

HW5 due before class on Monday.
Quiz5 on Tuesday.

HW5 Problem 2 typo:

$$(a) \quad P = \vec{a} (\vec{a}^T \vec{a})^{-1} \vec{a}^T$$

If \vec{a} has shape 3×1 , e.g., $\vec{a} = \begin{pmatrix} 2 \\ -3 \\ 1 \end{pmatrix}$
then P has what shape?

$$\begin{matrix} \vec{a}^T & \vec{a} & = & \vec{a} \cdot \vec{a} & = & \|\vec{a}\|^2 & . & \text{Just a} \\ 1 \times 3 & 3 \times 1 & & 1 \times 1 & & & & \text{scalar!} \end{matrix}$$

$$P = \vec{a} \left(\frac{1}{\|\vec{a}\|^2} \right) \vec{a}^T$$

$$= \frac{1}{\|\vec{a}\|^2} \underbrace{\vec{a} \vec{a}^T}_{3 \times 3} = 3 \times 3 \text{ matrix.}$$

What I originally wrote:

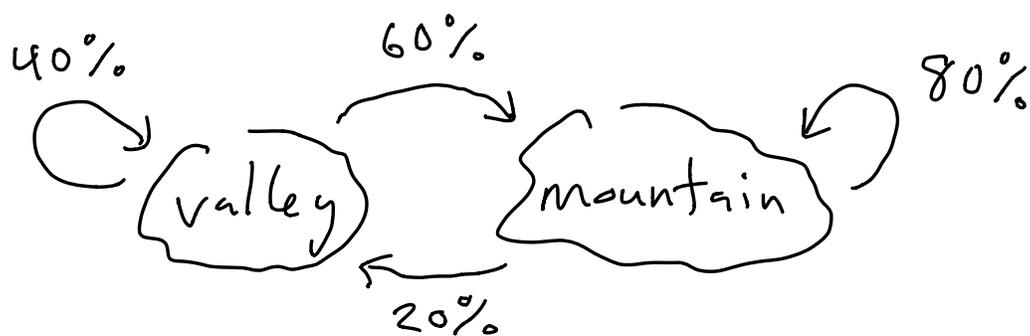
$$P = \frac{1}{\|\vec{a}\|^2} \vec{a} \vec{a} = \text{NOT DEFINED!}$$

$3 \times 1 \quad 3 \times 1$
OOPS

Today: "Diagonalization" means finding the "correct" coordinate system for a given problem.

Example from last time:

Yearly Migration of Bears



If x_n, y_n are # bears in the valley and on the mountain in year n , then

$$\begin{cases} x_{n+1} = 0.4x_n + 0.2y_n, \\ y_{n+1} = 0.6x_n + 0.8y_n. \end{cases}$$

We can express this system as a single matrix equation:

$$\begin{pmatrix} x_{n+1} \\ y_{n+1} \end{pmatrix} = \begin{pmatrix} 0.4 & 0.2 \\ 0.6 & 0.8 \end{pmatrix} \begin{pmatrix} x_n \\ y_n \end{pmatrix}$$

$$\vec{x}_{n+1} = A \vec{x}_n.$$

To analyze this problem we need to find the correct coordinate system, which is given by the "eigenvectors" of the matrix A .

[German: "eigen" = "belonging to."]

Definition: Let A be a SQUARE matrix. We say that a scalar $\lambda \in \mathbb{R}$ is an "eigenvalue" of A if there exists some nonzero vector $\vec{u} \neq \vec{0}$ such that

$$\boxed{A \vec{u} = \lambda \vec{u}}$$

In this case we say that \vec{u} is an "eigenvector" of A , belonging to eigenvalue λ . We could also say

\vec{u} is a " λ -eigenvector" of A . ///

Before discussing how to compute eigenvalues/vectors, let me just tell you that the bear matrix A satisfies

$$\begin{pmatrix} 0.4 & 0.2 \\ 0.6 & 0.8 \end{pmatrix} \begin{pmatrix} 1 \\ 3 \end{pmatrix} = \begin{pmatrix} 0.4 + 0.6 \\ 0.6 + 2.4 \end{pmatrix} = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$$

Say $\vec{u} = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$ is a "1-eigenvector" of A :

$$A \vec{u} = 1 \vec{u}.$$

AND:

$$\begin{pmatrix} 0.4 & 0.2 \\ 0.6 & 0.8 \end{pmatrix} \begin{pmatrix} -1 \\ 1 \end{pmatrix} = \begin{pmatrix} -0.4 + 0.2 \\ -0.6 + 0.8 \end{pmatrix} = \begin{pmatrix} -0.2 \\ 0.2 \end{pmatrix}$$

$$\begin{pmatrix} 0.4 & 0.2 \\ 0.6 & 0.8 \end{pmatrix} \begin{pmatrix} -1 \\ 1 \end{pmatrix} = 0.2 \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$A \vec{v} = (0.2) \vec{v}.$$

So $\vec{v} = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$ is a "0.2-eigenvector" of A .

I claim that the equations

$$A \begin{pmatrix} 1 \\ 3 \end{pmatrix} = \begin{pmatrix} 1 \\ 3 \end{pmatrix} \quad \& \quad A \begin{pmatrix} -1 \\ 1 \end{pmatrix} = 0.2 \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

tell us everything we need to solve the problem.

Suppose we begin with

$x_0 = 100$ bears in the valley

$y_0 = 0$ bears on the mountain.

$$\text{Then } \begin{pmatrix} x_n \\ y_n \end{pmatrix} = A^n \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} = A^n \begin{pmatrix} 100 \\ 0 \end{pmatrix}$$

Now what? Express the initial state vector $\vec{x}_0 = \begin{pmatrix} 100 \\ 0 \end{pmatrix}$ in terms of the "good coordinate system"

$$\vec{u} = \begin{pmatrix} 1 \\ 3 \end{pmatrix} \quad \& \quad \vec{v} = \begin{pmatrix} -1 \\ 1 \end{pmatrix} .$$

In other words:

$$\vec{x}_0 = a \vec{u} + b \vec{v}$$

$$\begin{pmatrix} 100 \\ 0 \end{pmatrix} = a \begin{pmatrix} 1 \\ 3 \end{pmatrix} + b \begin{pmatrix} -1 \\ 1 \end{pmatrix} .$$

Find a & b :

$$\begin{pmatrix} 1 & -1 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 100 \\ 0 \end{pmatrix}$$

$$\left(\begin{array}{cc|c} \textcircled{1} & -1 & 100 \\ 3 & 1 & 0 \end{array} \right)$$

$$\left(\begin{array}{cc|c} 1 & -1 & 100 \\ 0 & \textcircled{4} & -300 \end{array} \right)$$

$$\left(\begin{array}{cc|c} \textcircled{1} & -1 & 100 \\ 0 & \textcircled{1} & -75 \end{array} \right)$$

$$\left(\begin{array}{cc|c} 1 & 0 & 25 \\ 0 & 1 & -75 \end{array} \right) \quad \begin{array}{l} a = 25 \\ b = -75 \end{array}$$

Check:

$$\begin{pmatrix} 100 \\ 0 \end{pmatrix} = 25 \begin{pmatrix} 1 \\ 3 \end{pmatrix} - 75 \begin{pmatrix} -1 \\ 1 \end{pmatrix} \checkmark$$

Now that we have expressed the initial conditions in terms of eigenvectors we are done!

Solution :

$$\begin{pmatrix} x_n \\ y_n \end{pmatrix} = A^n \begin{pmatrix} 100 \\ 0 \end{pmatrix}$$

$$= A^n \left[25 \begin{pmatrix} 1 \\ 3 \end{pmatrix} - 75 \begin{pmatrix} -1 \\ 1 \end{pmatrix} \right]$$

$$= 25 A^n \begin{pmatrix} 1 \\ 3 \end{pmatrix} - 75 A^n \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$= 25 \begin{pmatrix} 1 \\ 3 \end{pmatrix} - 75 (0.2)^n \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

↓ (*)

$$= \begin{pmatrix} 25 + 75(0.2)^n \\ 75 - 75(0.2)^n \end{pmatrix}.$$

$x_n = \#$ valley bears in year n

$$= 25 + 75(0.2)^n$$

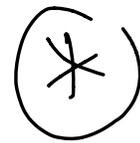
$y_n = \#$ mountain bears in year n

$$= 75 - 75(0.2)^n.$$



Key Fact that made it work:

If $A\vec{u} = \lambda\vec{u}$ then $A^n\vec{u} = \lambda^n\vec{u}$
for any power n .



How to compute eigenvalues/vectors?

Let A be square. Then λ is an eigenvalue

$$\Leftrightarrow A\vec{u} = \lambda\vec{u} \text{ for some } \vec{u} \neq \vec{0}$$

$$\Leftrightarrow A\vec{u} - \lambda\vec{u} = \vec{0} \text{ for some } \vec{u} \neq \vec{0}.$$

$$\Leftrightarrow \cancel{(A - \lambda)\vec{u} = \vec{0}}$$

oops: $A - \lambda$ makes no sense!

$$\Leftrightarrow \underbrace{(A - \lambda I)}_{\text{ok } \checkmark} \vec{u} = \vec{0} \text{ for some } \vec{u} \neq \vec{0}.$$

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$$\Leftrightarrow (A - \lambda I)^{-1} \text{ does not exist}$$

Can we turn this statement into a useful equation?

Recall: We have several equivalent conditions for invertibility of a square $n \times n$ matrix A :

$$A^{-1} \text{ exists} \iff \text{rank}(A) = n$$

$$\iff \text{rows are independent}$$

$$\iff \text{columns are independent}$$

$$\iff N(A) = \{ \vec{0} \}$$

$$\iff C(A) = \mathbb{R}^n$$

$$\iff \boxed{\det(A) \neq 0}$$

This last condition is useful for computing eigenvalues. Let's see:

λ is an eigenvalue of A

$$\iff (A - \lambda I)^{-1} \text{ does not exist}$$

$$\iff \det(A - \lambda I) (=) 0.$$

Equations are good because they give us something to solve.



Let's use this to find the eigenvalues of the bear matrix.

$$A = \begin{pmatrix} 0.4 & 0.2 \\ 0.6 & 0.8 \end{pmatrix}$$

$$\begin{aligned} A - \lambda I &= \begin{pmatrix} 0.4 & 0.2 \\ 0.6 & 0.8 \end{pmatrix} - \lambda \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \\ &= \begin{pmatrix} 0.4 - \lambda & 0.2 \\ 0.6 & 0.8 - \lambda \end{pmatrix}. \end{aligned}$$

$$\begin{aligned} \det(A - \lambda I) &= (0.4 - \lambda)(0.8 - \lambda) - (0.2)(0.6) \\ &= 0.32 - 1.2\lambda + \lambda^2 - 0.12 \\ &= \lambda^2 - 1.2\lambda + 0.2 \end{aligned}$$

So the eigenvalues of A are the solutions of the "characteristic equation":

$$\det(A - \lambda I) = 0$$

$$\lambda^2 - 1.2\lambda + 0.2 = 0.$$

Wait a minute. This is a nonlinear equation! Correct. The computation of eigenvalues is a nonlinear problem. !!

Quadratic Formula:

$$\lambda = \frac{1.2 \pm \sqrt{(1.2)^2 - 4(0.2)}}{2}$$

$$= \frac{1.2 \pm \sqrt{1.44 - 0.8}}{2}$$

$$= \frac{1.2 \pm \sqrt{0.64}}{2}$$

$$= \frac{1.2 \pm 0.8}{2}$$

$$= \frac{1.2 + 0.8}{2} \text{ or } \frac{1.2 - 0.8}{2}$$

$$= 1 \text{ or } (0.2) \quad \checkmark$$

Finally, we can use the eigenvalues to find the eigenvectors.

Remark: If λ is an eigenvalue of square $n \times n$ matrix A , then the λ -eigenvectors of A form a subspace of \mathbb{R}^n called the " λ -eigenspace."

$$\begin{aligned} N(A - \lambda I) &= \text{"}\lambda\text{-eigenspace" of } A \\ &= \left\{ \vec{u} \in \mathbb{R}^n : (A - \lambda I)\vec{u} = \vec{0} \right\} \\ &= \left\{ \vec{u} \in \mathbb{R}^n : A\vec{u} = \lambda\vec{u} \right\}. \quad \text{//} \end{aligned}$$

For the bears matrix, first compute the " 1 -eigenspace":

$$N(A - 1I)$$

$$N \begin{pmatrix} 0.4 - 1 & 0.2 \\ 0.6 & 0.8 - 1 \end{pmatrix}$$

$$\begin{pmatrix} 0.4 - 1 & 0.2 \\ 0.6 & 0.8 - 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\left(\begin{array}{cc|c} 0.4 & -1 & 0.2 \\ 0.6 & 0.8 & -1 \end{array} \right) \left| \begin{array}{c} 0 \\ 0 \end{array} \right.$$

$$\left(\begin{array}{cc|c} \textcircled{+0.4} & 0.2 & 0 \\ 0.6 & -0.2 & 0 \end{array} \right) \left| \begin{array}{c} 0 \\ 0 \end{array} \right.$$

$$\left(\begin{array}{cc|c} -0.6 & 0.2 & 0 \\ \textcircled{0} & \textcircled{0} & 0 \end{array} \right) \left| \begin{array}{c} 0 \\ 0 \end{array} \right.$$

Not a surprise because we know $A - \lambda I$ is not invertible!

$$\left(\begin{array}{cc|c} 1 & -1/3 & 0 \\ 0 & 0 & 0 \end{array} \right) \left| \begin{array}{c} 0 \\ 0 \end{array} \right.$$

$$x - \frac{1}{3}y = 0$$

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1/3 y \\ y \end{pmatrix} = y \begin{pmatrix} 1/3 \\ 1 \end{pmatrix}$$

Conclusion: The " $\lambda=1$ -eigenspace" is the line $t(\frac{1}{3}, 1)$. Check:

$$\begin{pmatrix} 0.4 & 0.2 \\ 0.6 & 0.8 \end{pmatrix} t \begin{pmatrix} 1/3 \\ 1 \end{pmatrix} = \underline{1} \cdot t \begin{pmatrix} 1/3 \\ 1 \end{pmatrix} \quad \checkmark$$

Note that $\vec{u} = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$ is on this line.

[I chose $\begin{pmatrix} 1 \\ 3 \end{pmatrix}$ instead of $\begin{pmatrix} 1/3 \\ 1 \end{pmatrix}$ because I don't like fractions.]

Next compute the "0.2-eigenspace":

$$N(A - 0.2I)$$

$$\left(\begin{array}{cc|c} 0.4 - 0.2 & 0.2 & 0 \\ 0.6 & 0.8 - 0.2 & 0 \end{array} \right)$$

$$\left(\begin{array}{cc|c} 0.2 & 0.2 & 0 \\ 0.6 & 0.6 & 0 \end{array} \right)$$

Surprise? No. We knew that the rows were going to be parallel.

$$\left(\begin{array}{cc|c} 1 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right)$$

$$x + y = 0$$

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -y \\ y \end{pmatrix} = y \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

The "0.2-eigenspace" is the line $t(-1, 1)$. Pick our favorite nonzero vector on this line:

$$\vec{v} = \begin{pmatrix} -1 \\ 1 \end{pmatrix} \quad \checkmark$$

This completes the problem of the migrating bears.

Yes, it took the entire lecture, but now that we know the method we could solve a similar problem much more quickly.

NEXT TIME!