vec{p} \in S} \sqrt{\det \left((\vec{J}_{\vec{r}})_{\vec{p}}^T (\vec{J}_{\vec{r}})_{\vec{p}} \right)} d\vec{p}$$

regular multiple integral
in Euclidean \mathbb{R}^k

e.g. Parametrized Path in \mathbb{R}^n

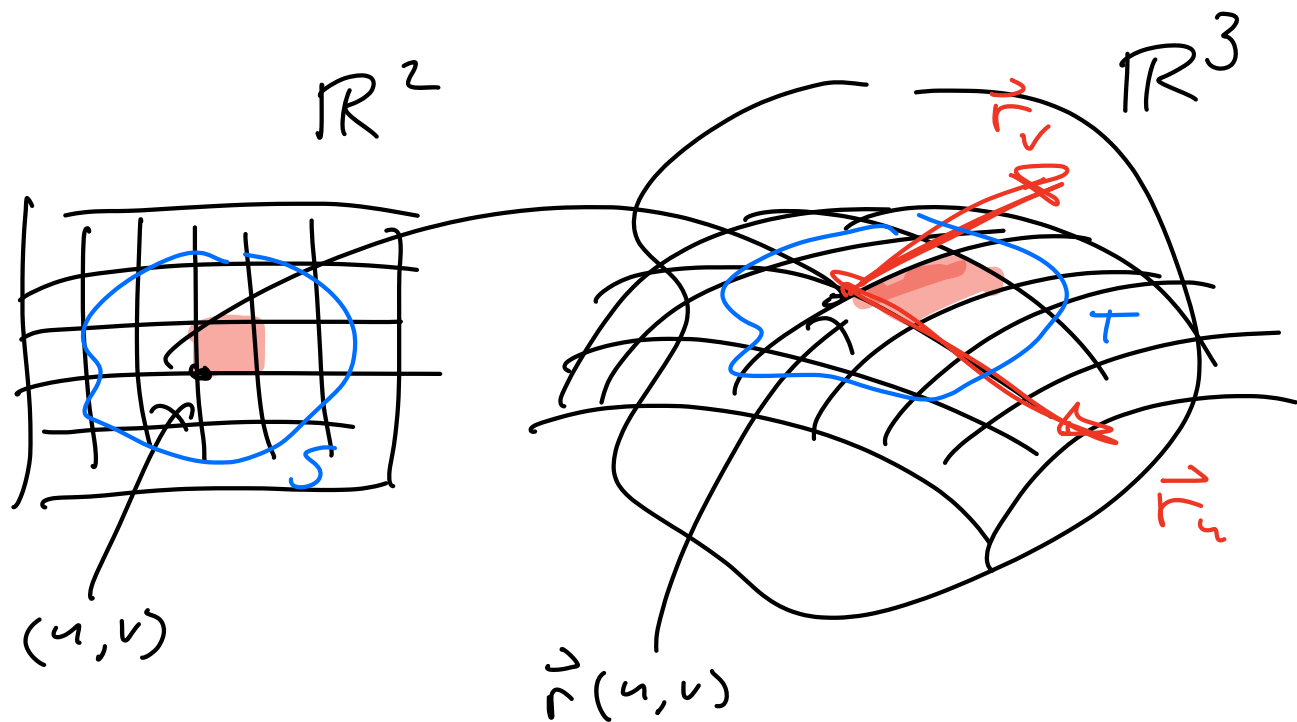


$$\vec{J}_{\vec{r}} = \nabla \vec{r} = \begin{pmatrix} \partial r_1 / \partial t \\ \partial r_2 / \partial t \\ \vdots \\ \partial r_n / \partial t \end{pmatrix} = \vec{r}'(t)$$

velocity.

$$\begin{aligned} \text{Arc length} &= \int \sqrt{\vec{r}'(t)^T \vec{r}'(t)} dt \\ &= \int \|\vec{r}'(t)\| dt \end{aligned}$$

Parametrized surface in \mathbb{R}^3 .



$$J_{\vec{r}} = \begin{pmatrix} \partial r_1 / \partial u & \partial r_1 / \partial v \\ \partial r_2 / \partial u & \partial r_2 / \partial v \\ \partial r_3 / \partial u & \partial r_3 / \partial v \end{pmatrix} = \begin{pmatrix} \vec{r}_u & | & \vec{r}_v \end{pmatrix}$$

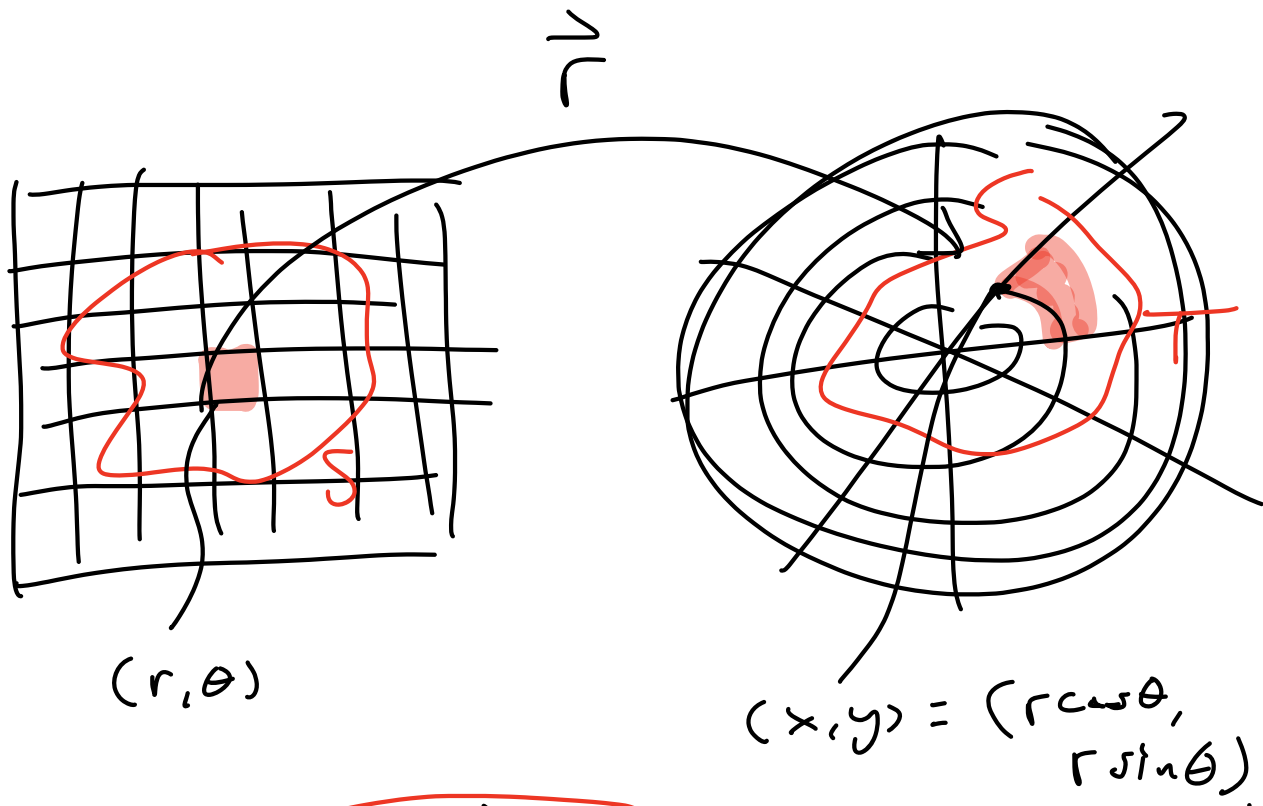
$$\sqrt{\det((J_{\vec{r}})^T (J_{\vec{r}}))} = \underbrace{\| \vec{r}_u \times \vec{r}_v \|}_{\text{peculiar 3D construction.}}$$

$$\text{Surface Area} = \int_S \| \vec{r}_u \times \vec{r}_v \| (u, v) \, du \, dv$$

Change of coordinates :

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$\begin{pmatrix} r \\ \theta \end{pmatrix} \mapsto \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} r \cos \theta \\ r \sin \theta \end{pmatrix}$$



$$J_{\vec{r}} = \begin{pmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{pmatrix}$$

gradient vectors.

$$= \begin{pmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{pmatrix}$$

$$\sqrt{\det((J_{\vec{r}})^T (J_{\vec{r}}))} = |\det(J_{\vec{r}})|$$

$$= r \cos^2 \theta + r \sin^2 \theta = r.$$

$$\text{Area of } T = \int_{(r,\theta) \in S} r \, dr \, d\theta$$



All the same!

Big Idea:

Alternating k -forms = Integrand