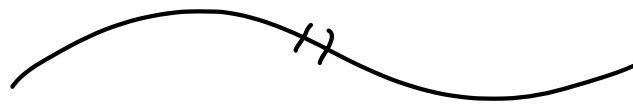


HW 6 due Tues Dec 13.

Choose 5 Problems.



Applications.

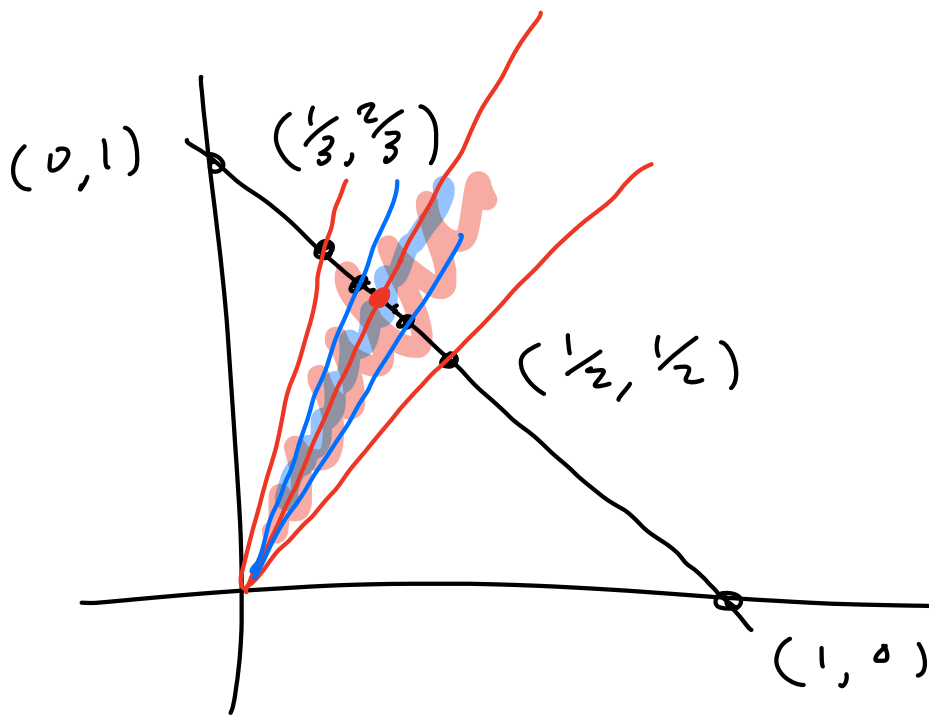
Last Time: Markov chains.

$$M = \begin{pmatrix} 1/2 & 1/3 \\ 1/2 & 2/3 \end{pmatrix}.$$

saw \exists unique equilibrium
distribution:

$$M \begin{pmatrix} 2/5 \\ 3/5 \end{pmatrix} = \begin{pmatrix} 2/5 \\ 3/5 \end{pmatrix}.$$

Geometry: look at how M^n
acts on the standard basis
of \mathbb{R}^2 .



$$M = \begin{pmatrix} 1/2 & 1/3 \\ 1/2 & 2/3 \end{pmatrix}$$

$$M^2 = \begin{pmatrix} 5/12 & 7/18 \\ 7/12 & 11/18 \end{pmatrix}.$$

M acting on 1st quadrant is a "contraction mapping".

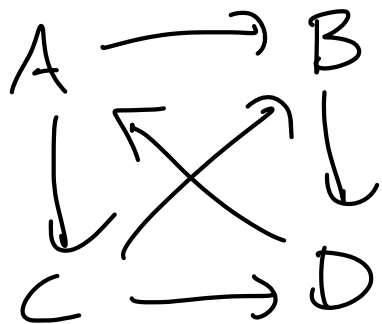
Contraction mappings in general converge to a unique limit.

4

Perron-Frobenius more general
than Markov chains.

e.g. Google Page-Rank.

Tournament arrow "A → B"
"A defeated B".



Who is the winner? A?

Rank the players.

Issue: D looks bad,

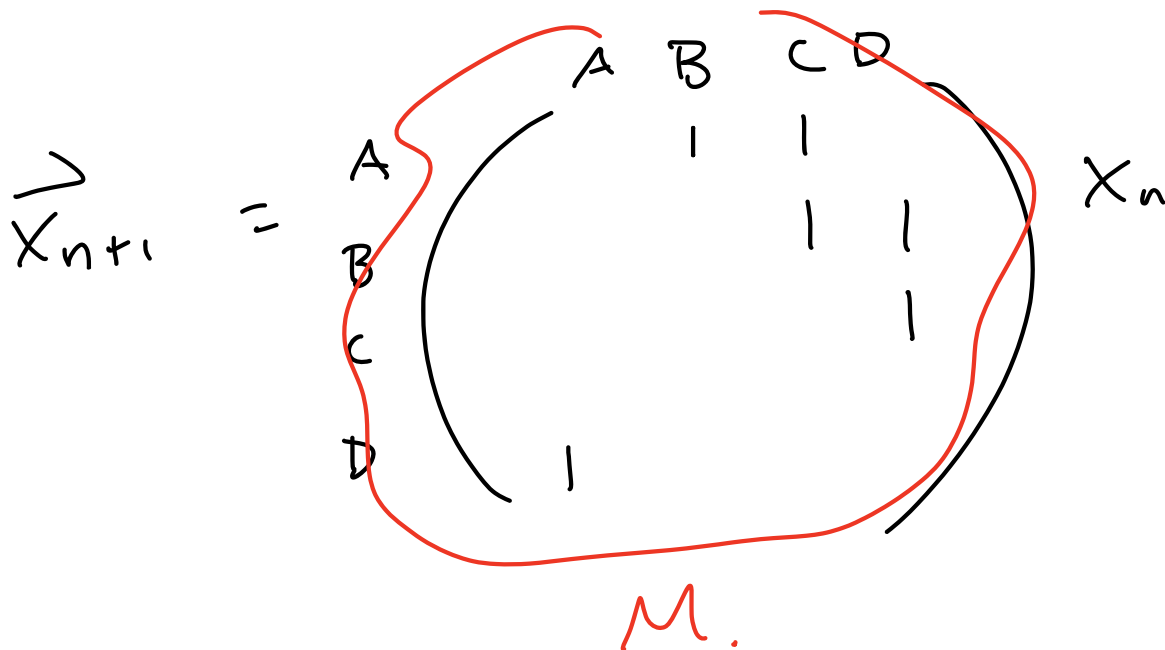
but D defeated A ...

Recursive: Assign random

initial scores $\vec{x}_0 = (1, 1, 1, 1)$.

update the scores

your $(n+1)$ st score = \sum nth scores of people you defeated.



$$\vec{X}_0 = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}, \vec{X}_1 = \begin{pmatrix} 2 \\ 2 \\ 1 \\ 1 \end{pmatrix}, \vec{X}_2 = \begin{pmatrix} 3 \\ 2 \\ 1 \\ 2 \end{pmatrix}$$

$$\dots, \vec{X}_5 = \begin{pmatrix} 8 \\ 6 \\ 3 \\ 5 \end{pmatrix}$$

Rank:

A > B > D > C.

$$\dots \vec{X}_{100} = \begin{pmatrix} 1037 \\ 933 \\ 547 \\ 731 \end{pmatrix}$$

When can we stop?

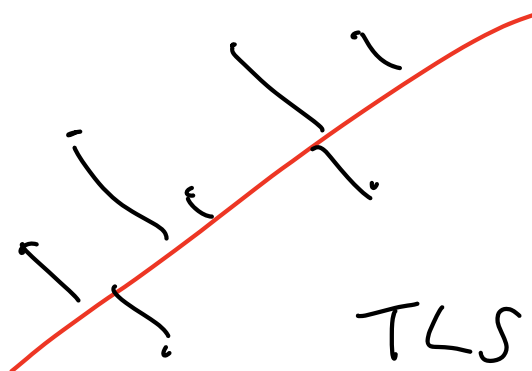
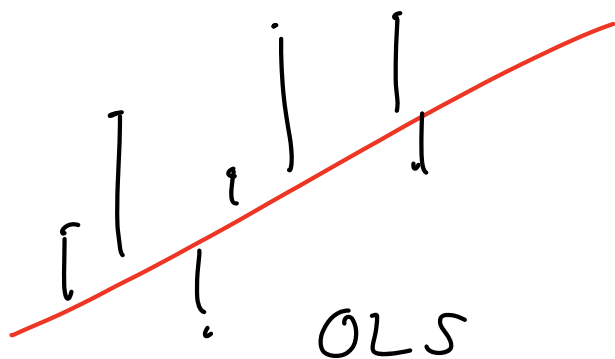
Perron-Frobenius: IF you normalize at each step (make the scores sum to 1) then there is a unique equilibrium:

$$\vec{x}_n \rightarrow \begin{pmatrix} 0.321 \dots \\ 0.283 \dots \\ 0.165 \dots \\ 0.230 \dots \end{pmatrix}$$

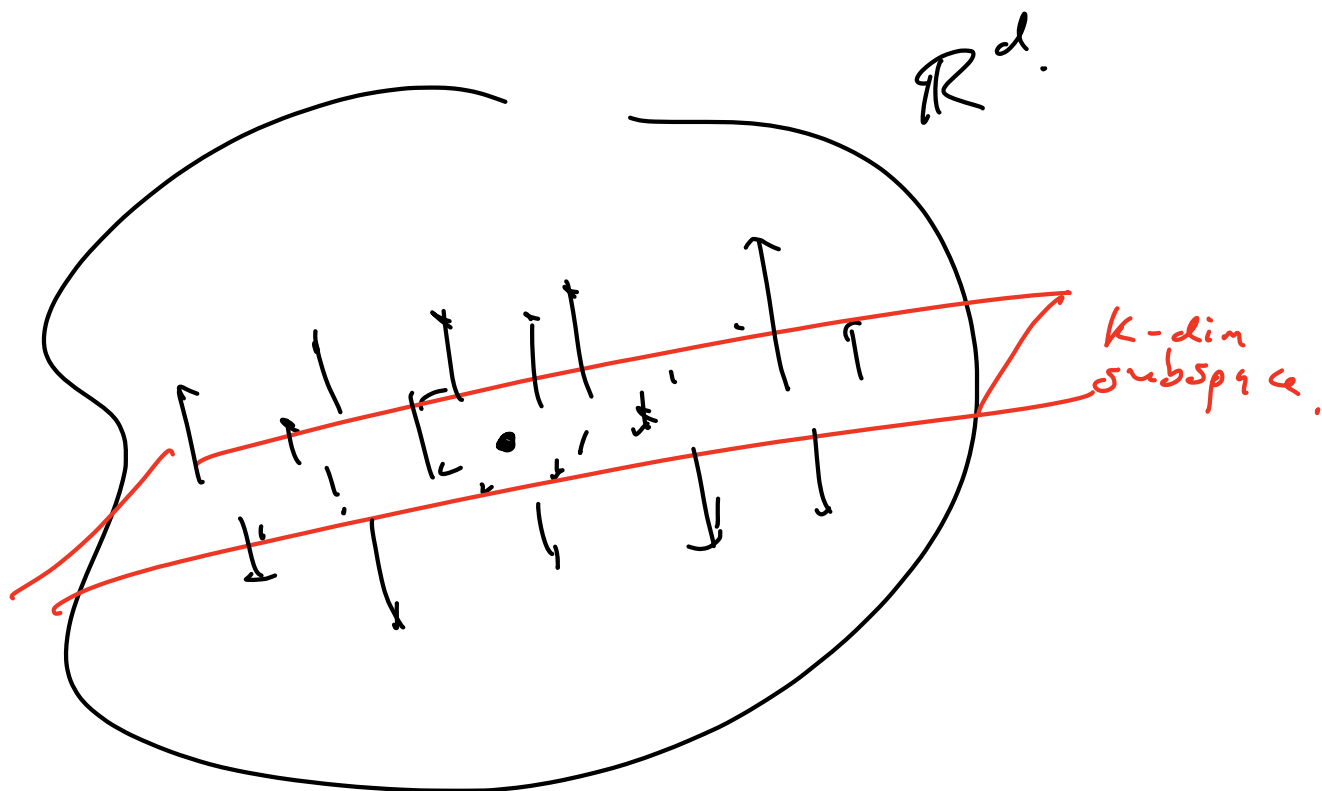
↑
normalized.



Recall: Ordinary vs. Total Least Squares.



Problem: Given n data points in d -dim space \mathbb{R}^d .



Data: $\vec{x}_1, \dots, \vec{x}_n \in \mathbb{R}^d$.

Assume data is centered:

$$\vec{x}_1 + \vec{x}_2 + \dots + \vec{x}_n = \vec{0}.$$

Problem: Find the k -dim subspace of \mathbb{R}^n that minimizes sum of squares of orthogonal distances to data points.

Form the data matrix:

$$X = \underbrace{\left(\begin{array}{c|c|c|c} \vec{x}_1 & \vec{x}_2 & \dots & \vec{x}_n \end{array} \right)}_n \Bigg\}^d.$$

Assume $n \gg d$,

so $\text{rank}(X) = d$.

Consider the invertible $d \times d$ matrix XX^T .

The eigenvalues are real & positive
symmetric *pos. def*

Typical to write e. values as

$$\sigma_1^2 \geq \sigma_2^2 \geq \dots \geq \sigma_d^2 > 0.$$

*probably strict
because data is noisy.*

Jargon: $\sigma_1, \sigma_2, \dots, \sigma_d$ are the "singular values" of the data matrix X .

Since XX^T is symmetric,
Spectral Theorem

$\implies \exists$ orthonormal basis
of eigenvectors:

$$\vec{u}_1, \vec{u}_2, \dots, \vec{u}_d \in \mathbb{R}^d$$

$$XX^T \vec{u}_k = \sigma_k^2 \vec{u}_k.$$

Theorem (Total Least Squares)

Best fit k -dim subspace

($k \leq d$) is

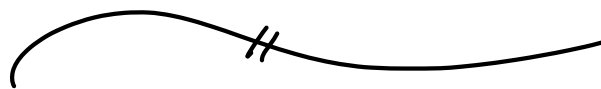
$$\text{span} \{ \vec{u}_1, \vec{u}_2, \dots, \vec{u}_k \}.$$

Special Case: Best fit line

For the data points is

$t\vec{u}_1$, where \vec{u}_1 is any
eigenvector for XX^T corresponding
to the largest eigenvalue.

Very common method in data
science called "principal
component analysis".



Background Theory:

The SVD (Singular Value
Decomposition).

Given $m \times n$ matrix A , rank r .

Recall

$$\begin{aligned}\text{rank}(A^T A) &= \text{rank}(A A^T) \\ &= \text{rank}(A) = \text{rank}(A^T).\end{aligned}$$

Eigenvalues of $A^T A$ are

$$\delta_1^2 \geq \delta_2^2 \geq \dots \geq \delta_r^2, \underbrace{0, 0, \dots, 0}_{n-r \text{ zeros.}}$$

Spectral Theorem

$\implies \exists$ o.n. basis of e.vectors.

$$\vec{v}_1, \dots, \vec{v}_r, \vec{v}_{r+1}, \dots, \vec{v}_n \in \mathbb{R}^n$$

$$A^T A \vec{v}_k = \begin{cases} \delta_k^2 \vec{v}_k & k \leq r, \\ 0 & \text{else.} \end{cases}$$

Claim that AA^T has eigenvalues

$$\delta_1^2 \geq \delta_2^2 \geq \dots \geq \delta_r^2; \underbrace{0, \dots, 0}_{m-r \text{ zeros.}}$$

i.e. $A^T A$ & AA^T have the same nonzero eigenvalues.

Furthermore, we can find an

o.n. basis of e.vectors for AA^T .

$$\vec{u}_1, \vec{u}_2, \dots, \vec{u}_m \in \mathbb{R}^m$$

such that

$$A^T A \vec{v}_k = \delta_k^2 \vec{v}_k$$

$$A A^T \vec{u}_k = \delta_k^2 \vec{u}_k$$

$$A \vec{v}_k = \delta_k \vec{u}_k$$

SVD

for all $k \leq r$.

"simultaneously diagonalized
 $A^T A$ & $A A^T$ "

In matrix terms:

$$A = \left(\begin{array}{c|c} \vec{u}_1 & \dots & \vec{u}_r \end{array} \right) \begin{pmatrix} \delta_1 & & \\ & \ddots & \\ & & \delta_r \end{pmatrix} \begin{pmatrix} \frac{\vec{v}_1^T}{\delta_1} \\ \vdots \\ \frac{\vec{v}_r^T}{\delta_r} \end{pmatrix}$$

$m \times n$ $m \times r$ $r \times r$ $r \times n$

We can also use the full bases
for \mathbb{R}^m & \mathbb{R}^n .

$$A = U \left(\begin{array}{ccc|cc} \delta_1 & & & & 0 \\ & \ddots & & & \\ & & \delta_r & & \\ \hline & & & 0 & \\ 0 & & & & 0 \end{array} \right) V^T$$

$m \times n$ $m \times m$ $m \times n$ $n \times n$

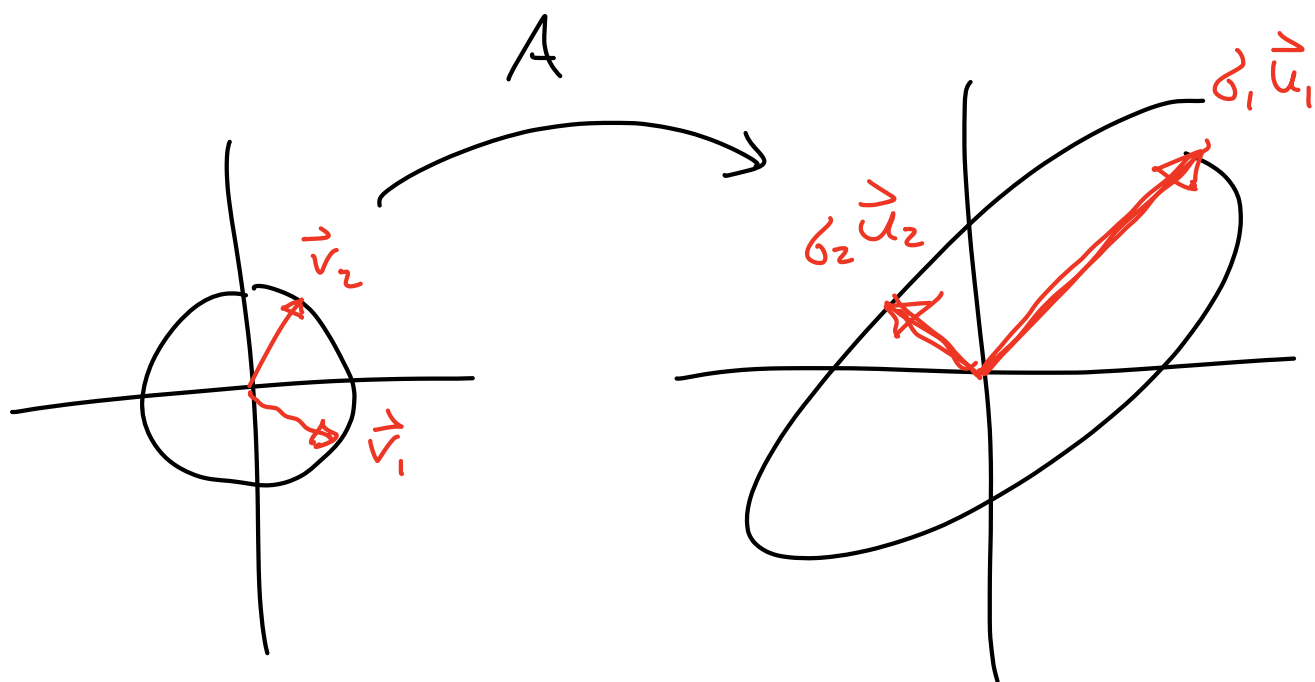
where U, V are square orthogonal.

Proof: For $k \in r$ ($\delta_k \neq 0$), define

$$\vec{u}_k = \frac{1}{\delta_k} A \vec{v}_k$$

check that it works. ✓

Picture: A is 2×2



Hard Theorem (Eckart - Young, 1936)

A $m \times n$, rank r .

$$A_{m \times n} = U_{m \times r} \Sigma_{r \times r} V^T_{r \times n}$$

$\delta_1 \geq \delta_2 \geq \dots \geq \delta_r > 0$.
SORT

$$= (\vec{u}_1 | \dots | \vec{u}_r) \begin{pmatrix} \delta_1 & & \\ & \dots & \\ & & \delta_r \end{pmatrix} \begin{pmatrix} \vec{v}_1^T \\ \vdots \\ \vec{v}_r^T \end{pmatrix}$$

$$= \sum_{i=1}^r \delta_i \vec{u}_i \vec{v}_i^T$$

sum of rank one matrices,

For $k \leq r$ define

$$A_k = \sum_{i=1}^k \delta_i \vec{u}_i \vec{v}_i^T$$

cut
the smallest
singular
values.

Then $\text{rank}(A_k) = k$.

For any X $m \times n$, $\text{rank } k$,

$$\|A - A_k\|_F \leq \|A - X\|_F$$

Best rank k approximation
to A .