

HW 6 due Tues Dec 13.
Office Hours, by appointment.



Singular Value Decomposition.

Recall, for normal matrices
 $A^*A = AA^*$ we have the
spectral Theorem:

$$A = U \Delta U^*$$

where $U^*U = I$ (unitary)

& Δ is diagonal.

If $A^*A \neq AA^*$ then A might
not even be diagonalizable:

$$A \neq X \Lambda X^{-1}$$

The Jordan form is one way out.

The other important Theorem is the SVD which applies even to non-square matrices:

$$A = U \Sigma V^*$$

Diagonal
pos. real
entries

$$U^*U = I \\ V^*V = I.$$

Proof: Let A $m \times n$, rank r .

Consider A^*A $n \times n$, rank r .

Since A^*A pos. semi-def, the eigenvalues are

$$\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_r > 0, \underbrace{0, \dots, 0}_{n-r \text{ zeros.}}$$

write $\sigma_i^2 = \lambda_i$
 $\sigma_i > 0$.

Since A^*A is normal (in fact, Hermitian), Spectral Theorem

$\Rightarrow \exists$ orthonormal eigenvectors.

$$\vec{v}_1, \dots, \vec{v}_r, \vec{v}_{r+1}, \dots, \vec{v}_n \in \mathbb{R}^n$$

$$A^* A \vec{v}_i = \sigma_i^2 \vec{v}_i \quad i \leq r$$

$$A^* A \vec{v}_i = 0 \quad i > r.$$

TRICK: for $1 \leq i \leq r$, define vectors $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_r \in \mathbb{R}^m$ by

$$\vec{u}_i = \frac{1}{\sigma_i} A \vec{v}_i. \quad A \vec{v}_i = \sigma_i \vec{u}_i$$

Then automatically have

$$A (\vec{v}_1 | \dots | \vec{v}_r)$$

$$= (A \vec{v}_1 | \dots | A \vec{v}_r)$$

$$= (\sigma_1 \vec{u}_1 | \dots | \sigma_r \vec{u}_r)$$

$$= (\vec{u}_1 | \dots | \vec{u}_r) \begin{pmatrix} \delta_1 & & \\ & \ddots & \\ & & \delta_r \end{pmatrix}$$

$$A V = U \Sigma$$

$$A \begin{pmatrix} \vec{v}_1 | \dots | \vec{v}_r \end{pmatrix} = \begin{pmatrix} \vec{u}_1 | \dots | \vec{u}_r \end{pmatrix} \Sigma$$

$m \times n$ $n \times r$ $m \times r$ $r \times r$

Know $V^* V = I_r$ since \vec{v}_i
are orthonormal: $\vec{v}_i^* \vec{v}_j = \delta_{ij}$.

Hence

$$A = U \Sigma V^*$$

Still need to check that $U^* U = I_r$
i.e. that $\vec{u}_i^* \vec{u}_j = \delta_{ij}$.

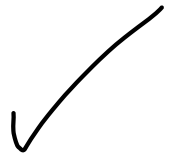
By definition,

$$\begin{aligned} \vec{u}_i^* \vec{u}_j &= \left(\frac{1}{\delta_i} A \vec{v}_i \right)^* \left(\frac{1}{\delta_j} A \vec{v}_j \right) \\ &= \frac{1}{\delta_i \delta_j} \vec{v}_i^* \boxed{A^* A \vec{v}_j} \end{aligned}$$

$$= \frac{1}{\delta_i \delta_j} \vec{v}_i^* (\delta_j^2 \vec{v}_j)$$

$$= \frac{\delta_j}{\delta_i} \vec{v}_i^* \vec{v}_j = \begin{cases} 0 & i \neq j \\ \delta_i / \delta_i = 1 & i = j. \end{cases}$$

Hence $\vec{u}_i^* \vec{u}_j = \delta_{ij}$ (orthonormal).



But more is true. We started with \vec{v}_i to get \vec{u}_i . But it's really a symmetric theorem.

In fact we have

$$AA^* = (U \Sigma V^*) (U \Sigma V^*)^*$$

$$= U \Sigma \cancel{V^* V} \Sigma^* U^*$$

$$= U \Sigma^2 U^* \quad \Sigma^* = \Sigma.$$

$$\implies AA^* \vec{u}_i = \delta_i^2 \vec{u}_i$$

For all $i \leq r$.

That is, A^*A & AA^* have the same nonzero eigenvalues

$\delta_1^2 \geq \dots \geq \delta_r^2$ and \exists orthonormal

sets of e.vectors satisfying

$$A^*A \vec{v}_i = \delta_i^2 \vec{v}_i$$

$$AA^* \vec{u}_i = \delta_i^2 \vec{u}_i$$

$$A \vec{v}_i = \delta_i \vec{u}_i$$

SVD.

SVD gives the Moore-Penrose pseudo-inverse of a rectangular matrix. A $m \times n$.

$$A = U \Sigma V^*$$

$m \times n$ $m \times r$ $r \times r$ $r \times n$.

Σ is diagonal and invertible:

$$\begin{pmatrix} \sigma_1 & & \\ & \ddots & \\ & & \sigma_r \end{pmatrix}^{-1} = \begin{pmatrix} 1/\sigma_1 & & \\ & \ddots & \\ & & 1/\sigma_r \end{pmatrix}.$$

Define the pseudo-inverse

$$A^+ = V \Sigma^{-1} U^*.$$

$m \times n$ $m \times r$ $r \times r$ $r \times n$.

Satisfies 4 defining properties:

$$AA^+A = A$$

$$A^+AA^+ = A^+$$

$$(AA^+)^* = AA^+$$

$$(A^+A)^* = A^+A.$$

\exists unique matrix with these properties & SVD allows you to find it.

If A has independent columns
then

$$A^+ = (A^* A)^{-1} A^*$$

which (as we know) is a left
inverse of A .

$$A^+ A = \cancel{(A^* A)^{-1} A^* A} = I.$$

If A has independent rows
then

$$A^+ = A^* (A A^*)^{-1}$$

which is a right inverse:

$$A A^+ = \cancel{A A^* (A A^*)^{-1}} = I.$$

If A is square with ind rows
& columns, then

$$A A^+ = A^+ A = I.$$

$$\Rightarrow A^+ = A^{-1}.$$

What is SVD used for?

Eckart - Young - Mirsky etc...

Rediscovered many times...

Given $m \times n$ matrix A , rank r ,
consider SVD:

$$A = U \Sigma V^*$$
$$= (\vec{u}_1 | \dots | \vec{u}_r) \begin{pmatrix} \sigma_1 & & \\ & \ddots & \\ & & \sigma_r \end{pmatrix} \begin{pmatrix} \vec{v}_1^* \\ \vdots \\ \vec{v}_r^* \end{pmatrix}$$

$$= \sum_{i=1}^r \sigma_i \vec{u}_i \vec{v}_i^*$$

rank one matrix.

Sort $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_r > 0$.

For any $k \leq r$, define

$$A_k = \sum_{i=1}^k \sigma_i \vec{u}_i \vec{v}_i^*$$

Then (theorem) for any $m \times n$ matrix B of rank $\leq k$, have

$$\|A - A_k\| \leq \|A - B\|$$

best rank k approximation to A .

for any "unitarily invariant" norm.

Includes Frobenius & Operator norms.



Special Case on HWG.

Rayleigh Quotient.

Given $m \times n$ matrix A , consider

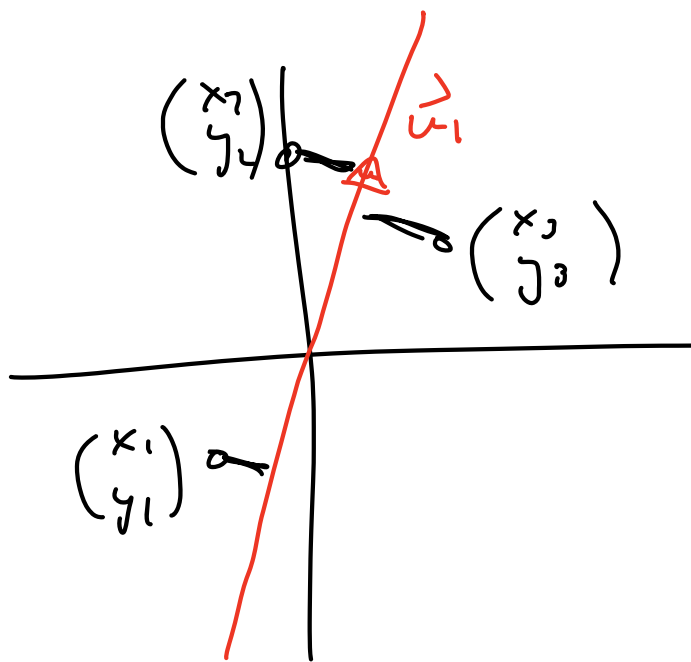
$$r: \mathbb{R}^n \rightarrow \mathbb{R}_{\geq 0}$$

$$r(\vec{x}) = \frac{\|A\vec{x}\|^2}{\|\vec{x}\|^2}$$

Problem: Find \vec{x} to maximize $r(\vec{x})$.

Answer: Vector \vec{u}_1 from
the SVD of A .

Apply to T.L.S.



$$X = \begin{pmatrix} x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \end{pmatrix} \quad 2 \times 3.$$

$$X = U \Sigma V^*$$
$$= \begin{pmatrix} \vec{u}_1 & \vec{u}_2 \end{pmatrix} \begin{pmatrix} \sigma_1 & \sigma_2 \end{pmatrix} \begin{pmatrix} \vec{v}_1^* \\ \vec{v}_2^* \end{pmatrix}.$$

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Apply SVD to image compression.

$m \times n$ pixel image = $m \times n$ matrix.
greyscale.

A $m \times n$ image (rank r),
certainly $r = \min\{m, n\}$.

$$A = \sum_{i=1}^r \sigma_i \vec{u}_i \vec{v}_i^*$$

$$\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_r > 0.$$

Truncation ($k \leq r$)

$$A_k = \sum_{i=1}^k \sigma_i \vec{u}_i \vec{v}_i^*$$

is a compressed version of
the image.

Works well if the singular
values drop off:

