

Today: The Spectral Theorem. (Principal Axes Theorem).

Recall:

$$\lambda \text{ e. vector} \iff \exists \vec{x} \neq \vec{0}, A\vec{x} = \lambda\vec{x}$$

$$\iff (\lambda I - A)\vec{x} = \vec{0}, \vec{x} \neq \vec{0}$$

$$\iff N(\lambda I - A) \text{ not } \{\vec{0}\}$$

$$\iff \det(\lambda I - A) = 0.$$

i.e. e. values are the roots of the characteristic polynomial

$$\chi_A(x) = \det(xI - A).$$

For any polynomial $f(x)$ we can evaluate at A :

$$f(x) = b_0 + b_1x + \dots + b_kx^k$$

$$f(A) = b_0I + b_1A + \dots + b_kA^k.$$

Cayley - Hamilton Theorem:

Any square matrix A is a "root"
of its own char poly:

$$\chi_A(A) = \text{zero matrix.}$$

Proof: Assume A diag'ble:

$$A = X \Lambda X^{-1}$$

$$\Lambda = \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{pmatrix}.$$

By definition, every e.value of A
is a root of χ_A , so

$$\chi_A(\Lambda) = \begin{pmatrix} \cancel{\chi_A(\lambda_1)} & & \\ & \ddots & \\ & & \cancel{\chi_A(\lambda_n)} \end{pmatrix}$$

$$= \begin{pmatrix} 0 & & \\ & \ddots & \\ & & 0 \end{pmatrix} = \mathbf{0}.$$

But then, *important.*

$$\chi_A(A) \stackrel{\text{important.}}{=} \chi_A(X \Lambda X^{-1})$$

$$= X \cdot \chi_A(\Lambda) \cdot X^{-1}$$

$$= X \cdot 0 \cdot X^{-1} = 0.$$

[$A = X B X^{-1}$. For any poly $f(x)$,

$$f(A) = X \cdot f(B) \cdot X^{-1}.$$

Recall:

$$A^k = (X B X^{-1})^k$$

$$= (X B X^{-1}) (X B X^{-1})^{k-1}$$

$$= X B \cancel{X^{-1} X} B^{k-1} X^{-1}$$

$$= X B^k X^{-1}.]$$

Cayley-Hamilton follows for non-diag'ble matrices "by continuity"



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If χ_A has distinct roots
we showed A has a basis of
e.vectors so A is d'ble.

Not "if and only if".

e.g. $A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ has

$\chi_A(x) = (x-1)^2$ repeated e.value.

But it's still d'ble.

Better Theorem (Won't prove it).

A is d'ble \iff

$f(A) = 0$ for some polynomial
with distinct roots.

e.g. $P^2 = P \implies P$ d'ble.

because $f(x) = x^2 - x = x(x-1)$
has distinct roots.

e.g. $\mathbb{R}^n = \mathbb{I} \implies \mathbb{R}$ d'ble.

because $f(x) = x^n - 1$ has
distinct roots:

$$f(x) = \prod_{k=1}^n (x - e^{2\pi i k/n}).$$



Simplest Non-Example:

$$A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}.$$

$$\chi_A(x) = (x-1)^2 \text{ repeated root.}$$

But A is not a root of any
smaller polynomial.

$$f(x) = x - 1.$$

$$f(A) = A - I = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \neq \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}.$$

[Remark: Nilpotent matrices, i.e.

$$A^k = 0 \text{ for some } k,$$

are the abstraction to diagonalization.]



The Spectral Theorem
(Principal Axes Theorem).

Call a matrix A normal when

$$A^*A = AA^*$$

$$A^T A = A A^T.$$

Includes several important classes
of matrices:

$$A^T = A$$

$$A^* = A$$

$$A^T A = I$$

$$A^* A = I.$$

Theorem: Not only are these
diagonalizable, they are
unitarily diagonalizable.

Meaning they have o.n. basis

of e.vectors.

$$A^* A = A A^*$$

$\implies \exists$ e.vectors $\vec{u}_1, \dots, \vec{u}_n \in \mathbb{C}^n$
such that $\vec{u}_i^* \vec{u}_j = \delta_{ij}$

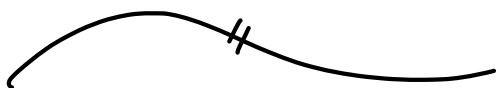
Implies $U = (\vec{u}_1 | \dots | \vec{u}_n)$ is
a unitary matrix:

$$\begin{aligned} U^* U &= \begin{pmatrix} \vec{u}_1^* \\ \vdots \\ \vec{u}_n^* \end{pmatrix} (\vec{u}_1 | \dots | \vec{u}_n) \\ &= \begin{pmatrix} \vec{u}_1^* \vec{u}_1 & \dots & \vec{u}_1^* \vec{u}_n \\ \vdots & & \vdots \\ \vec{u}_n^* \vec{u}_1 & \dots & \vec{u}_n^* \vec{u}_n \end{pmatrix} = \mathbf{I}. \end{aligned}$$

Hence

$$A = U \Lambda U^{-1}$$

$$A = U \Lambda U^*.$$



Proof uses an auxiliary result called Schur's Theorem.

Any square matrix is unitarily triangularizable:

$$A = U T U^*$$

where $U^* U = I$ &

$$T = \begin{pmatrix} t_{11} & & * \\ & t_{22} & \\ 0 & & \ddots \\ & & & t_{nn} \end{pmatrix}.$$

Assume this for the moment.

Then Spectral Theorem follows right away:

e.g. Take $A^T = A$ symmetric and real. Then

Schur: $A = Q T Q^T$

where $Q^T Q = I$ is real

orthogonal matrix.

Equivalently: $T = Q^T A Q$.

Use the fact that $A^T = A$
to see

$$\begin{aligned} T^T &= (Q^T A Q)^T \\ &= Q^T A^T Q^{TT} \\ &= Q^T A Q = T. \end{aligned}$$

Have $T = \begin{pmatrix} t_{11} & * \\ 0 & t_{nn} \end{pmatrix}$

$$\& T = T^T = \begin{pmatrix} t_{11} & 0 \\ * & t_{nn} \end{pmatrix}.$$

$\implies T$ is diagonal:

$$T = \begin{pmatrix} t_{11} & 0 \\ 0 & t_{nn} \end{pmatrix}.$$

Proof of Schur:

Square matrix A .

Any matrix has at least one
eigenvalue $\in \mathbb{C}$. Let

char poly
has at least
one root in \mathbb{C} .

$$A \vec{u}_1 = t_{11} \vec{u}_1$$

for some $\vec{u}_1 \in \mathbb{C}^n$, $t_{11} \in \mathbb{C}$.

Assume $\|\vec{u}_1\| = 1$. Choose any
unitary matrix with 1st col \vec{u}_1 :

$$U_1 = \left(\vec{u}_1 \mid \underbrace{\vec{u}_2 \mid \dots \mid \vec{u}_n}_{\text{easy to choose}} \right).$$

So $U_1^* = U_1^{-1}$. Then

$$\begin{aligned} & U_1^* A U_1 \\ &= \begin{pmatrix} \vec{u}_1^* \\ \vdots \\ \vec{u}_n^* \end{pmatrix} \left(A \vec{u}_1 \mid A \vec{u}_2 \mid \dots \mid A \vec{u}_n \right) \end{aligned}$$

$$= \begin{pmatrix} \overrightarrow{u_1^*} \\ \vdots \\ \overrightarrow{u_n^*} \end{pmatrix} \left(t_{11} \overrightarrow{u_1} \mid * \mid \dots \mid * \right).$$

$$= \left(\begin{array}{c|ccc} t_{11} & * & \dots & * \\ \hline 0 & & & \\ \vdots & & & \\ 0 & & & \end{array} \right) \begin{array}{c} \\ \\ \\ A_2 \end{array}$$

Now use induction.

\exists unitary U_2 , $U_2^* A_2 U_2 = T_2$
 where T_2 is upper triangular.

Finally, let

$$U = U_1 \left(\begin{array}{c|ccc} 1 & 0 & \dots & 0 \\ \hline 0 & & & \\ \vdots & & & \\ 0 & & & U_2 \end{array} \right),$$

which satisfies $U^* U = I$:

$$\left(\begin{array}{c} 1 \\ \hline U_2^* \end{array} \right) \cancel{U_1^*} U_1 \left(\begin{array}{c} 1 \\ \hline U_2 \end{array} \right)$$

$$= \left(\begin{array}{c|c} 1 & \\ \hline & u_2^* u_2 \end{array} \right)$$

$$= \left(\begin{array}{c|c} 1 & \\ \hline & I_{n-1} \end{array} \right) = I_n \quad \checkmark$$

$$u^* A u$$

$$= \left(\begin{array}{c|c} 1 & \\ \hline & u_2^* \end{array} \right) u_1^* A u_1 \left(\begin{array}{c|c} 1 & \\ \hline & u_2 \end{array} \right)$$

$$= \left(\begin{array}{c|c} 1 & \\ \hline & u_2 \end{array} \right) \left(\begin{array}{c|c} t_{11} & * \dots * \\ \hline 0 & A_2 \\ \vdots & \\ 0 & \end{array} \right) \left(\begin{array}{c|c} 1 & \\ \hline & u_2 \end{array} \right)$$

$$= \left(\begin{array}{c|c} t_{11} & * \dots * \\ \hline 0 & u_2^* A_2 u_2 \\ \vdots & \\ 0 & \end{array} \right)$$

$$= \left(\begin{array}{c|c} t_{11} & * \dots * \\ \hline 0 & T_2 \\ \vdots & \\ 0 & \end{array} \right) \quad \text{triangular} \quad \checkmark$$