

## Four Fundamental Subspaces:

Given  $m \times n$  matrix  $A$ , get 4 subspaces:

$$R(A) \subseteq \mathbb{R}^n$$

$$N(A) \subseteq \mathbb{R}^n$$

$$C(A) \subseteq \mathbb{R}^m$$

$$N(A^T) \subseteq \mathbb{R}^m$$

$$A \begin{pmatrix} \vec{y} \\ \vec{x} \end{pmatrix} = \vec{0}$$

$m \times n$     $n \times 1$

$$\vec{x}^T A = \vec{0}^T$$

## Fundamental Theorems:

- Rank-Nullity Theorem

$$\dim R(A) + \dim N(A) = \# \text{ cols} = n$$

Proof:  $N(A) = R(A)^\perp$

$$A \vec{x} = \vec{0} \iff \vec{x} \perp \text{every row}$$

$$\begin{pmatrix} \vec{a}_1^T \\ \vdots \\ \vec{a}_m^T \end{pmatrix} \vec{x} = \begin{pmatrix} \vec{a}_1^T \vec{x} \\ \vdots \\ \vec{a}_m^T \vec{x} \end{pmatrix} = \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix}$$

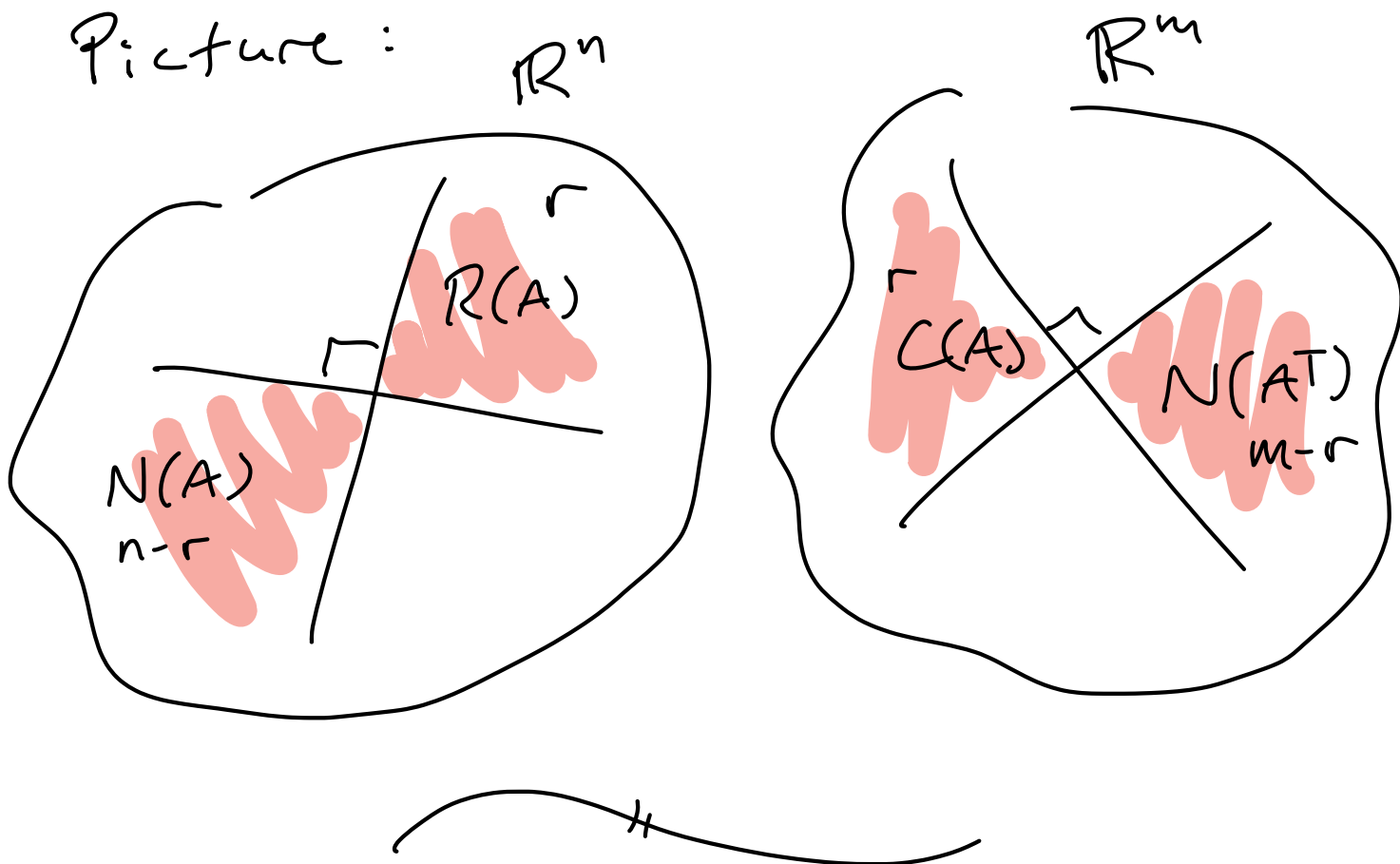
- Similar:  $N(A^T) = C(A)^\perp$

- $\dim R(A) = \dim C(A) = r$

- $\dim N(A) = n - r$

- $\dim N(A^T) = m - r.$

Picture :



EXAMPLE :

Consider  $A = \begin{pmatrix} 1 & 3 & 8 \\ 1 & 2 & 6 \\ 0 & 1 & 2 \end{pmatrix}.$

Compute the 4 subspaces.

$$N(A) = \left\{ \vec{x} : A\vec{x} = \vec{0} \right\}$$

$$\begin{pmatrix} 1 & 3 & 8 \\ 1 & 2 & 6 \\ 0 & 1 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}.$$

Row reduction:

$$\begin{pmatrix} \textcircled{1} & 3 & 8 \\ 1 & 2 & 6 \\ 0 & 1 & 2 \end{pmatrix} \rightsquigarrow \begin{pmatrix} 1 & 3 & 8 \\ 0 & \textcircled{-1} & -2 \\ 0 & 1 & 2 \end{pmatrix}$$

$$\rightsquigarrow \begin{pmatrix} 1 & 3 & 8 \\ 0 & -1 & -2 \\ 0 & 0 & 0 \end{pmatrix} \rightsquigarrow \begin{pmatrix} 1 & 3 & 8 \\ 0 & \textcircled{1} & 2 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\rightsquigarrow \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{pmatrix} \quad \text{RREF} \quad \checkmark$$

Matrices:

$$\underbrace{\begin{pmatrix} 1 & -3 \\ & 1 \\ & & 1 \end{pmatrix} \begin{pmatrix} 1 & & \\ & -1 & \\ & & 1 \end{pmatrix} \begin{pmatrix} 1 & & \\ & 1 & \\ & & 1 \end{pmatrix} \begin{pmatrix} 1 & & \\ & -1 & \\ & & 1 \end{pmatrix}}_E A$$

upper triang.      diagonal      lower triang.

$$E = \begin{pmatrix} -2 & 3 & 0 \\ 1 & -1 & 0 \\ -1 & 1 & 1 \end{pmatrix}$$

$$EA = \begin{pmatrix} -2 & 3 & 0 \\ 1 & -1 & 0 \\ -1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 3 & 8 \\ 1 & 2 & 6 \\ 0 & 1 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{pmatrix}$$

To solve  $A\vec{x} = \vec{0}$ .

$$EA\vec{x} = E\vec{0}$$

$$R\vec{x} = \vec{0}$$

$$\begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} x + 2z \\ y + 2z \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -2z \\ -2z \\ z \end{pmatrix} = z \begin{pmatrix} -2 \\ -2 \\ 1 \end{pmatrix}$$

$N(A)$  is a line.

$$R(A) = N(A)^\perp$$

= plane  $\perp$  to line  $\begin{pmatrix} -2 \\ -2 \\ 1 \end{pmatrix}$

= plane with eqn

$$-2x - 2y + z = 0$$

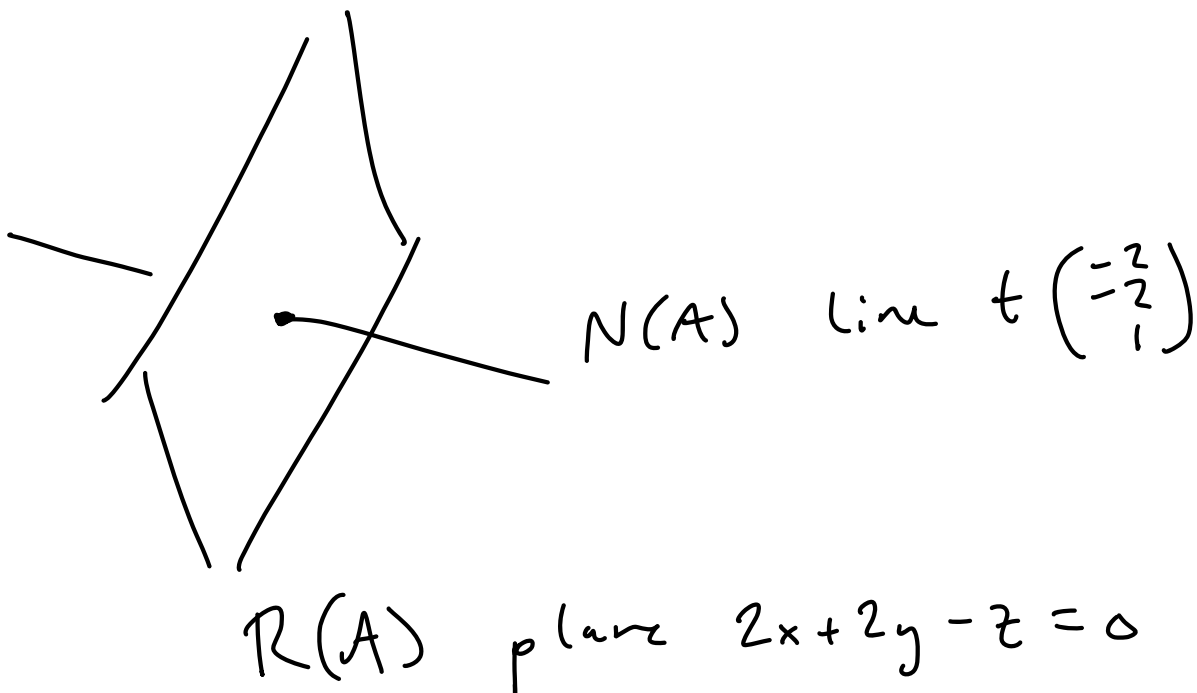
$$2x + 2y - z = 0$$

In fact the rows of  $R$  are a basis for  $R(A)$  because

$$R(EA) = R(A).$$

$$R \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{pmatrix} = R \begin{pmatrix} 1 & 3 & 2 \\ 1 & 2 & 0 \\ 0 & 1 & 8 \end{pmatrix}.$$

$$= s \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix} + t \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix}$$



Next  $C(A)$ : TWO WAYS.

$$\textcircled{1} \quad R = \begin{pmatrix} \textcircled{1} & 0 & 2 \\ 0 & \textcircled{1} & 2 \\ 0 & 0 & 0 \end{pmatrix}$$

has pivot cols 1 & 2 so  $C(A)$   
has basis given by its cols 1 & 2.

$$\text{basis for } C(A) = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \& \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix}.$$

Proof: Row ops do not change  
col relations: In  $R$  we have.

$$2(\text{col } 1) + 2(\text{col } 2) = (\text{col } 3)$$

Also holds in  $A$ :

$$2 \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + 2 \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 8 \\ 6 \\ 2 \end{pmatrix} \quad \checkmark$$

\textcircled{2} Compute  $R(A^T)$ :

$$\begin{pmatrix} 1 & 1 & 0 \\ 3 & 2 & 1 \\ 8 & 6 & 2 \end{pmatrix} \xrightarrow{\text{RREF}} \begin{pmatrix} \textcircled{1} & \textcircled{0} & \textcircled{1} \\ \textcircled{0} & \textcircled{1} & \textcircled{-1} \\ 0 & 0 & 0 \end{pmatrix}$$

so  $R(A^T)$  has basis  $\begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \in \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$

SAME:

$$\text{span} \left\{ \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} \right\} = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \right\}$$

$C(A)$  = plane with eqn?

$$N(A^T): \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} x + z \\ y - z \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -z \\ z \\ z \end{pmatrix} = z \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix}$$

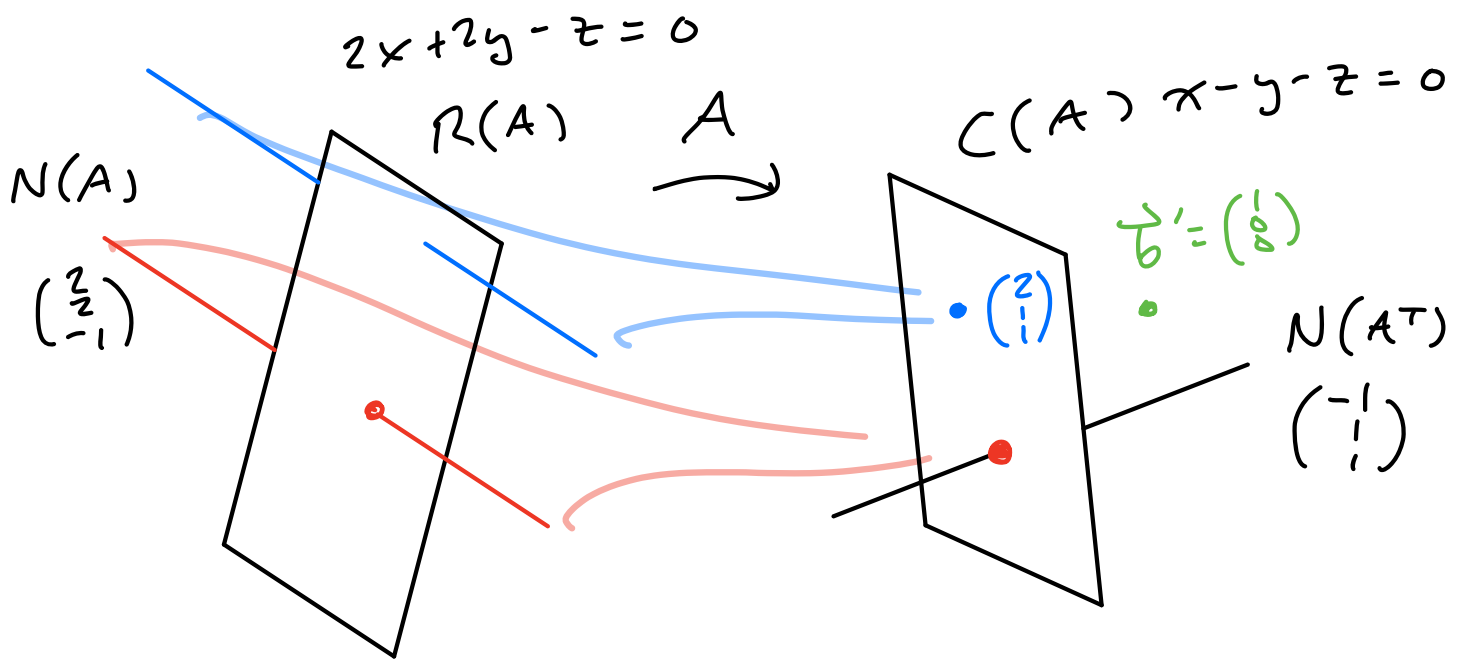
$$N(A^T) = \text{line } t \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix}$$

$C(A)$  = plane  $\perp$  to line  $t \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix}$

$$\text{has eqn } -x + y + z = 0.$$

$$x - y - z = 0.$$





$N(A) \rightsquigarrow$  origin

Note  $\begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}$  is in  $C(A)$  since  $x - y - z = 0$ .

So  $A\vec{x} = \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}$  has a solution!

Solution is a line  $\parallel$  to  $N(A)$ .

$$A\vec{x} = \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} \Leftrightarrow \vec{x} = \vec{x}' + t \begin{pmatrix} 2 \\ 2 \\ -1 \end{pmatrix}$$

So we just need one particular solution.

$$A\vec{x} = \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} \Rightarrow EA\vec{x} = E \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}$$



$$R \vec{x} = \begin{pmatrix} -2 & 3 & 0 \\ 1 & -1 & 0 \\ -1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \vec{x}'$$

$$\begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -1 - 2z \\ 1 - 2z \\ 0 + z \end{pmatrix}$$

$$= \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} + t \begin{pmatrix} 2 \\ 2 \\ -1 \end{pmatrix}$$

Finally: Take  $\vec{b}' = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \notin C(A)$ .

So  $A\vec{x} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$  has NO SOLUTION.

Instead look for  $\vec{x}$  so

$\|A\vec{x} - \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}\|$  minimized.

Geometrically: Project  $\vec{b}'$

onto the col space.

